

GST-UNet: Spatiotemporal Causal Inference with Time-Varying Confounders

Space X Time X Causality Reading Group

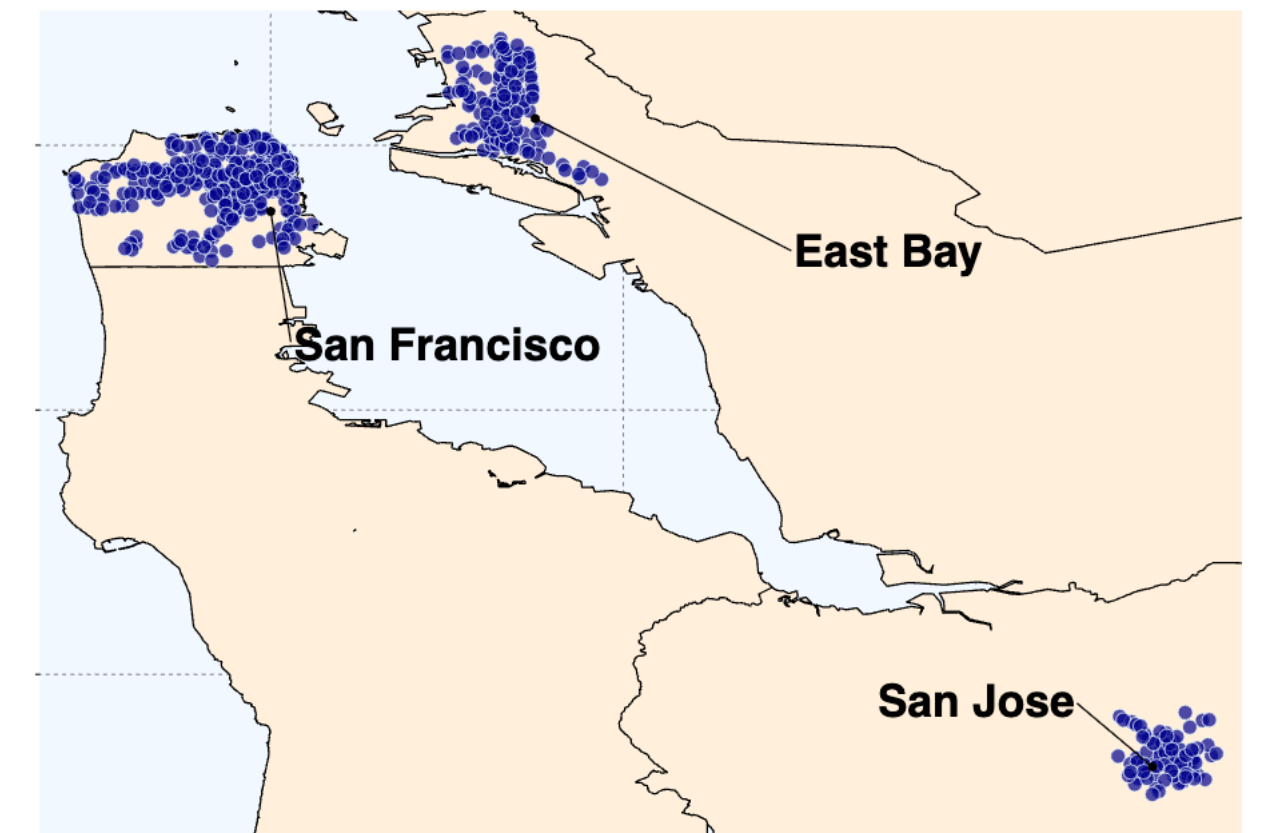
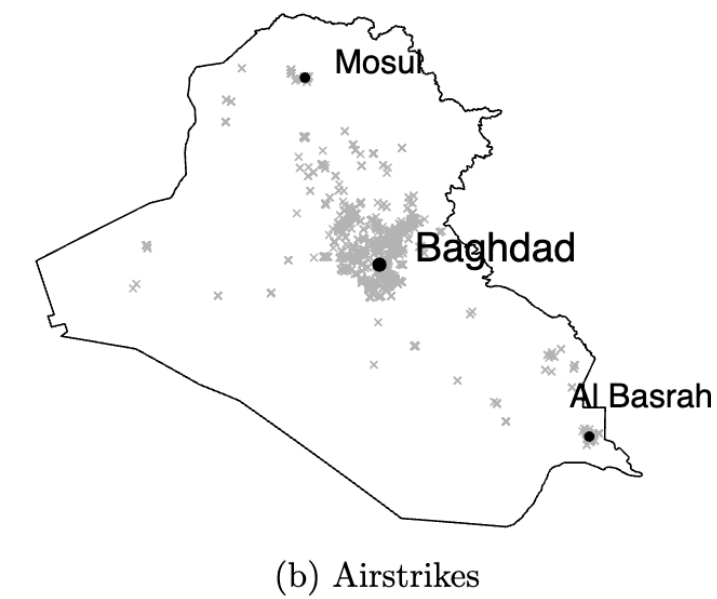
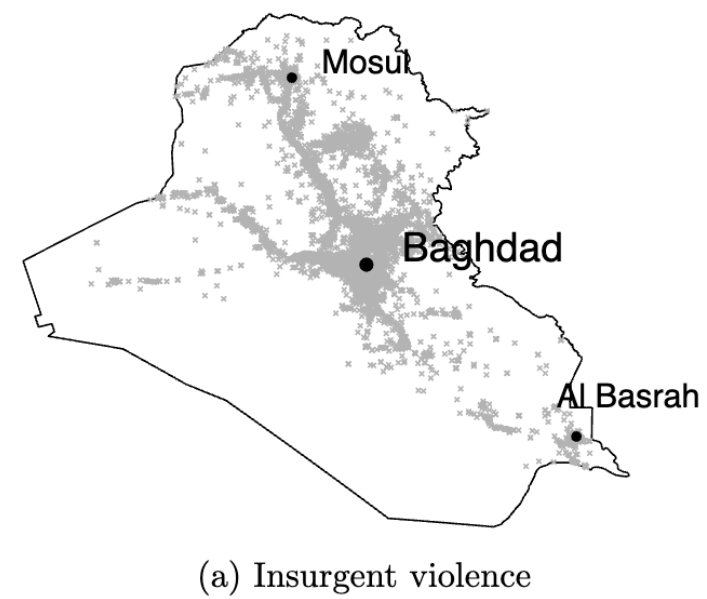
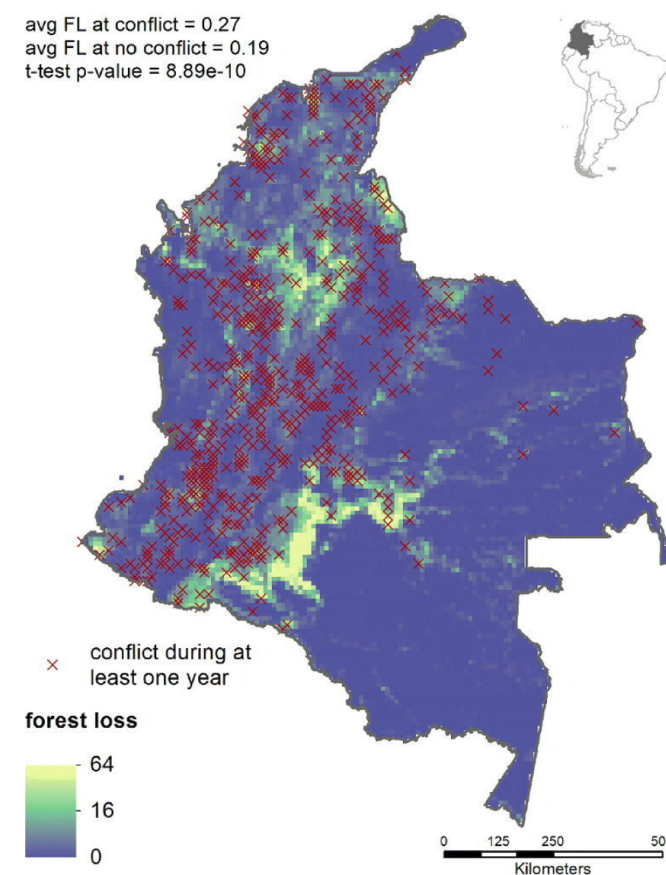


