

Causal Spaces: A Measure-Theoretic Axiomatisation of Causality



Simon Buchholz²



Bernhard Schölkopf²



Krikamol Muandet³



Fanny Yang¹



Thomas Icard⁴

¹ETH Zürich

²Max Planck Institute for Intelligent Systems, Tübingen

³CISPA Helmholtz Center for Information Security, Saarbrücken

⁴Stanford University

Spatiotemporal Causality Reading Group, 25 June 2025

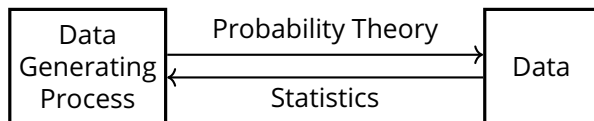
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- ① Introduction & Motivation
- ② Causal Spaces
- ③ Examples
- ④ Conclusion

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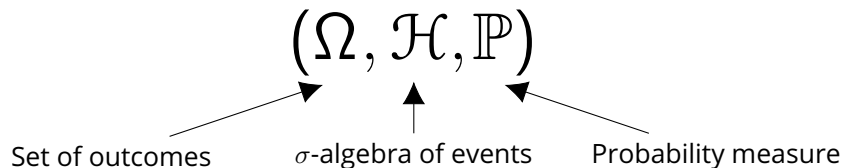
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- 2 Causal Spaces
- 3 Examples
- 4 Conclusion

Probability vs Statistics



Probability Theory

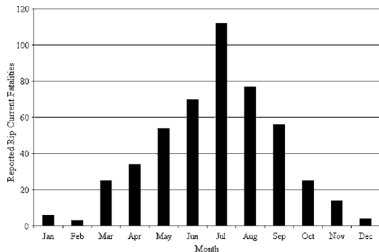
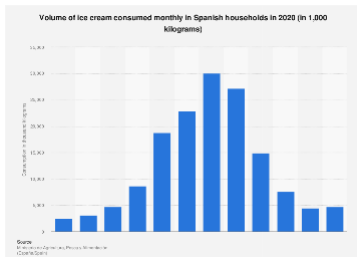
Probability Space



Foundations of the Theory of Probability, Andrei N Kolmogorov, 1933.

Is Probability Theory All We Need?

Ice Cream Sales vs Beach Accidents



Is Probability Theory All We Need?

Rain and Plant Growth



Is Probability Theory All We Need?

Is Moderate Drinking Good For Health?

Moderate drinking not better for health than abstaining, analysis suggests

Scientists say flaws in previous research mean health benefits from alcohol were exaggerated



For the regular boozier it is a source of great comfort: the fat pile of studies that say a daily tipples is better for a longer life than avoiding alcohol completely.

Is Probability Theory All We Need?

Is Moderate Drinking Good For Health?

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For the regular boozier it is a source of great comfort: the fat pile of studies that say a daily tippie is better for a longer life than avoiding alcohol completely.

But a new analysis challenges the thinking and blames the rosy message on flawed research that compares drinkers with people who are sick and sober.

Scientists in Canada delved into 107 published studies on people's drinking habits and how long they lived. In most cases, they found that drinkers were compared with people who abstained or consumed very little alcohol, without taking into account that some had cut down or quit through ill health.

Why is Causality Important?

Evaluation of Policy / Drug / Business Strategy



Why is Causality Important?

Image Classification



Why is Causality Important?

Large Language Models

Tutorial

Causality for Large Language Models

Zhijing Jin · Sergio Garrido

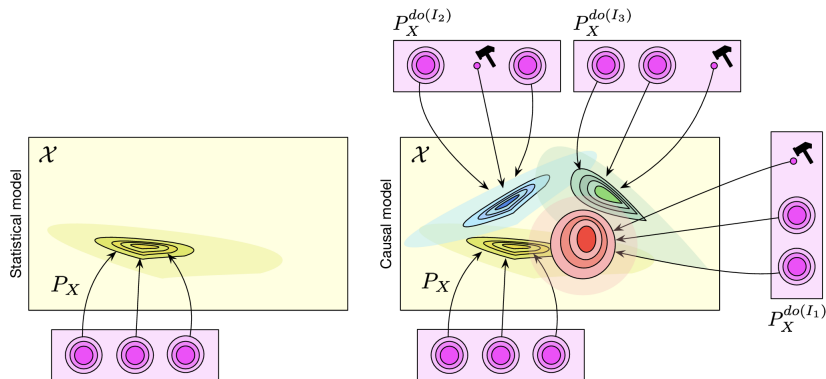
West Ballroom A

[[Abstract](#)] [[Join Zoom](#) pwd: canstomb]

