

# Causal Spaces: A Measure-Theoretic Axiomatisation of Causality



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Spatiotemporal Causality Reading Group, 25 June 2025

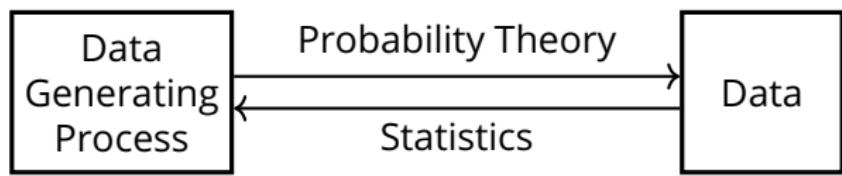
# Table of Contents

- ① Introduction & Motivation
- ② Causal Spaces
- ③ Examples
- ④ Conclusion

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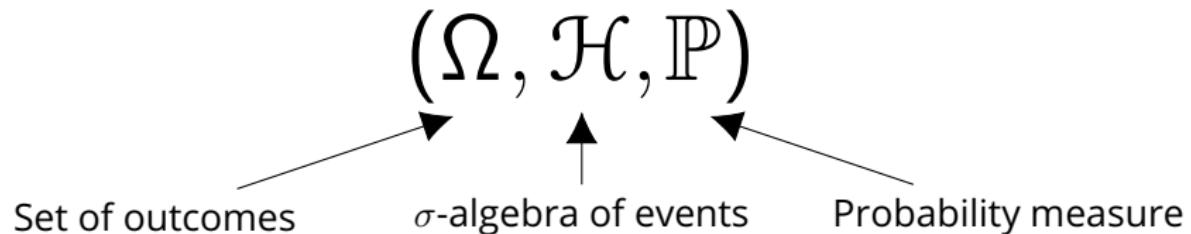
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# Probability vs Statistics



# Probability Theory

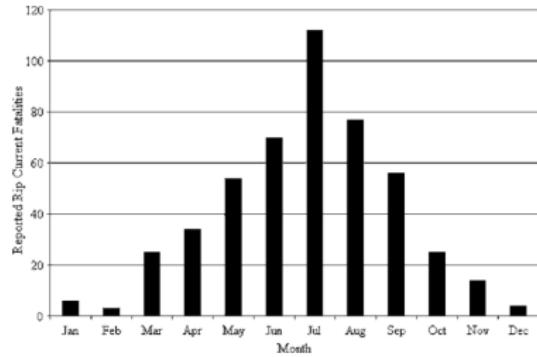
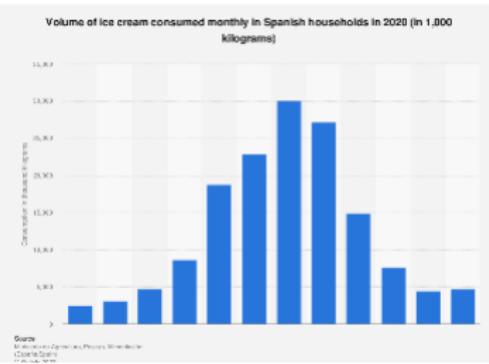
## Probability Space



*Foundations of the Theory of Probability*, Andrei N Kolmogorov, 1933.

# Is Probability Theory All We Need?

## Ice Cream Sales vs Beach Accidents



# Is Probability Theory All We Need?

Rain and Plant Growth



# Is Probability Theory All We Need?

## Is Moderate Drinking Good For Health?

Moderate drinking not better for health than abstaining, analysis suggests

Scientists say flaws in previous research mean health benefits from alcohol were exaggerated



For the regular boozer it is a source of great comfort: the fat pile of studies that say a daily tipple is better for a longer life than avoiding alcohol completely.

# Is Probability Theory All We Need?

## Is Moderate Drinking Good For Health?

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For the regular boozier it is a source of great comfort: the fat pile of studies that say a daily tipple is better for a longer life than avoiding alcohol completely.

But a new analysis challenges the thinking and blames the rosy message on flawed research that compares drinkers with people who are sick and sober.

Scientists in Canada delved into 107 published studies on people's drinking habits and how long they lived. In most cases, they found that drinkers were compared with people who abstained or consumed very little alcohol, without taking into account that some had cut down or quit through ill health.

# Why is Causality Important?

Evaluation of Policy / Drug / Business Strategy



# Why is Causality Important?

Image Classification



# Why is Causality Important?

Large Language Models

Tutorial

## Causality for Large Language Models

Zhijing Jin · Sergio Garrido

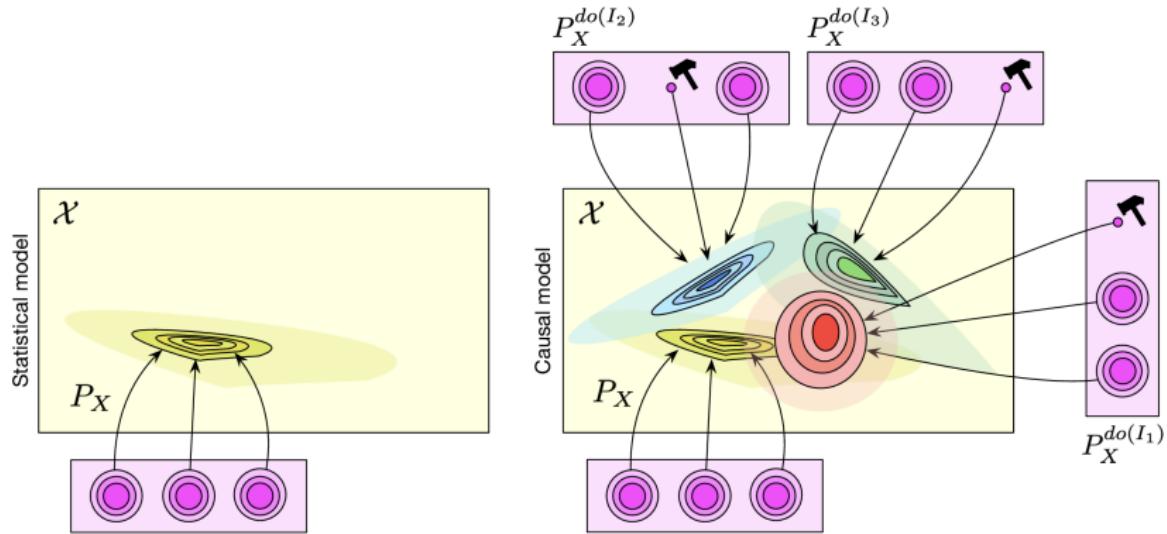
West Ballroom A

[ [Abstract](#) ] [ [Join Zoom](#) pwd: canstomb ]

Tue 10 Dec 9:30 a.m. PST – noon PST ([Bookmark](#))

Please do not share or post zoom links

# Manipulation is at the heart of Causality



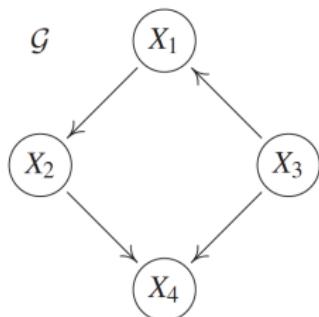
We are interested in what happens to a system, when we intervene on a sub-system.