Gerrit Großmann, May 28

Reminder

cumulative forest loss 2000–2018

avg FL at conflict = 0.27
avg FL at no conflict = 0.19
t-test p-value = 8.89e-10

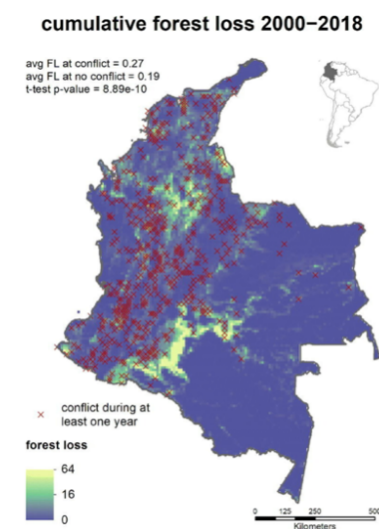


Conflict
Deforestation
Road Network

Airstrikes
Insurgency Violence
Aid

Wildfire
Bike Rental Hours
Temperature + Wind

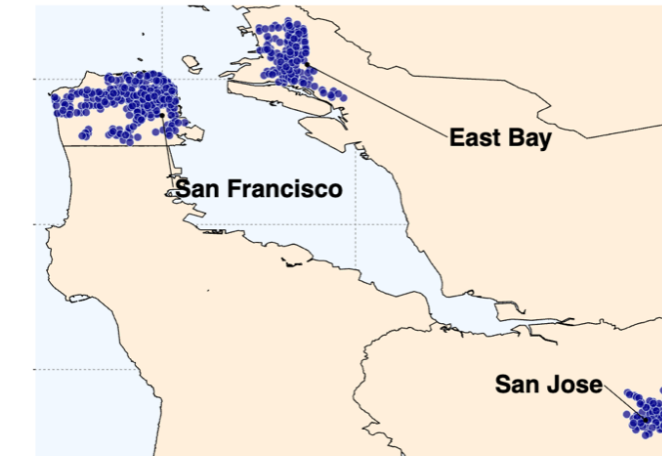
Challenges



Conflict
Deforestation
Road Network



Airstrikes
Insurgency Violence
Aid



Wildfire
Bike Rental Hours
Temperature + Wind

(Temporal) Carryover:

A wildfire today increases bike rentals tomorrow.

(Spatial) Spillover:

A wildfire in one county drifts into neighboring counties.

Time-Varying Confounding:

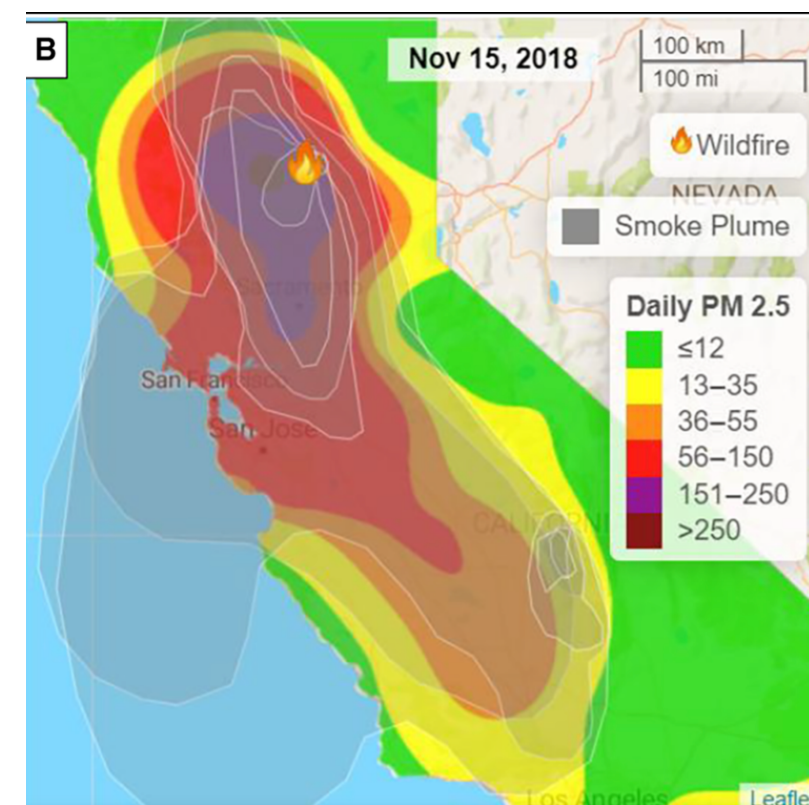
Weather affects wildfires and bike rentals.