Tue 10 Dec 9:30 a.m. PST — noon PST ([Bookmark](#))

Please do not share or post zoom links

Manipulation is at the heart of Causality

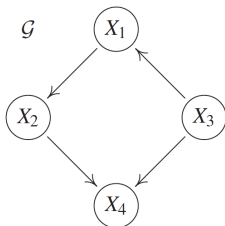


We are interested in what happens to a system, when we intervene on a sub-system.

Schölkopf, Locatello, Bauer, Ke, Kalchbrenner, Goyal and Bengio, *Towards Causal Representation Learning*, 2021.

Existing Frameworks

Structural Causal Models (SCMs)



Potential Outcomes

	$Y^{a=0}$	$Y^{a=1}$
Rheia	0	1
Kronos	1	0
Demeter	0	0
Hades	0	0
Hestia	0	0
Poseidon	1	0
Hera	0	0
Zeus	0	1
Artemis	1	1
Apollo	1	0



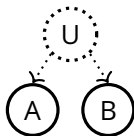
Causality, Pearl, Cambridge University Press, 2009

Elements of Causal Inference, Peters, Janzing and Schölkopf, MIT Press, 2017

Causal Inference for Statistics, Social, and Biomedical Sciences: An Introduction, Rubin and Imbens, Cambridge University Press, 2015

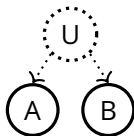
Limitations of Existing Frameworks

- Latent confounding

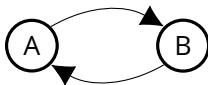


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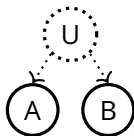


- Cyclic causal relationships

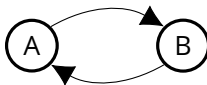


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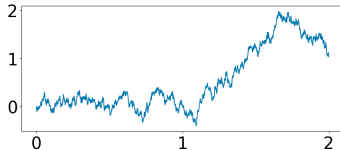
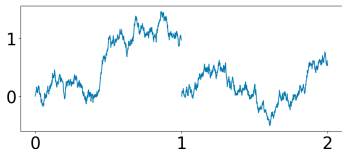
- Latent confounding



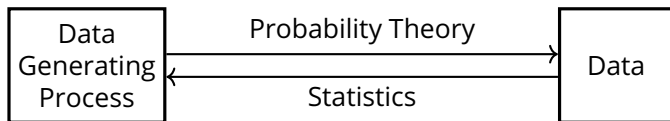
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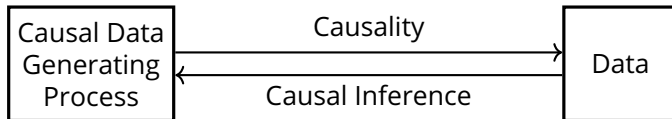
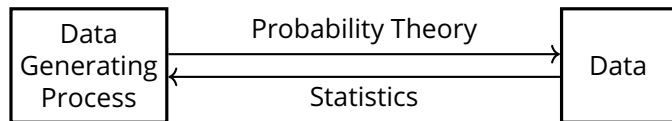
- Continuous-time stochastic processes