---

Schölkopf, Locatello, Bauer, Ke, Kalchbrenner, Goyal and Bengio, *Towards Causal Representation Learning*, 2021.

# Existing Frameworks

## Structural Causal Models (SCMs)



## Potential Outcomes

	$Y^{a=0}$	$Y^{a=1}$
Rheia	0	1
Kronos	1	0
Demeter	0	0
Hades	0	0
Hestia	0	0
Poseidon	1	0
Hera	0	0
Zeus	0	1
Artemis	1	1
Apollo	1	0



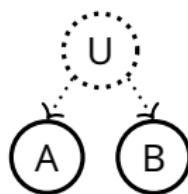
*Causality*, Pearl, Cambridge University Press, 2009

*Elements of Causal Inference*, Peters, Janzing and Schölkopf, MIT Press, 2017

*Causal Inference for Statistics, Social, and Biomedical Sciences: An Introduction*, Rubin and Imbens, Cambridge University Press, 2015

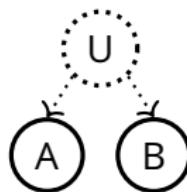
# Limitations of Existing Frameworks

- Latent confounding

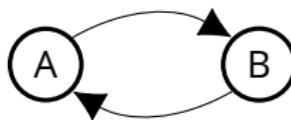


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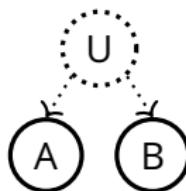


- Cyclic causal relationships

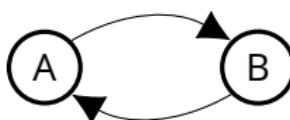


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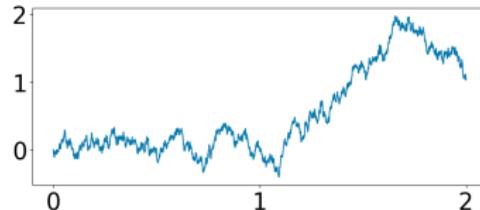
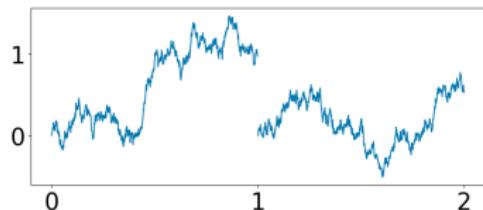
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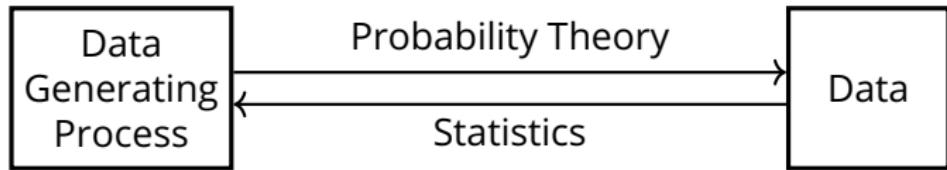
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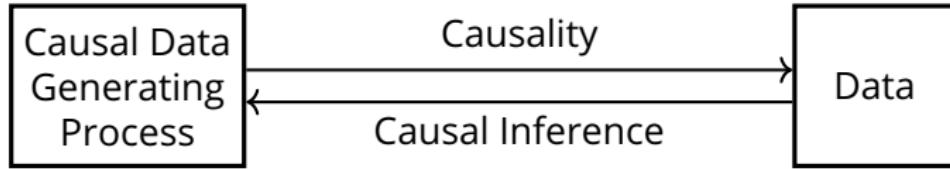
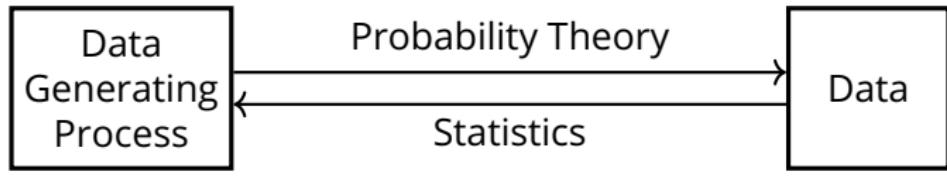
- Continuous-time stochastic processes