Treatment-Covariate Feedback:

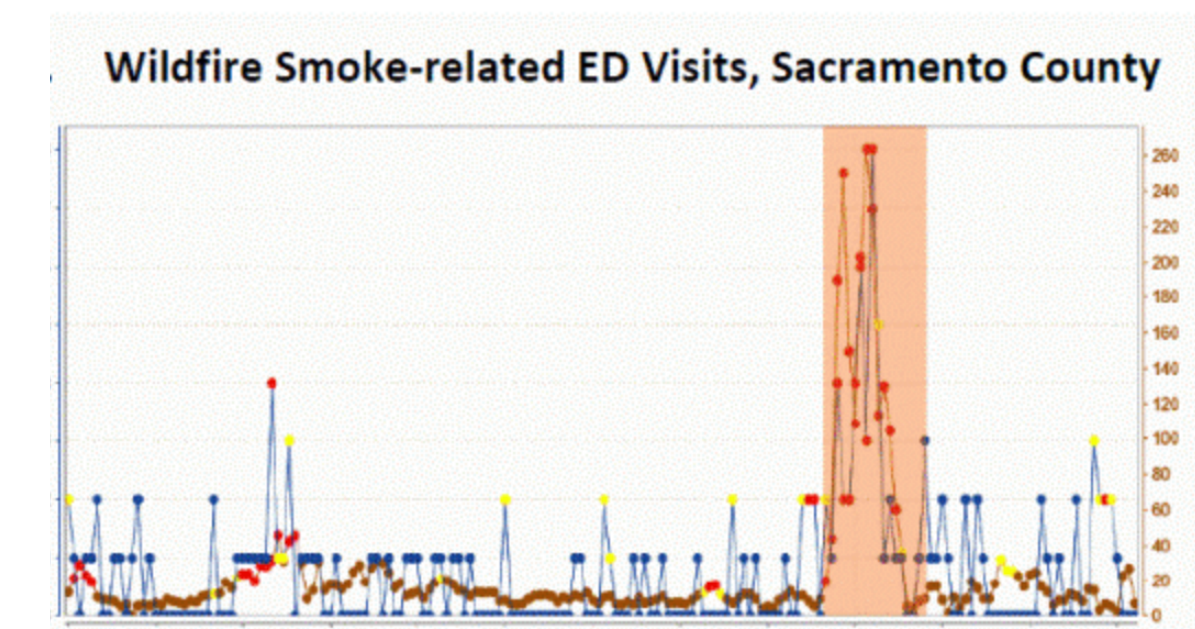
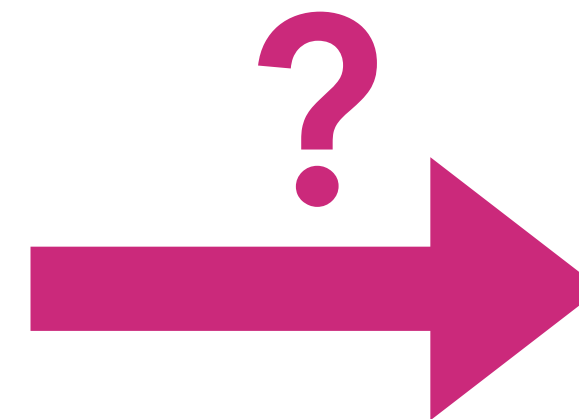
A Covid lockdown reduces mobility, which in turn affects lockdown necessity.

GST-UNet: Spatiotemporal Causal Inference with Time-Varying Confounders

Miruna Oprescu¹ David K. Park² Xihaier Luo² Shinjae Yoo² Nathan Kallus¹



Wildfire Air Pollution and Rates of Cardiovascular Events and Mortality in Northern California in 2018 (Alexeeff et al., 2025)



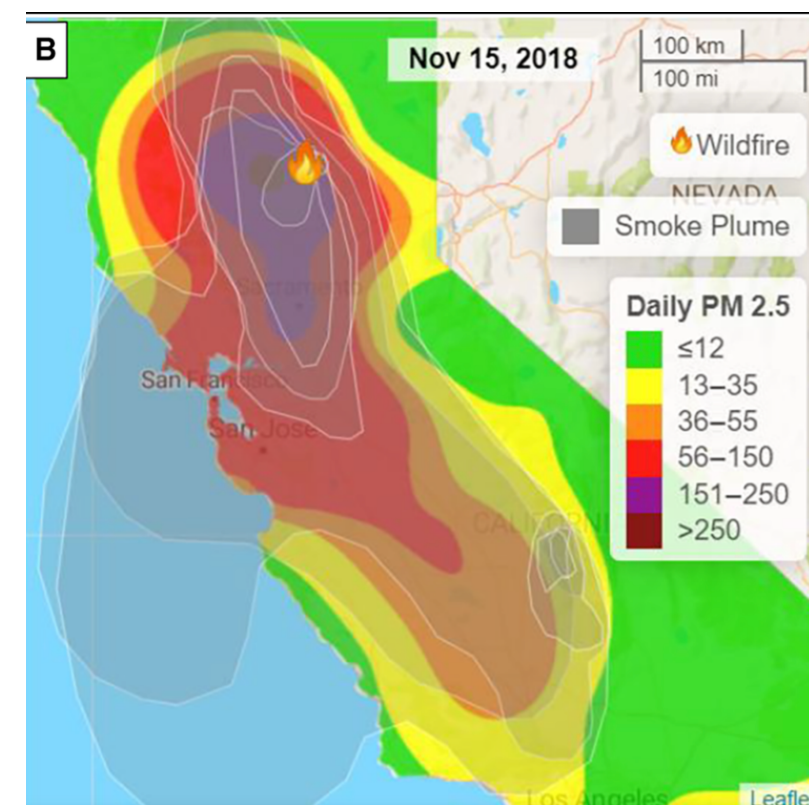
<https://www.cdc.gov/nssp/php/story/regional-collaboration-during-california-wildfires.html>