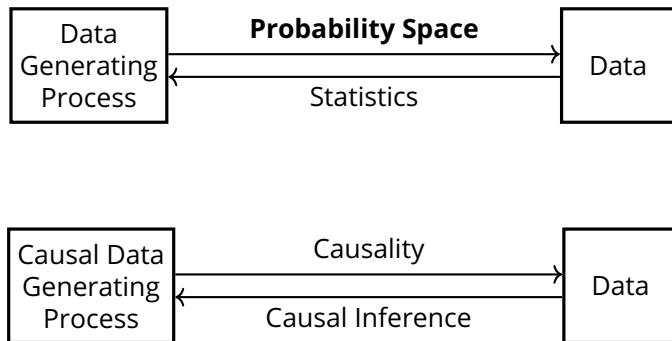
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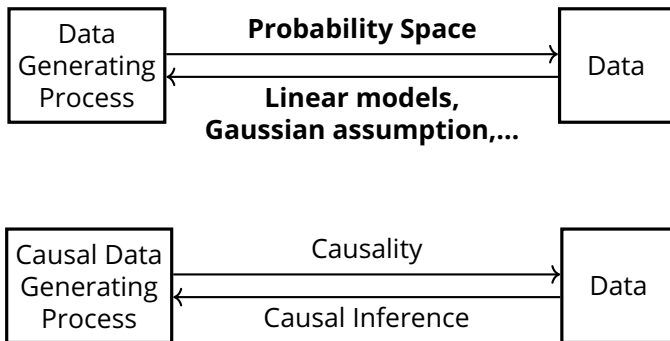
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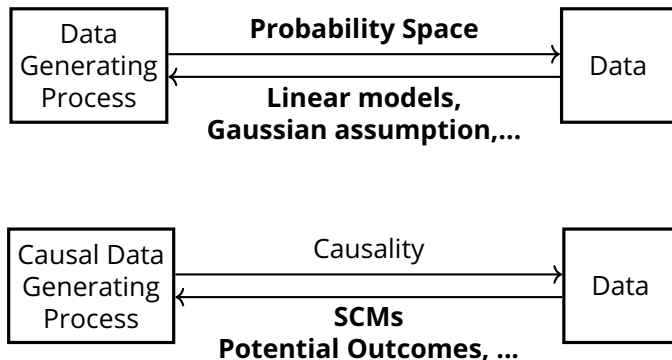
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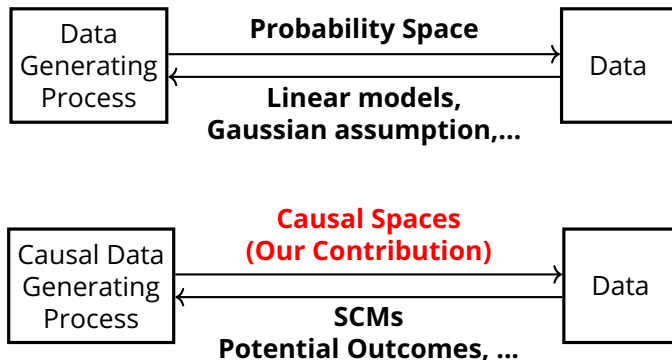


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Notations

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$$(\Omega, \mathcal{H}) = (\times_{t \in T} E_t, \otimes_{t \in T} \mathcal{E}_t).$$

\mathcal{H}_S : sub- σ -algebra of \mathcal{H} corresponding to $S \in \mathcal{P}(T)$.

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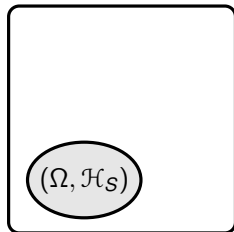
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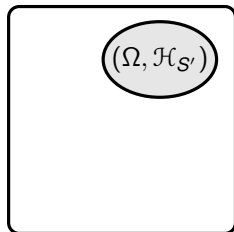
\mathcal{H}_S : sub- σ -algebra of \mathcal{H} corresponding to $S \in \mathcal{P}(T)$.

Intuition: $\mathcal{H} = \mathcal{H}_T$ is the entire space. \mathcal{H}_S is a subspace.

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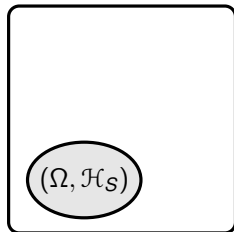
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- “Transition probability kernel”
 K_S from (Ω, \mathcal{H}_S) into (Ω, \mathcal{H}) :

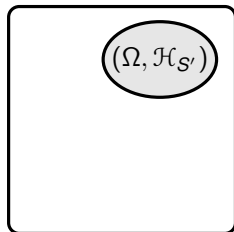
$$K_S(x, \cdot) \rightarrow [0, 1].$$

For every $x \in (\Omega, \mathcal{H}_S)$, $K_S(x, \cdot)$ is a measure on (Ω, \mathcal{H}) .

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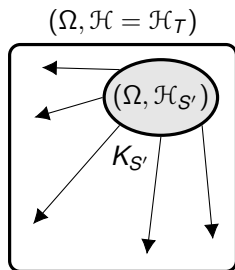
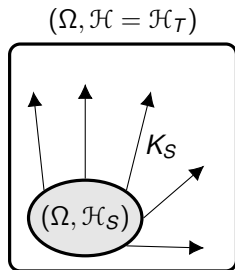
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Intuition: conditional distribution.