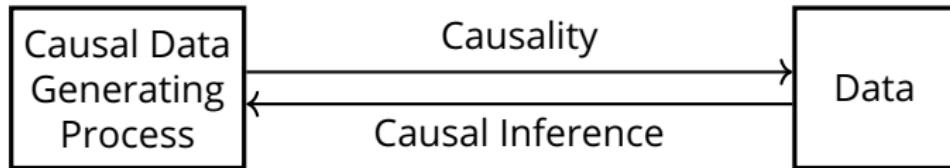
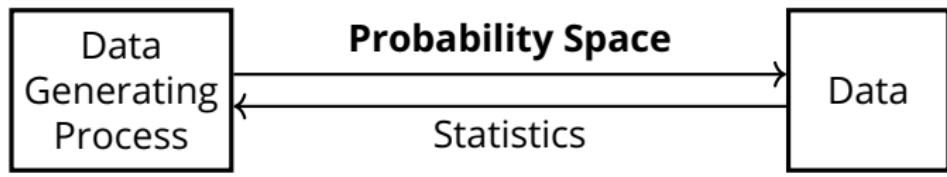
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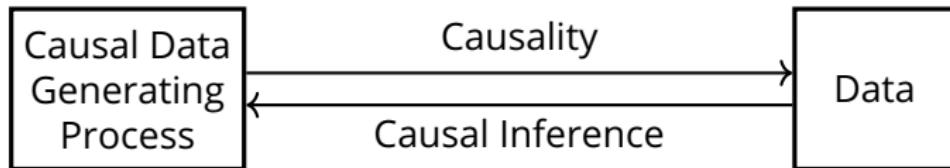
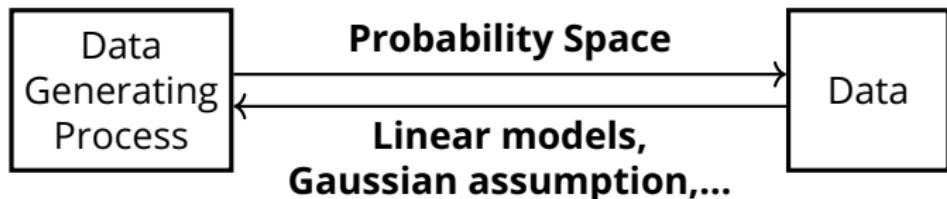
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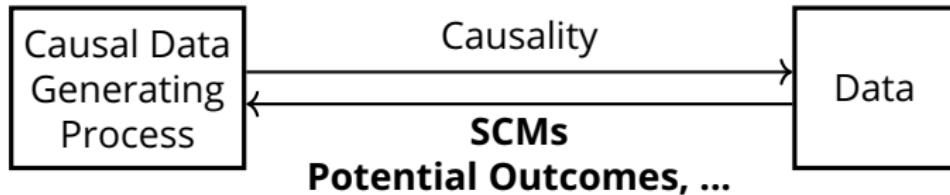
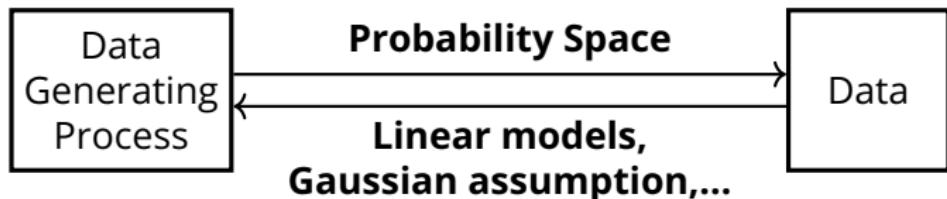
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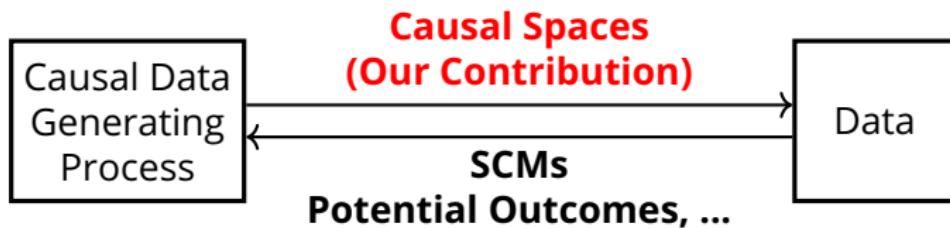
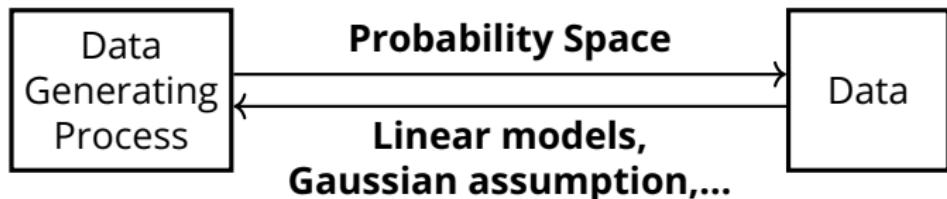
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- Product measurable space with index set  $T$ :

$$(\Omega, \mathcal{H}) = (\times_{t \in T} E_t, \otimes_{t \in T} \mathcal{E}_t).$$

$\mathcal{H}_S$ : sub- $\sigma$ -algebra of  $\mathcal{H}$  corresponding to  $S \in \mathcal{P}(T)$ .

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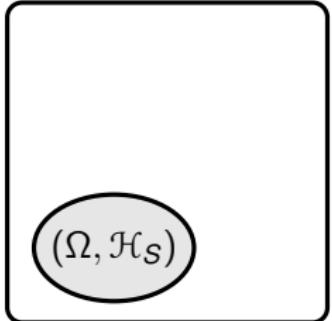
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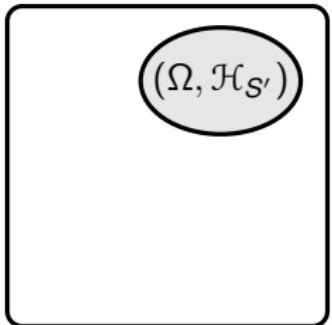
$\mathcal{H}_S$ : sub- $\sigma$ -algebra of  $\mathcal{H}$  corresponding to  $S \in \mathcal{P}(T)$ .

**Intuition:**  $\mathcal{H} = \mathcal{H}_T$  is the entire space.  $\mathcal{H}_S$  is a subspace.

$$(\Omega, \mathcal{H} = \mathcal{H}_T)$$


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- “Transition probability kernel”  $K_S$  from  $(\Omega, \mathcal{H}_S)$  into  $(\Omega, \mathcal{H})$ :

$$K_S(x, \cdot) \rightarrow [0, 1].$$

For every  $x \in (\Omega, \mathcal{H}_S)$ ,  $K_S(x, \cdot)$  is a measure on  $(\Omega, \mathcal{H})$ .

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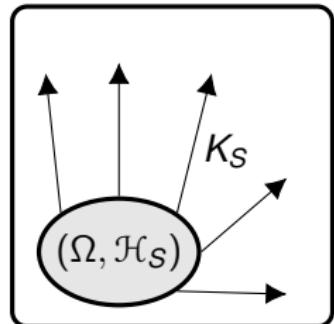
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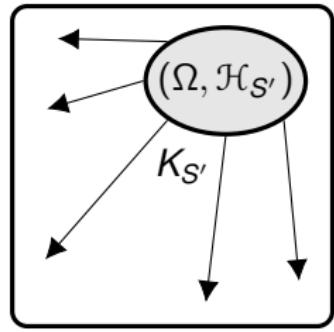
For every  $x \in (\Omega, \mathcal{H}_S)$ ,  $K_S(x, \cdot)$  is a measure on  $(\Omega, \mathcal{H})$ .

**Intuition:** conditional distribution.

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# Causal Spaces

A **causal space** is a quadruple  $(\Omega, \mathcal{H}, \mathbb{P}, \mathbb{K})$ , where

$$(\Omega, \mathcal{H}, \mathbb{P}) = (\times_{t \in T} E_t, \otimes_{t \in T} \mathcal{E}_t, \mathbb{P});$$

and

$$\mathbb{K} = \{K_S : S \subseteq T\}, \quad K_S : (\Omega, \mathcal{H}_S) \rightarrow (\Omega, \mathcal{H})$$

where  $K_S$  are **causal kernels**, such that

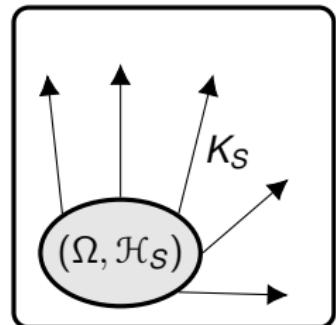
i) for all  $A \in \mathcal{H}$  and  $x \in \Omega$ ,

$$K_\emptyset(x, A) = \mathbb{P}(A);$$

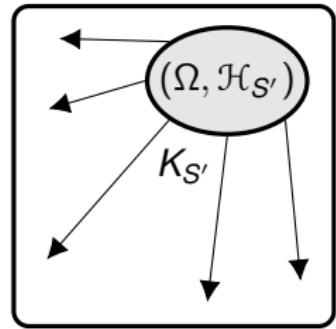
ii) for all  $A \in \mathcal{H}_S$  and  $x \in \Omega$ ,