Wildfire smoke exposure
during the 2018 Camp Fire

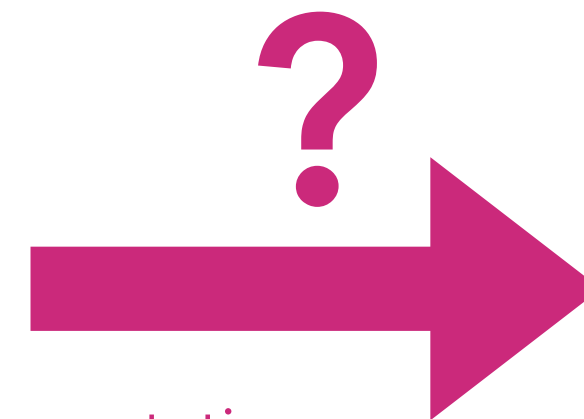
Respiratory hospitalizations

GST-UNet: Spatiotemporal Causal Inference with Time-Varying Confounders

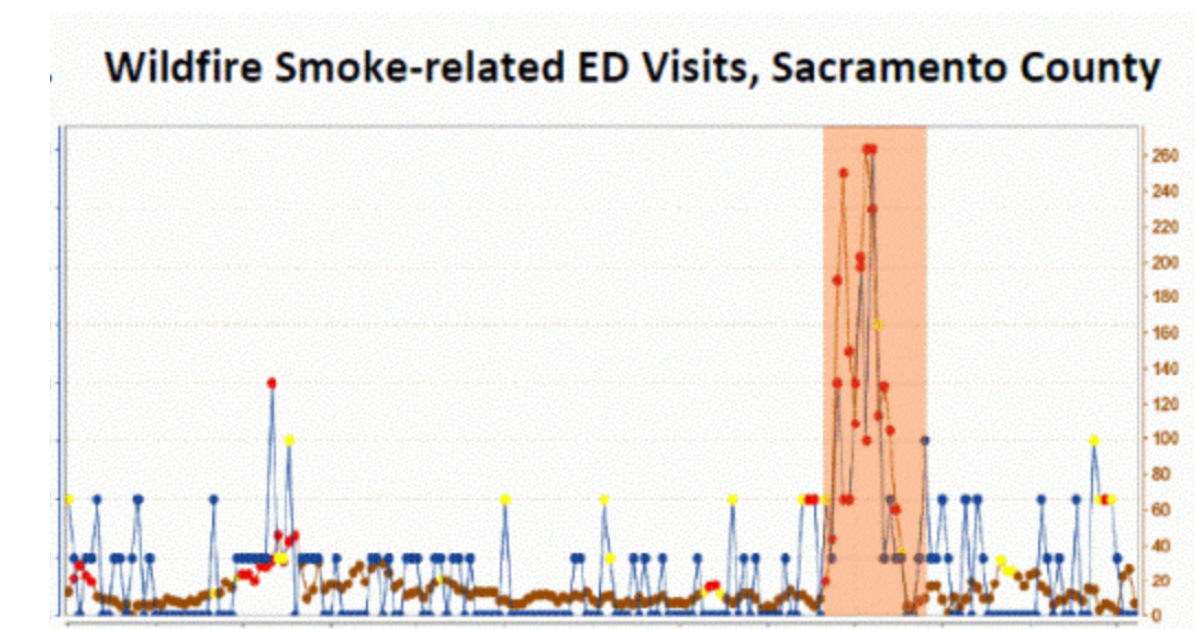
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Wildfire Air Pollution and Rates of Cardiovascular Events and Mortality in Northern California in 2018 (Alexeeff et al., 2025)



- G-computation
- NN-based spatio-temporal prediction
- Single realization of the process