Causal Spaces

A **causal space** is a quadruple $(\Omega, \mathcal{H}, \mathbb{P}, \mathbb{K})$, where

$$(\Omega, \mathcal{H}, \mathbb{P}) = (\times_{t \in T} E_t, \otimes_{t \in T} \mathcal{E}_t, \mathbb{P});$$

and

$$\mathbb{K} = \{K_S : S \subseteq T\}, \quad K_S : (\Omega, \mathcal{H}_S) \rightarrow (\Omega, \mathcal{H})$$

where K_S are **causal kernels**, such that

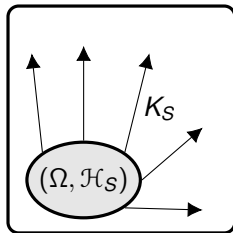
(i) for all $A \in \mathcal{H}$ and $x \in \Omega$,

$$K_\emptyset(x, A) = \mathbb{P}(A);$$

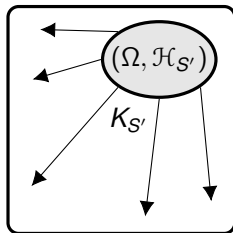
(ii) for all $A \in \mathcal{H}_S$ and $x \in \Omega$,

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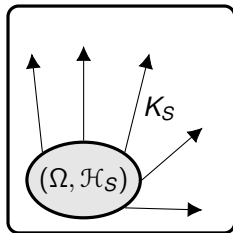
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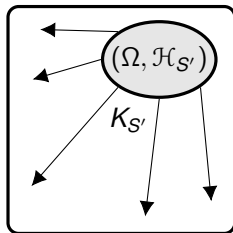
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\mathbb{P} is the “observational distribution”.

$$(\Omega, \mathcal{H} = \mathcal{H}_T)$$



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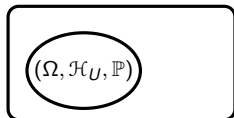


Interventions

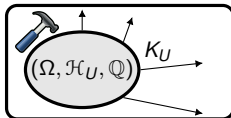
An intervention is the process of

- (a) choosing a sub- σ -algebra \mathcal{H}_U , and
- (b) placing any measure \mathbb{Q} on (Ω, \mathcal{H}_U) .

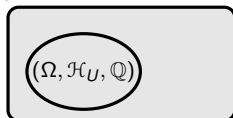
$(\Omega, \mathcal{H}, \mathbb{P}, \mathbb{K})$



$(\Omega, \mathcal{H}, ?, ?)$



$(\Omega, \mathcal{H}, \mathbb{P}^{\text{do}(U, \mathbb{Q})}, \mathbb{K}^{\text{do}(U, \mathbb{Q})})$



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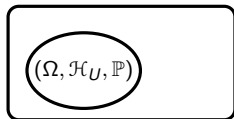
New causal space: $(\Omega, \mathcal{H}, \mathbb{P}^{\text{do}(U, \mathbb{Q})}, \mathbb{K}^{\text{do}(U, \mathbb{Q})})$, where

$$\mathbb{P}^{\text{do}(U, \mathbb{Q})}(A) = \int \mathbb{Q}(d\omega) K_U(\omega, A)$$

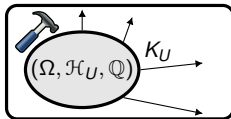
and $\mathbb{K}^{\text{do}(U, \mathbb{Q})} = \{K_S^{\text{do}(U, \mathbb{Q})} : S \in \mathcal{P}(T)\}$ with

$$K_S^{\text{do}(U, \mathbb{Q})}(\omega, A) = \int \mathbb{Q}(d\omega'_{U \setminus S}) K_{S \cup U}((\omega_S, \omega'_{U \setminus S}), A).$$

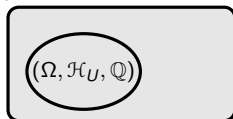
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Axioms of Causal Kernels

Recall that causal kernels K_S from (Ω, \mathcal{H}_S) into (Ω, \mathcal{H}) satisfy

(i) for all $A \in \mathcal{H}$ and $x \in \Omega$,

$$K_{\emptyset}(x, A) = \mathbb{P}(A);$$

(ii) for all $A \in \mathcal{H}_S$ and $x \in \Omega$,

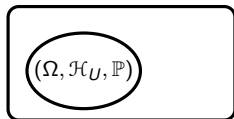
$$K_S(x, A) = 1_A(x).$$

Intuition on the axioms:

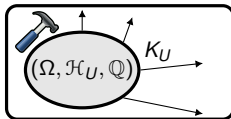
(i) $\mathbb{P}^{\text{do}(\emptyset, \mathbb{Q})}(A) = \mathbb{P}(A)$.