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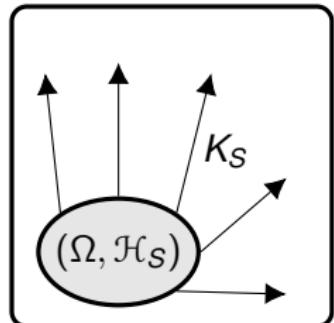
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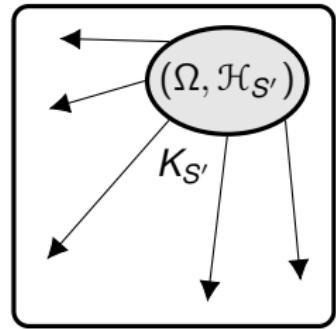
$$K_S(x, A) = 1_A(x).$$

$\mathbb{P}$  is the “observational distribution”.

$$(\Omega, \mathcal{H} = \mathcal{H}_T)$$



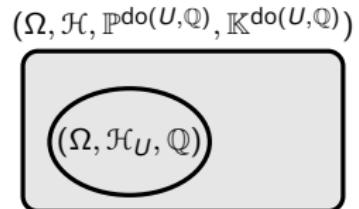
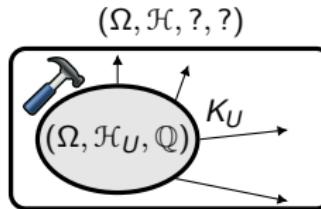
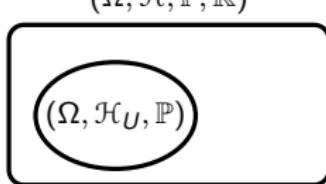
$$(\Omega, \mathcal{H} = \mathcal{H}_T)$$



# Interventions

An intervention is the process of

- (a) choosing a sub- $\sigma$ -algebra  $\mathcal{H}_U$ , and
- (b) placing any measure  $\mathbb{Q}$  on  $(\Omega, \mathcal{H}_U)$ .



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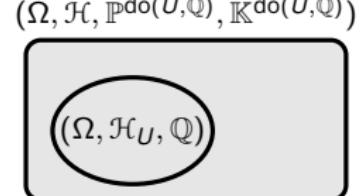
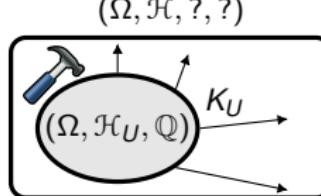
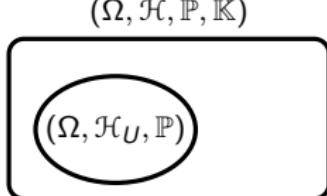
- (a) choosing a sub- $\sigma$ -algebra  $\mathcal{H}_U$ , and
- (b) placing any measure  $\mathbb{Q}$  on  $(\Omega, \mathcal{H}_U)$ .

New causal space:  $(\Omega, \mathcal{H}, \mathbb{P}^{\text{do}(U, \mathbb{Q})}, \mathbb{K}^{\text{do}(U, \mathbb{Q})})$ , where

$$\mathbb{P}^{\text{do}(U, \mathbb{Q})}(A) = \int \mathbb{Q}(d\omega) K_U(\omega, A)$$

and  $\mathbb{K}^{\text{do}(U, \mathbb{Q})} = \{K_S^{\text{do}(U, \mathbb{Q})} : S \in \mathcal{P}(T)\}$  with

$$K_S^{\text{do}(U, \mathbb{Q})}(\omega, A) = \int \mathbb{Q}(d\omega'_{U \setminus S}) K_{S \cup U}((\omega_S, \omega'_{U \setminus S}), A).$$



# Axioms of Causal Kernels

Recall that causal kernels  $K_S$  from  $(\Omega, \mathcal{H}_S)$  into  $(\Omega, \mathcal{H})$  satisfy

① for all  $A \in \mathcal{H}$  and  $x \in \Omega$ ,

$$K_\emptyset(x, A) = \mathbb{P}(A);$$

② for all  $A \in \mathcal{H}_S$  and  $x \in \Omega$ ,

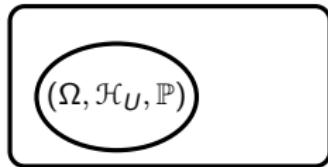
$$K_S(x, A) = 1_A(x).$$

Intuition on the axioms:

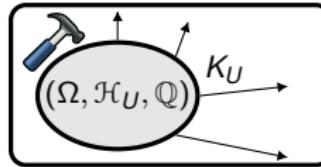
①  $\mathbb{P}^{\text{do}(\emptyset, \mathbb{Q})}(A) = \mathbb{P}(A)$ .

② For  $A \in \mathcal{H}_U$ ,  $\mathbb{P}^{\text{do}(U, \mathbb{Q})}(A) = \int \mathbb{Q}(dx) 1_A(x) = \mathbb{Q}(A)$ .

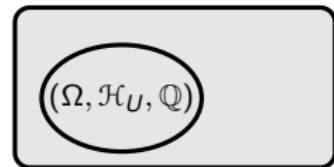
$(\Omega, \mathcal{H}, \mathbb{P}, \mathbb{K})$



$(\Omega, \mathcal{H}, ?, ?)$



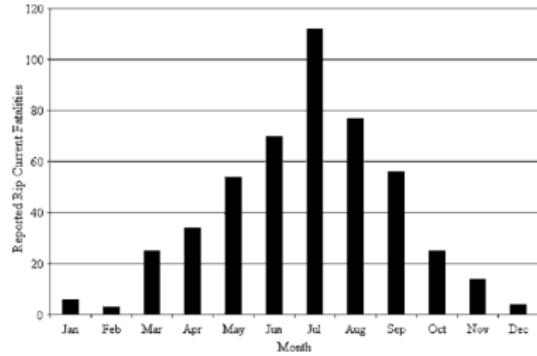
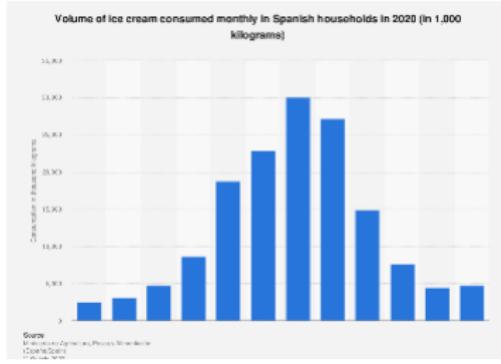
$(\Omega, \mathcal{H}, \mathbb{P}^{\text{do}(U, \mathbb{Q})}, \mathbb{K}^{\text{do}(U, \mathbb{Q})})$