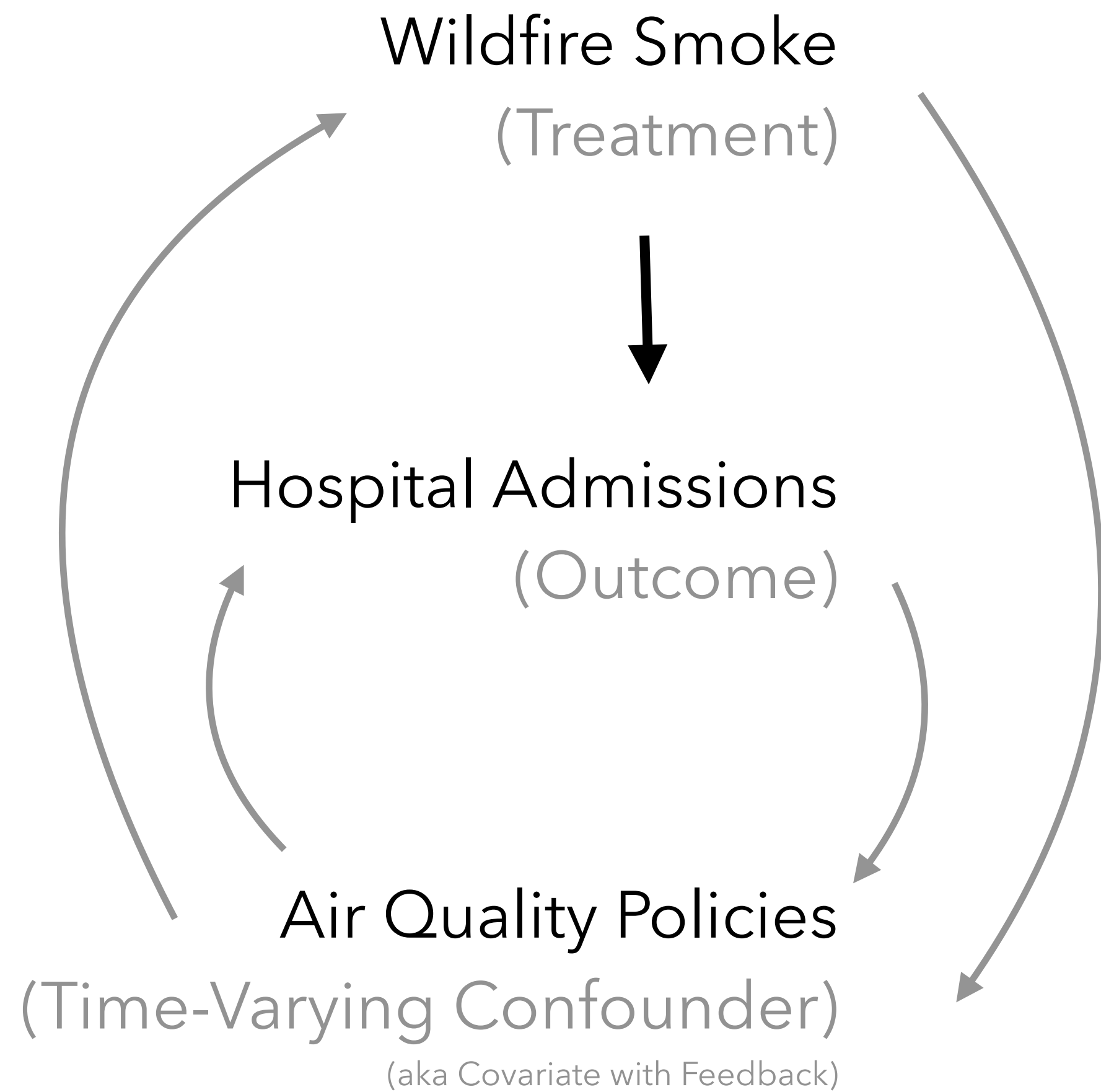


<https://www.cdc.gov/nssp/php/story/regional-collaboration-during-california-wildfires.html>

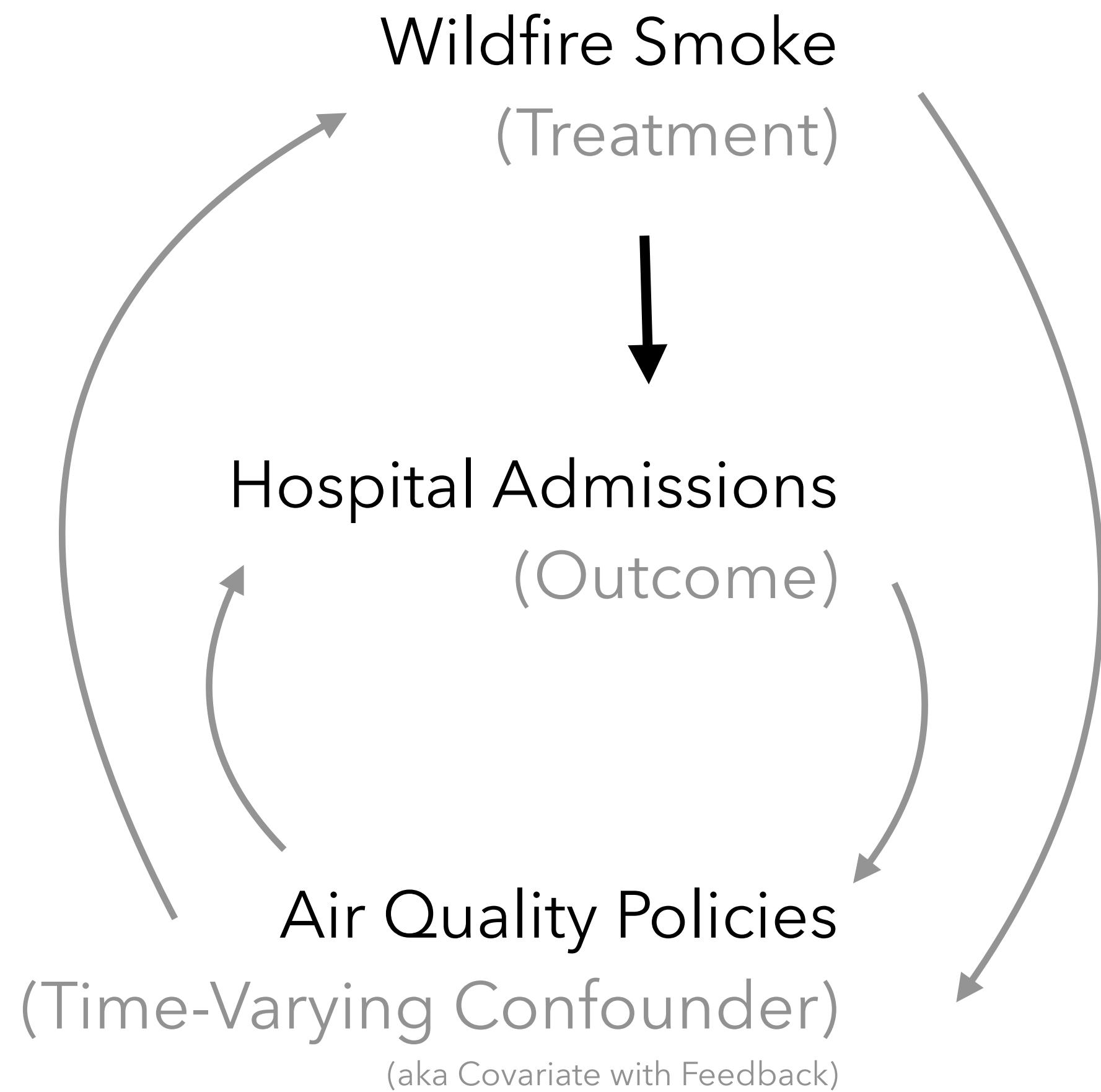
Wildfire smoke exposure
during the 2018 Camp Fire