(ii) For $A \in \mathcal{H}_U$, $\mathbb{P}^{\text{do}(U, \mathbb{Q})}(A) = \int \mathbb{Q}(dx) 1_A(x) = \mathbb{Q}(A)$.

$(\Omega, \mathcal{H}, \mathbb{P}, \mathbb{K})$



$(\Omega, \mathcal{H}, ?, ?)$



$(\Omega, \mathcal{H}, \mathbb{P}^{\text{do}(U, \mathbb{Q})}, \mathbb{K}^{\text{do}(U, \mathbb{Q})})$

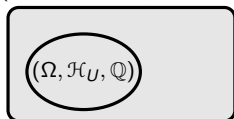
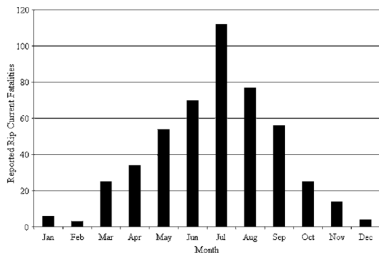
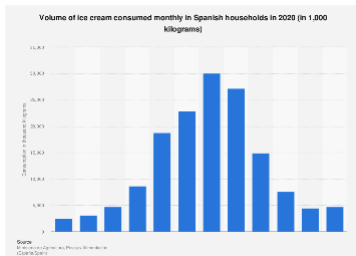


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Ice Cream Sales and Beach Accidents



- Causal space: $(E_{\text{ice}} \times E_{\text{acc}}, \mathcal{E}_{\text{ice}} \otimes \mathcal{E}_{\text{acc}}, \mathbb{P}, \mathbb{K})^1$.
- \mathbb{P} has strong correlation.
- For causal kernels, let
 - $K_{\text{ice}}(x, A) = \mathbb{P}(A)$ for all $A \in \mathcal{E}_{\text{acc}}$; and
 - $K_{\text{acc}}(y, B) = \mathbb{P}(B)$ for all $B \in \mathcal{E}_{\text{ice}}$.

¹ $E_{\text{ice}} = E_{\text{acc}} = \mathbb{R}$ and $\mathcal{E}_{\text{ice}} = \mathcal{E}_{\text{acc}}$ is the Lebesgue σ -algebra.

Ice Cream Sales and Beach Accidents

A Number of beach accidents.

I Ice cream sales.

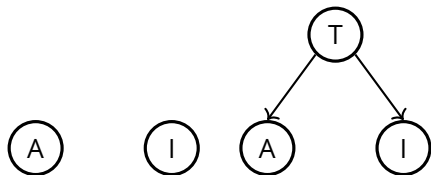


Ice Cream Sales and Beach Accidents

A Number of beach accidents.

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T Temperature.



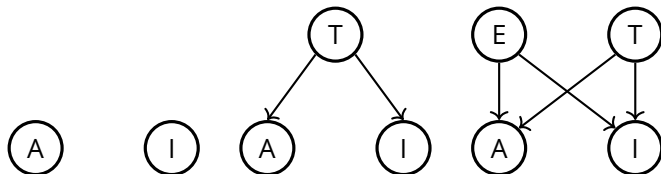
Ice Cream Sales and Beach Accidents

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Ice Cream Sales and Beach Accidents

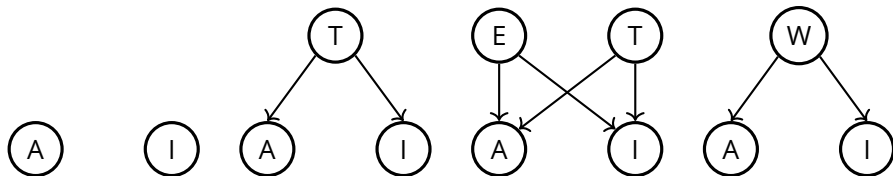
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Ice Cream Sales and Beach Accidents