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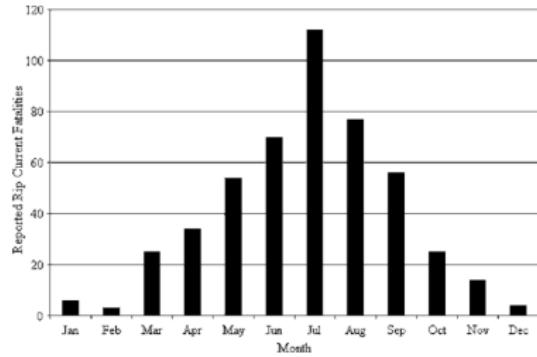
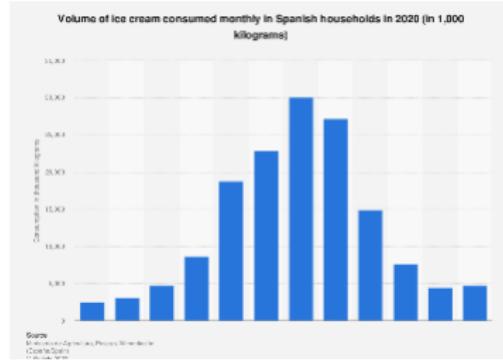
# Ice Cream Sales and Beach Accidents



- Causal space:  $(E_{\text{ice}} \times E_{\text{acc}}, \mathcal{E}_{\text{ice}} \otimes \mathcal{E}_{\text{acc}}, \mathbb{P}, \mathbb{K})^1$ .

<sup>1</sup> $E_{\text{ice}} = E_{\text{acc}} = \mathbb{R}$  and  $\mathcal{E}_{\text{ice}} = \mathcal{E}_{\text{acc}}$  is the Lebesgue  $\sigma$ -algebra.

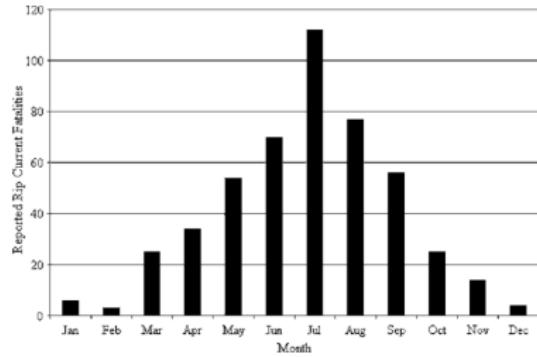
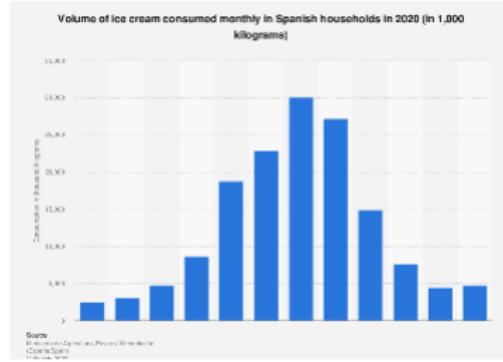
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- Causal space:  $(E_{\text{ice}} \times E_{\text{acc}}, \mathcal{E}_{\text{ice}} \otimes \mathcal{E}_{\text{acc}}, \mathbb{P}, \mathbb{K})^1$ .
- $\mathbb{P}$  has strong correlation.
- For causal kernels, let
  - $K_{\text{ice}}(x, A) = \mathbb{P}(A)$  for all  $A \in \mathcal{E}_{\text{acc}}$ ; and
  - $K_{\text{acc}}(y, B) = \mathbb{P}(B)$  for all  $B \in \mathcal{E}_{\text{ice}}$ .

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# Ice Cream Sales and Beach Accidents

- A Number of beach accidents.
- I Ice cream sales.

A

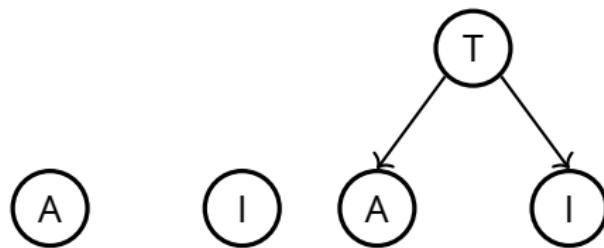
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# Ice Cream Sales and Beach Accidents

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T Temperature.



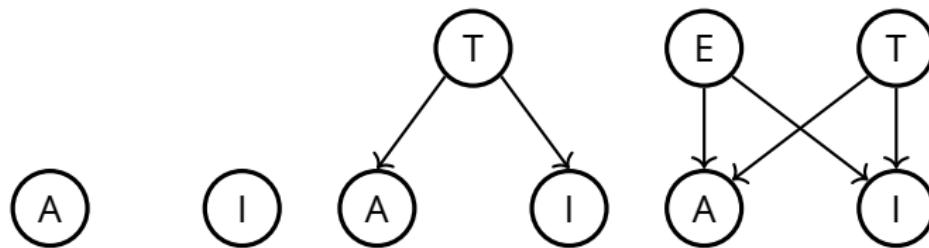
# Ice Cream Sales and Beach Accidents

A Number of beach accidents.

I Ice cream sales.

T Temperature.

E Economy.



# Ice Cream Sales and Beach Accidents

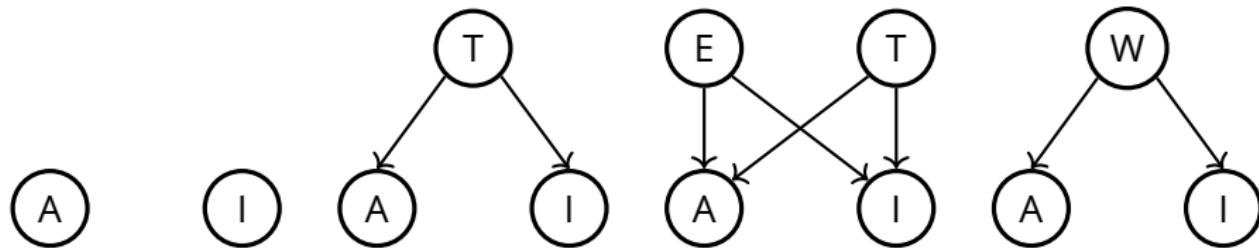
A Number of beach accidents.

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W World.



# Ice Cream Sales and Beach Accidents

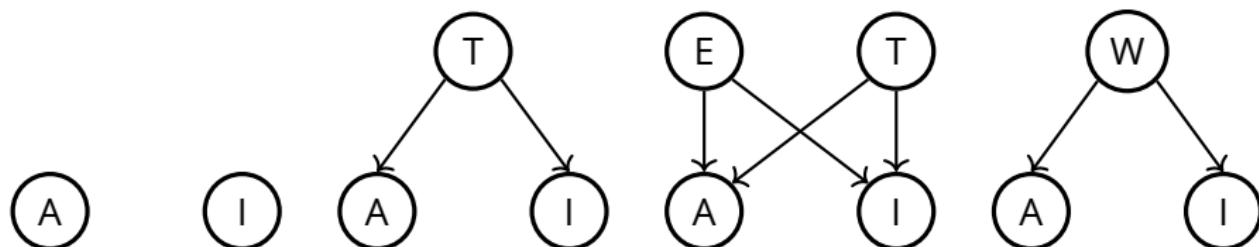
A Number of beach accidents.