Respiratory hospitalizations

Running Example



Running Example

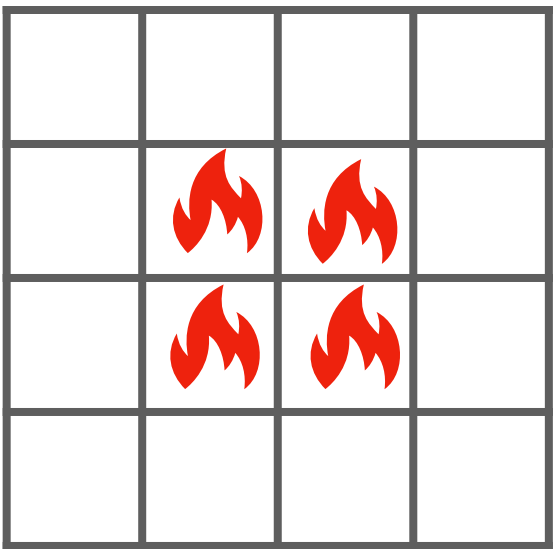
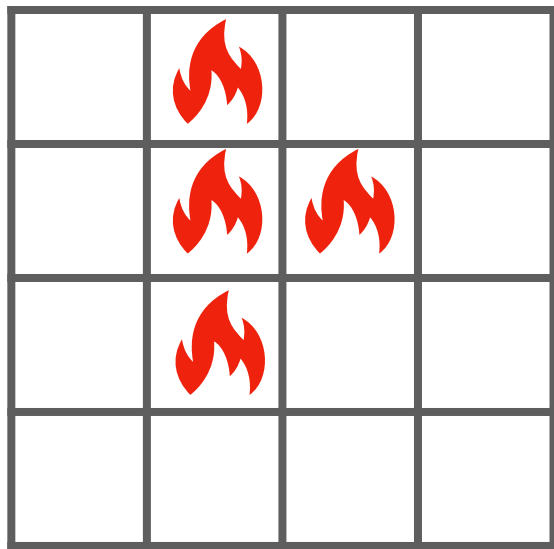
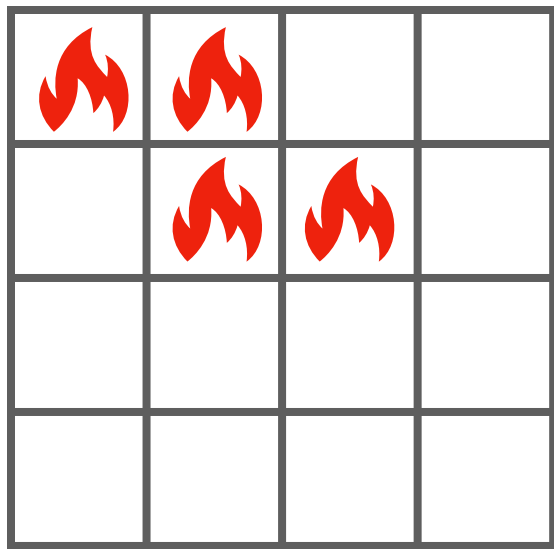
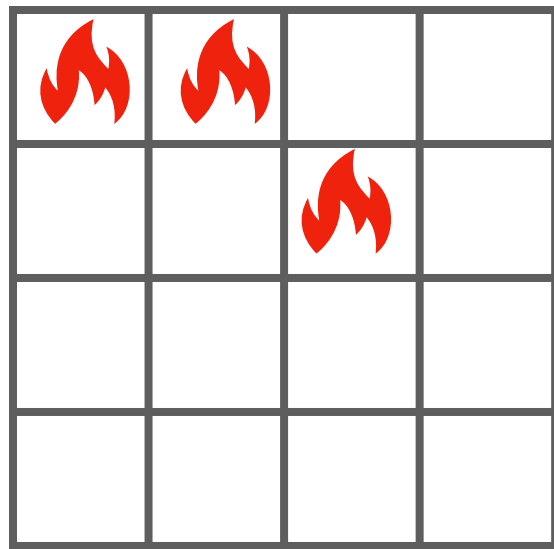


Time-varying confounders:

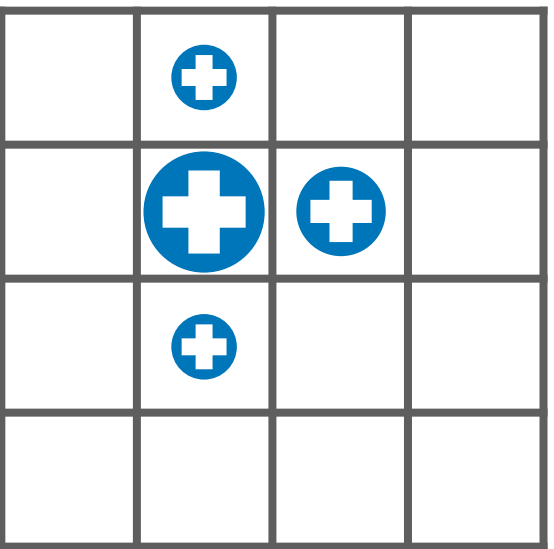
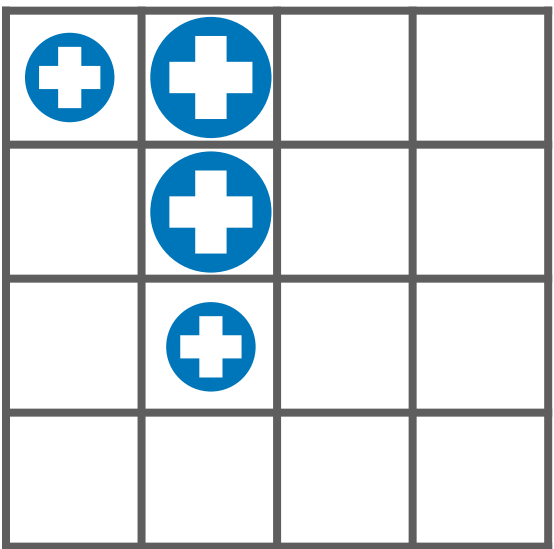
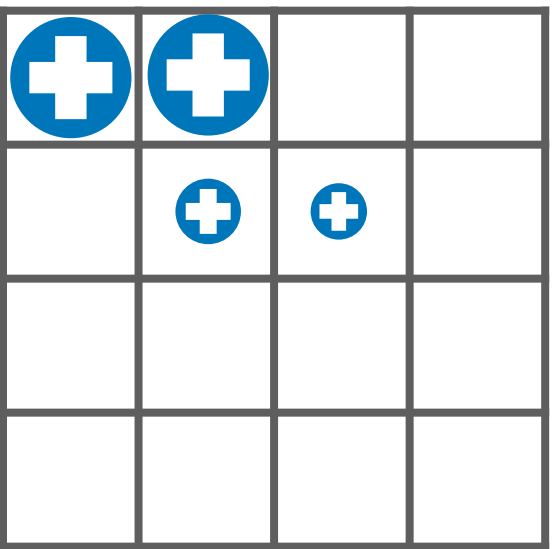
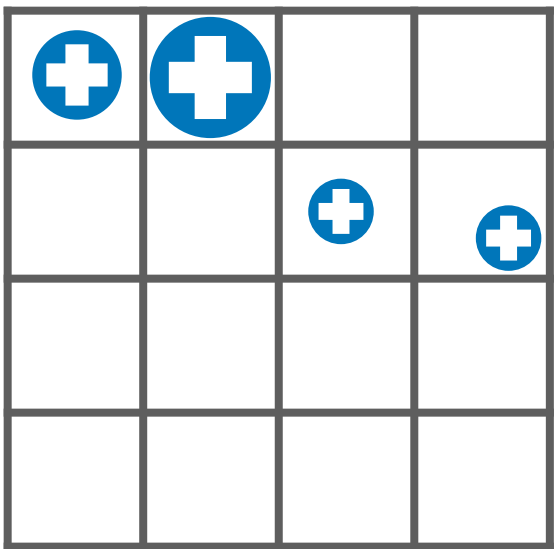
Covariates that both influence and are influenced by past treatments and outcomes (creates feedback loops).