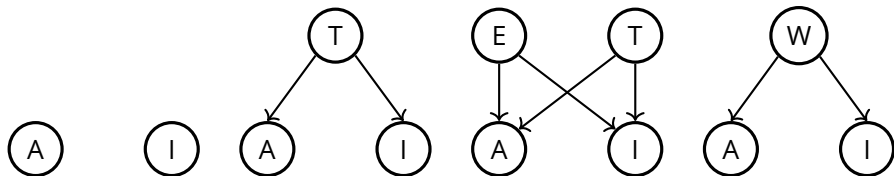
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Recall:

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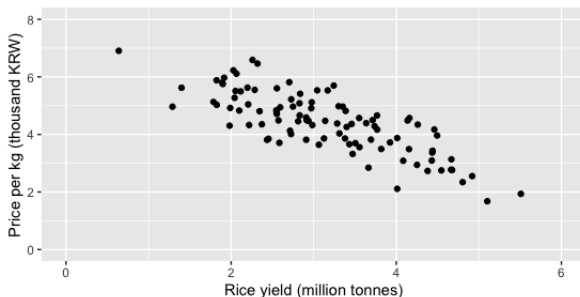
Crop Yield and Price

- Causal space: $(E_{\text{rice}} \times E_{\text{price}}, \mathcal{E}_{\text{rice}} \otimes \mathcal{E}_{\text{price}}, \mathbb{P}, \mathbb{K})^2$.

² $E_{\text{rice}} = E_{\text{price}} = \mathbb{R}$ and $\mathcal{E}_{\text{rice}} = \mathcal{E}_{\text{price}}$ is the Lebesgue σ -algebra.

Crop Yield and Price

- Causal space: $(E_{\text{rice}} \times E_{\text{price}}, \mathcal{E}_{\text{rice}} \otimes \mathcal{E}_{\text{price}}, \mathbb{P}, \mathbb{K})^2$.
- No Intervention:



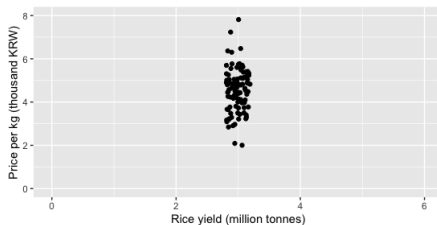
${}^2E_{\text{rice}} = E_{\text{price}} = \mathbb{R}$ and $\mathcal{E}_{\text{rice}} = \mathcal{E}_{\text{price}}$ is the Lebesgue σ -algebra.

Crop Yield and Price

- Intervention to fix rice = 3:

$$K_{\text{rice}}(3, A) = \int_A \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}(x-4.5)^2} dx$$

for $A \in \mathcal{E}_{\text{price}}$.

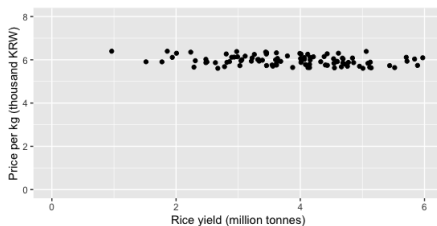


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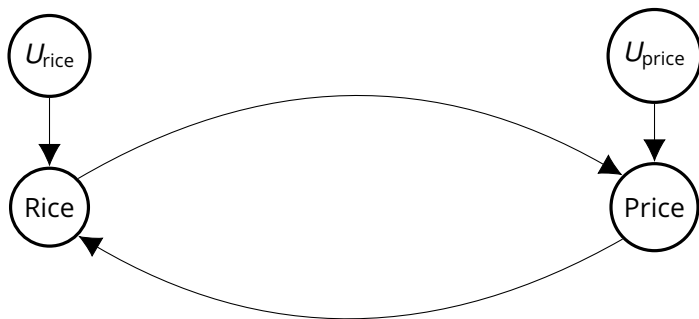
- Intervention to fix price = 6:

$$K_{\text{price}}(6, B) = \int_B \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}(x-4)^2} dx$$

for $B \in \mathcal{E}_{\text{rice}}$.