I Ice cream sales.

T Temperature.

E Economy.

W World.



Recall:

- Causal space:  $(E_{\text{ice}} \times E_{\text{acc}}, \mathcal{E}_{\text{ice}} \otimes \mathcal{E}_{\text{acc}}, \mathbb{P}, \mathbb{K})$ .
- $\mathbb{P}$  has strong correlation.
- For causal kernels, let
  - $K_{\text{ice}}(x, A) = \mathbb{P}(A)$  for all  $A \in \mathcal{E}_{\text{acc}}$ ; and
  - $K_{\text{acc}}(y, B) = \mathbb{P}(B)$  for all  $B \in \mathcal{E}_{\text{ice}}$ .

# Crop Yield and Price

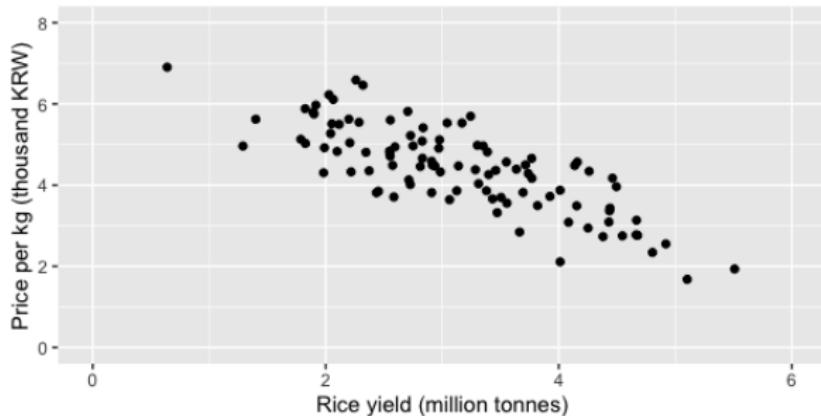
- Causal space:  $(E_{\text{rice}} \times E_{\text{price}}, \mathcal{E}_{\text{rice}} \otimes \mathcal{E}_{\text{price}}, \mathbb{P}, \mathbb{K})^2$ .

---

<sup>2</sup> $E_{\text{rice}} = E_{\text{price}} = \mathbb{R}$  and  $\mathcal{E}_{\text{rice}} = \mathcal{E}_{\text{price}}$  is the Lebesgue  $\sigma$ -algebra.

# Crop Yield and Price

- Causal space:  $(E_{\text{rice}} \times E_{\text{price}}, \mathcal{E}_{\text{rice}} \otimes \mathcal{E}_{\text{price}}, \mathbb{P}, \mathbb{K})^2$ .
- No Intervention:



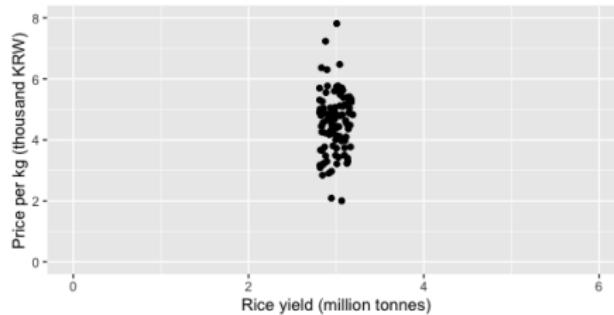
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# Crop Yield and Price

- Intervention to fix rice = 3:

$$K_{\text{rice}}(3, A) = \int_A \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}(x-4.5)^2} dx$$

for  $A \in \mathcal{E}_{\text{price}}$ .

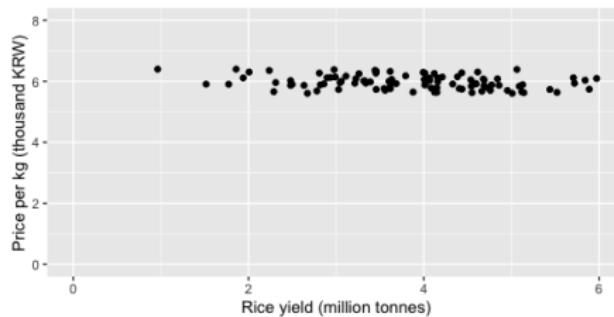


# Crop Yield and Price

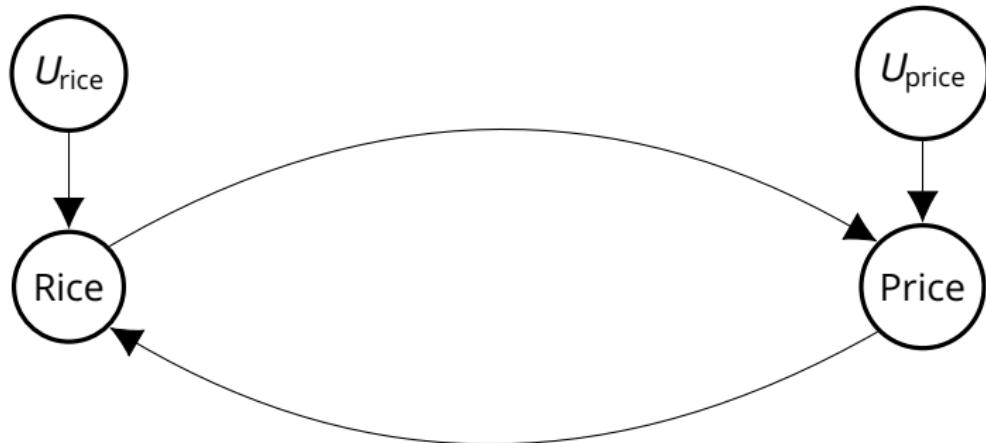
- Intervention to fix price = 6:

$$K_{\text{price}}(6, B) = \int_B \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}(x-4)^2} dx$$

for  $B \in \mathcal{E}_{\text{rice}}$ .