Running Example

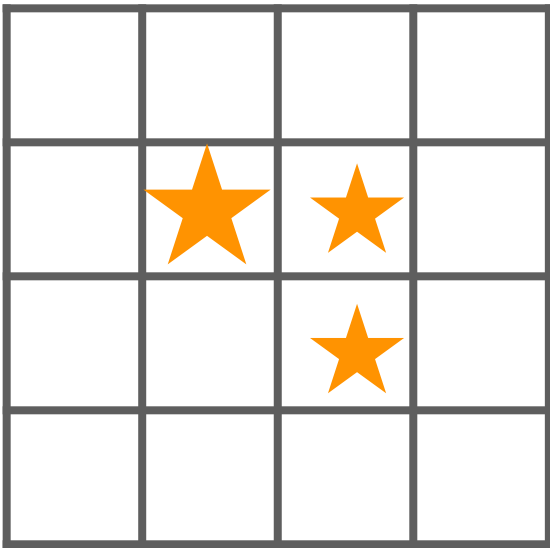
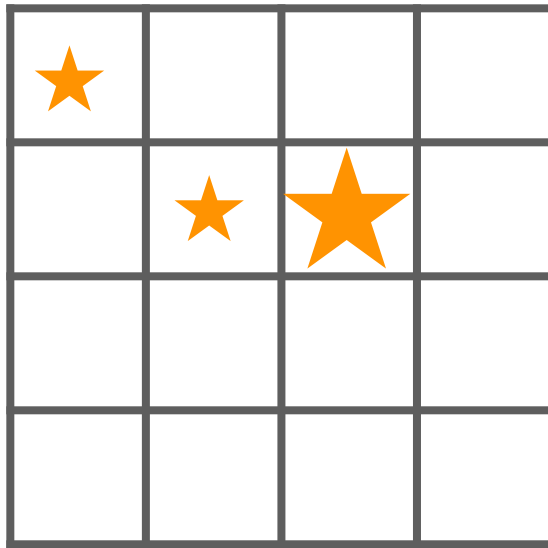
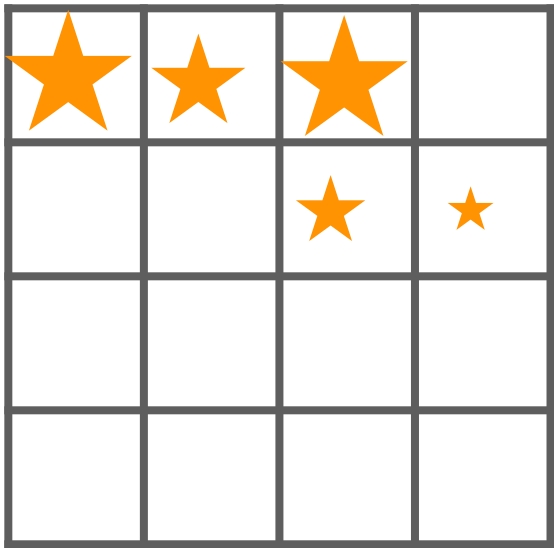
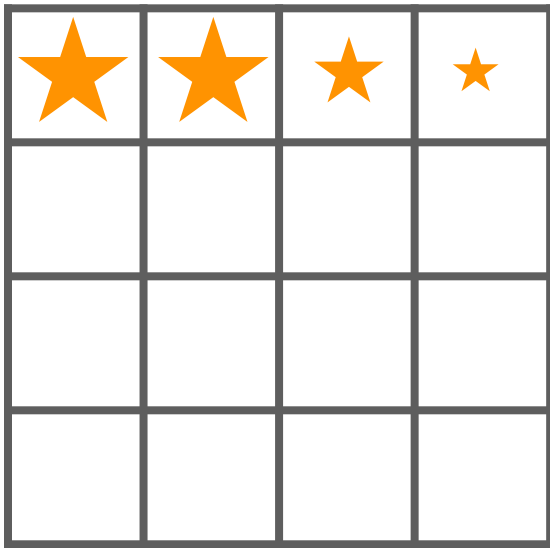
Wildfire Smoke
(Treatment)



Hospital Admissions
(Outcome)