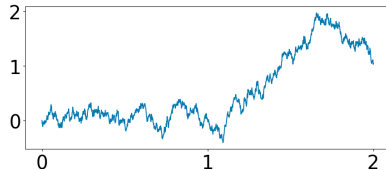
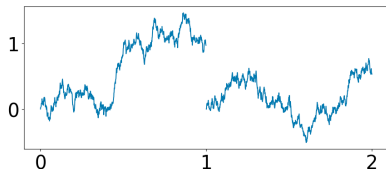


Crop Yield and Price



$$\text{Rice} = f_{\text{rice}}(\text{Price}, U_{\text{rice}}), \quad \text{Price} = f_{\text{price}}(\text{Rice}, U_{\text{price}}).$$

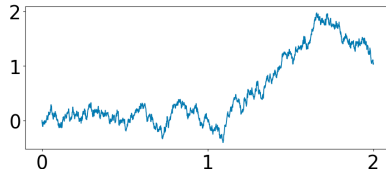
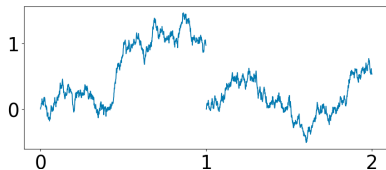
1-dimensional Brownian Motion



- Causal space: $(\times_{t \in \mathbb{R}_+} E_t, \otimes_{t \in \mathbb{R}_+} \mathcal{E}_t, \mathbb{P}, \mathbb{K})^3$.

³For each $t \in \mathbb{R}_+$, $E_t = \mathbb{R}$ and \mathcal{E}_t is the Lebesgue σ -algebra.

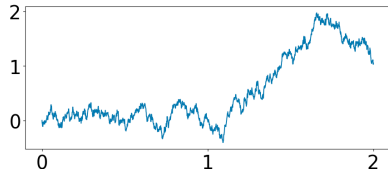
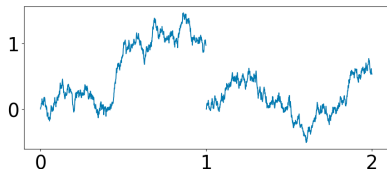
1-dimensional Brownian Motion



- Causal space: $(\times_{t \in \mathbb{R}_+} E_t, \otimes_{t \in \mathbb{R}_+} \mathcal{E}_t, \mathbb{P}, \mathbb{K})^3$.
- \mathbb{P} is the Wiener measure.

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1-dimensional Brownian Motion

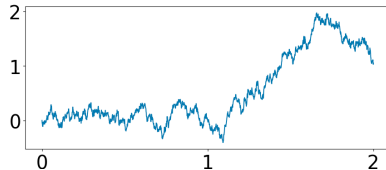
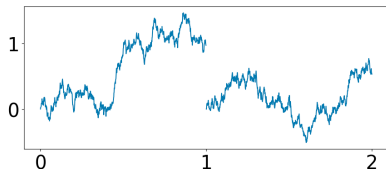


- Causal space: $(\times_{t \in \mathbb{R}_+} E_t, \otimes_{t \in \mathbb{R}_+} \mathcal{E}_t, \mathbb{P}, \mathbb{K})^3$.
- \mathbb{P} is the Wiener measure.
- For any $s < t$, the causal kernels are

$$K_s(x, y) = \frac{1}{\sqrt{2\pi(t-s)}} e^{-\frac{1}{2(t-s)}(y-x)^2}, \quad K_t(x, y) = \frac{1}{\sqrt{2\pi s}} e^{-\frac{1}{2s}y^2}.$$

³For each $t \in \mathbb{R}_+$, $E_t = \mathbb{R}$ and \mathcal{E}_t is the Lebesgue σ -algebra.

1-dimensional Brownian Motion



- Causal space: $(\times_{t \in \mathbb{R}_+} E_t, \otimes_{t \in \mathbb{R}_+} \mathcal{E}_t, \mathbb{P}, \mathbb{K})^3$.
- \mathbb{P} is the Wiener measure.
- For any $s < t$, the causal kernels are

$$K_s(x, y) = \frac{1}{\sqrt{2\pi(t-s)}} e^{-\frac{1}{2(t-s)}(y-x)^2}, \quad K_t(x, y) = \frac{1}{\sqrt{2\pi s}} e^{-\frac{1}{2s}y^2}.$$

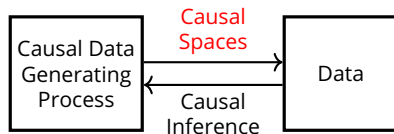
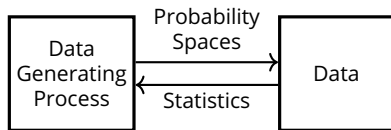
Past values affect the future, but future values do not affect the past.

³For each $t \in \mathbb{R}_+$, $E_t = \mathbb{R}$ and \mathcal{E}_t is the Lebesgue σ -algebra.