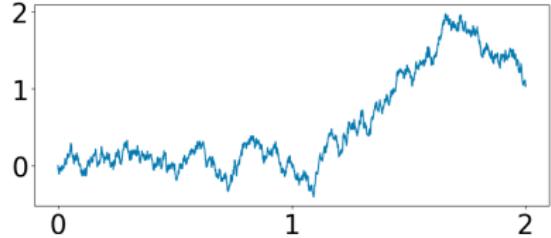
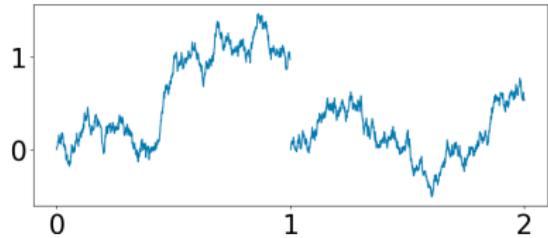


# Crop Yield and Price



$$\text{Rice} = f_{\text{rice}}(\text{Price}, U_{\text{rice}}), \quad \text{Price} = f_{\text{price}}(\text{Rice}, U_{\text{price}}).$$

# 1-dimensional Brownian Motion

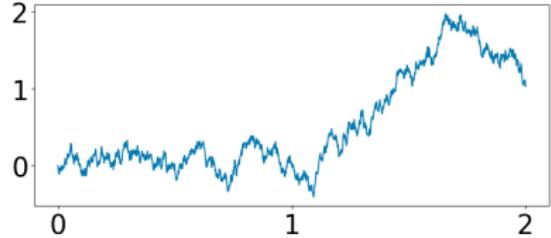
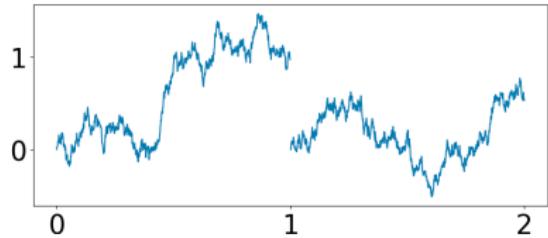


- Causal space:  $(\times_{t \in \mathbb{R}_+} E_t, \otimes_{t \in \mathbb{R}_+} \mathcal{E}_t, \mathbb{P}, \mathbb{K})^3$ .

---

<sup>3</sup>For each  $t \in \mathbb{R}_+$ ,  $E_t = \mathbb{R}$  and  $\mathcal{E}_t$  is the Lebesgue  $\sigma$ -algebra.

# 1-dimensional Brownian Motion

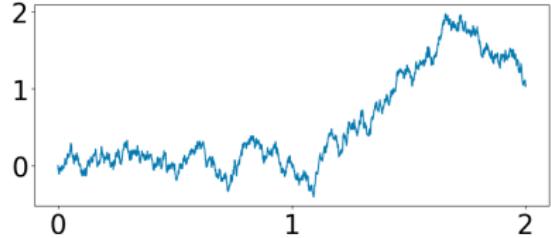
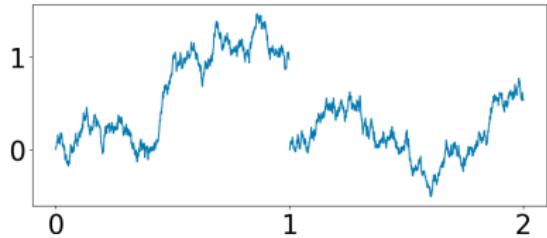


- Causal space:  $(\times_{t \in \mathbb{R}_+} E_t, \otimes_{t \in \mathbb{R}_+} \mathcal{E}_t, \mathbb{P}, \mathbb{K})^3$ .
- $\mathbb{P}$  is the Wiener measure.

---

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# 1-dimensional Brownian Motion



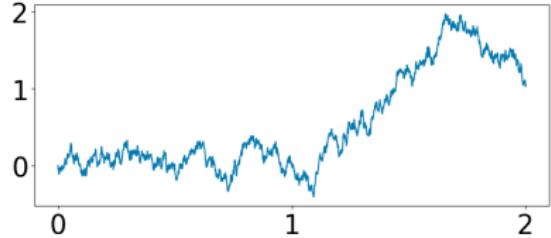
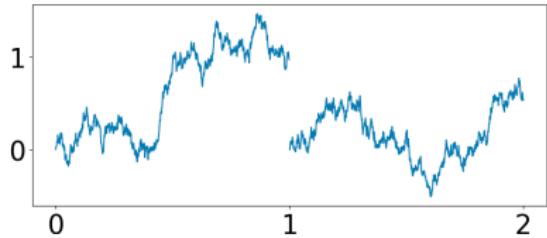
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- $\mathbb{P}$  is the Wiener measure.
- For any  $s < t$ , the causal kernels are

$$K_s(x, y) = \frac{1}{\sqrt{2\pi(t-s)}} e^{-\frac{1}{2(t-s)}(y-x)^2}, \quad K_t(x, y) = \frac{1}{\sqrt{2\pi s}} e^{-\frac{1}{2s}y^2}.$$

---

<sup>3</sup>For each  $t \in \mathbb{R}_+$ ,  $E_t = \mathbb{R}$  and  $\mathcal{E}_t$  is the Lebesgue  $\sigma$ -algebra.

# 1-dimensional Brownian Motion



- Causal space:  $(\times_{t \in \mathbb{R}_+} E_t, \otimes_{t \in \mathbb{R}_+} \mathcal{E}_t, \mathbb{P}, \mathbb{K})^3$ .
- $\mathbb{P}$  is the Wiener measure.
- For any  $s < t$ , the causal kernels are

$$K_s(x, y) = \frac{1}{\sqrt{2\pi(t-s)}} e^{-\frac{1}{2(t-s)}(y-x)^2}, \quad K_t(x, y) = \frac{1}{\sqrt{2\pi s}} e^{-\frac{1}{2s}y^2}.$$

**Past values affect the future, but future values do not affect the past.**

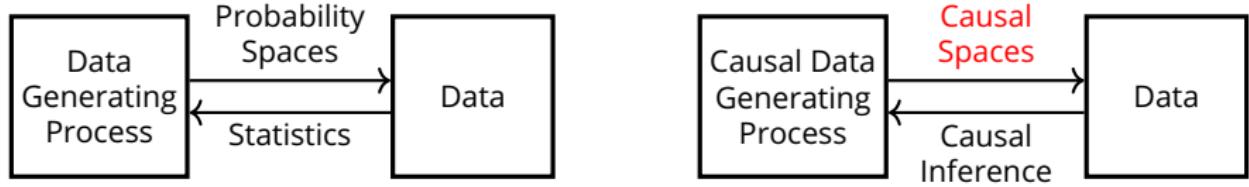
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<sup>3</sup>For each  $t \in \mathbb{R}_+$ ,  $E_t = \mathbb{R}$  and  $\mathcal{E}_t$  is the Lebesgue  $\sigma$ -algebra.