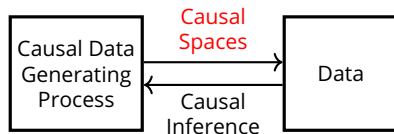
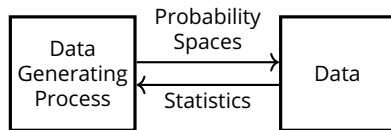
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- ② Causal Spaces
- ③ Examples
- ④ Conclusion

Summary



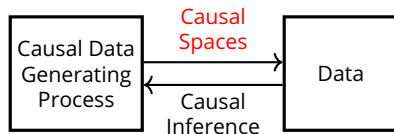
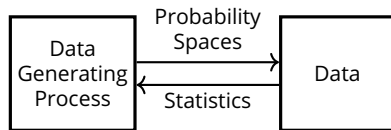
Summary



Causal spaces

- are a **measure-theoretic axiomatisation** of causality;

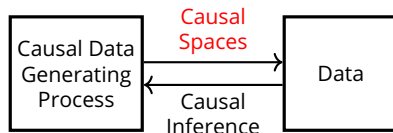
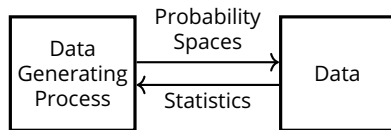
Summary



Causal spaces

- are a **measure-theoretic axiomatisation** of causality;
- strictly generalise existing frameworks;

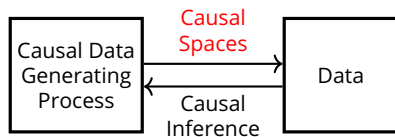
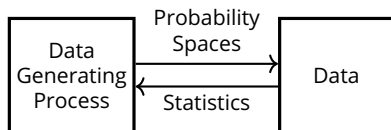
Summary



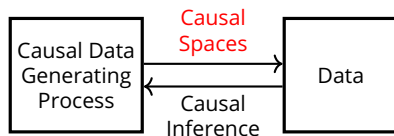
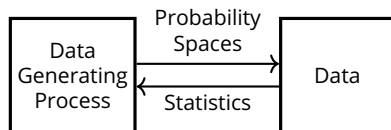
Causal spaces

- are a **measure-theoretic axiomatisation** of causality;
- strictly generalise existing frameworks;
- overcome long-standing limitations of existing frameworks, for example,
 - latent confounders,
 - cyclic causal relationships,
 - continuous-time stochastic processes.

Summary

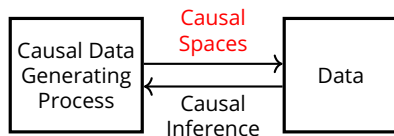
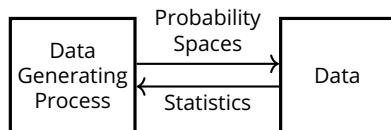


Summary



- We hope that causal spaces can play the same role as probability spaces for causality.

Summary



- We hope that causal spaces can play the same role as probability spaces for causality.
- Our view is that SCMs and potential outcomes are valuable tools to specify a causal space.

Not covered in this talk

- Causal effect [1].
- Sources & identifiability [1].
- Causal stochastic processes [1].

[1] A Measure-Theoretic Axiomatisation of Causality, P., Buchholz, Schölkopf and Muandet, NeurIPS 2023

[2] Products, Abstractions and Inclusions of Causal Spaces, Buchholz*, P.* and Schölkopf, UAI 2024

Not covered in this talk

- Causal effect [1].
- Sources & identifiability [1].
- Causal stochastic processes [1].
- Multiple causal spaces [2].
- Causal independence [2].

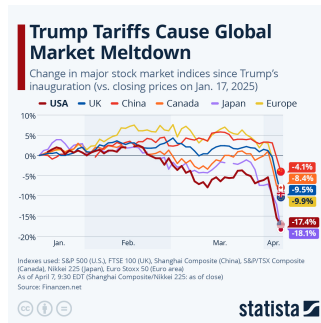
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[2] Products, Abstractions and Inclusions of Causal Spaces, Buchholz*, P.* and Schölkopf, UAI 2024

Not covered in this talk

Counterfactuals

- Counterfactuals [3].
- Fundamental Theorem of Causality [3].
- Independence and Synchronisation of counterfactual worlds [3].



[3] Counterfactual Causal Spaces and the Fundamental Theorem of Causality, P., Yang and Icard, to be submitted soon.

Thank you.