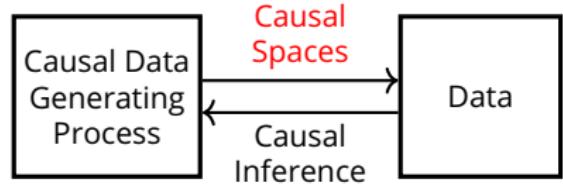
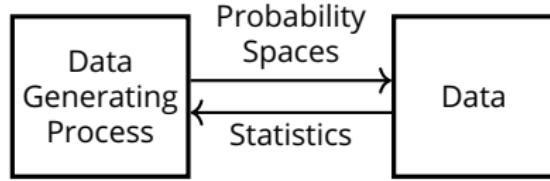
# Table of Contents

- 1 Introduction & Motivation
- 2 Causal Spaces
- 3 Examples
- 4 Conclusion

# Summary



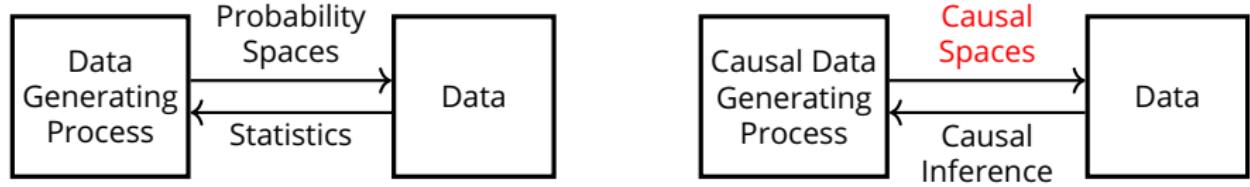
# Summary



## Causal spaces

- are a **measure-theoretic axiomatisation** of causality;

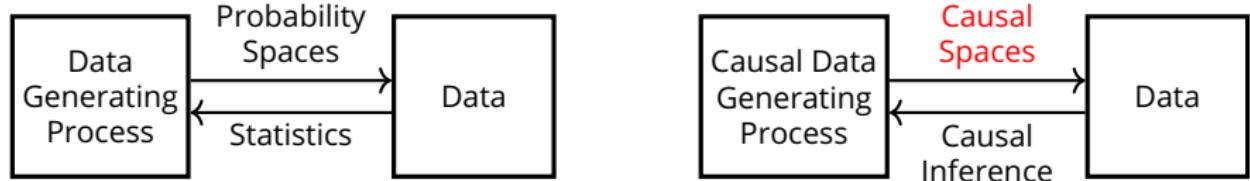
# Summary



## Causal spaces

- are a **measure-theoretic axiomatisation** of causality;
- strictly generalise existing frameworks;

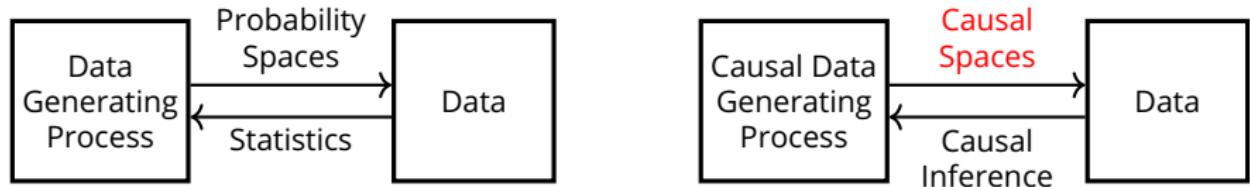
# Summary



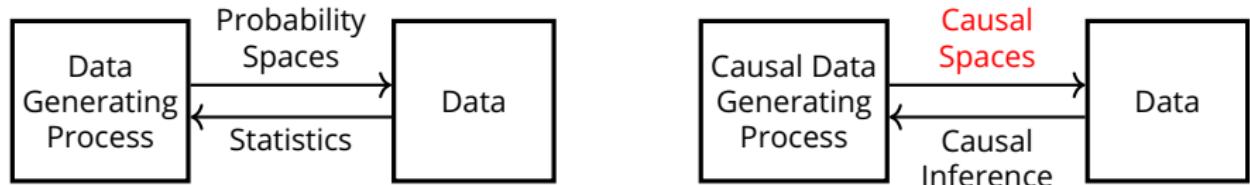
## Causal spaces

- are a **measure-theoretic axiomatisation** of causality;
- strictly generalise existing frameworks;
- overcome long-standing limitations of existing frameworks, for example,
  - latent confounders,
  - cyclic causal relationships,
  - continuous-time stochastic processes.

# Summary

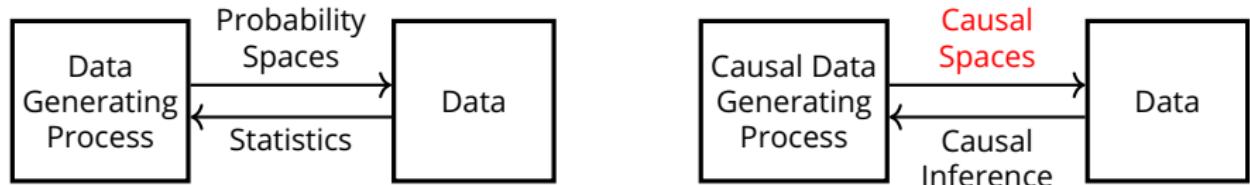


# Summary



- We hope that causal spaces can play the same role as probability spaces for causality.

# Summary



- We hope that causal spaces can play the same role as probability spaces for causality.
- Our view is that SCMs and potential outcomes are valuable tools to specify a causal space.

# Not covered in this talk

- Causal effect [1].
- Sources & identifiability [1].
- Causal stochastic processes [1].

---

[1] A Measure-Theoretic Axiomatisation of Causality, P., Buchholz, Schölkopf and Muandet, NeurIPS 2023

[2] Products, Abstractions and Inclusions of Causal Spaces, Buchholz\*, P.\* and Schölkopf, UAI 2024

# Not covered in this talk

- Causal effect [1].
- Sources & identifiability [1].
- Causal stochastic processes [1].
- Multiple causal spaces [2].
- Causal independence [2].

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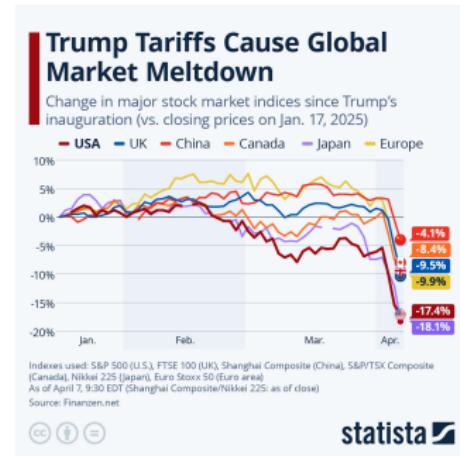
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[2] Products, Abstractions and Inclusions of Causal Spaces, Buchholz\*, P.\* and Schölkopf, UAI 2024

# Not covered in this talk

## Counterfactuals

- Counterfactuals [3].
- Fundamental Theorem of Causality [3].
- Independence and Synchronisation of counterfactual worlds [3].



[3] Counterfactual Causal Spaces and the Fundamental Theorem of Causality, P., Yang and Icard, to be submitted soon.

Thank you.