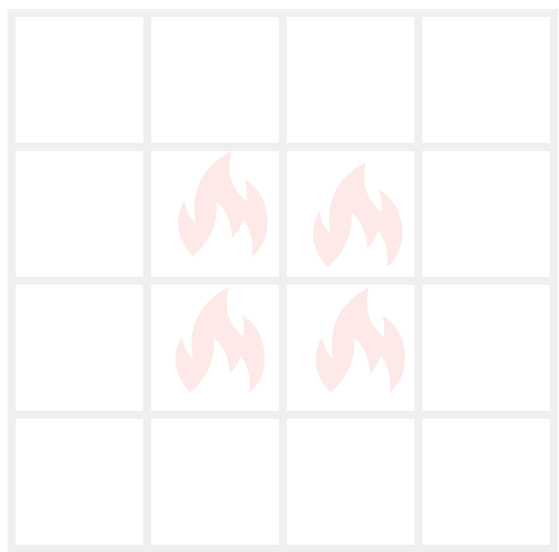
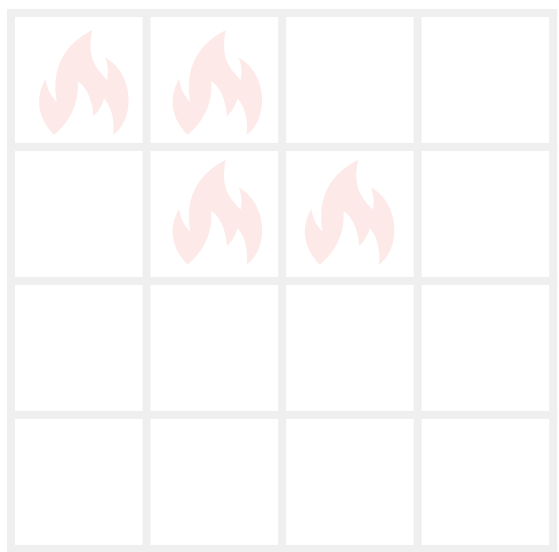
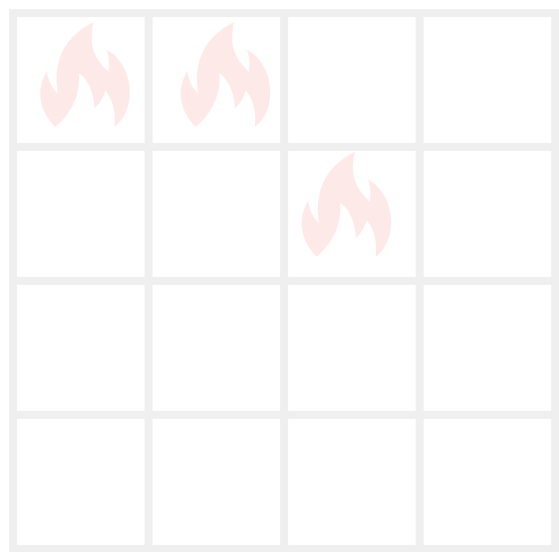


Air Quality Policies
(Time-Varying Confounder)
(aka Covariate with Feedback)



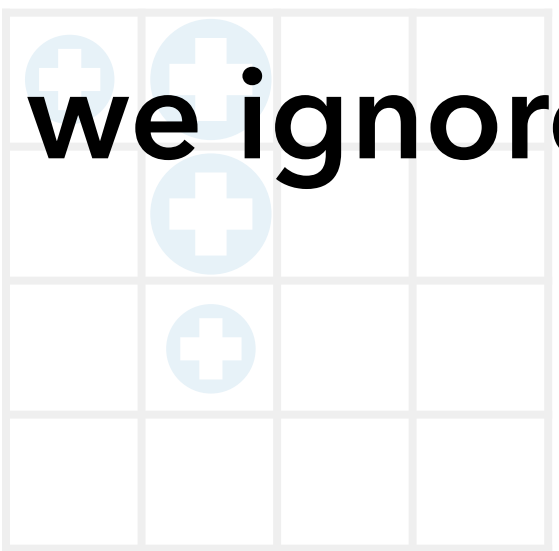
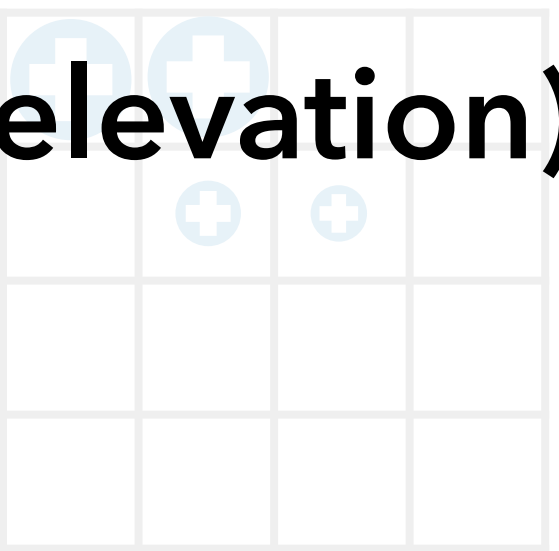
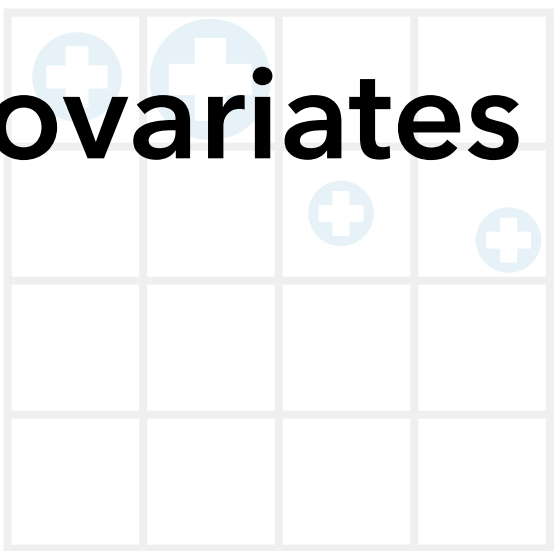
Running Example

Wildfire Smoke
(Treatment)

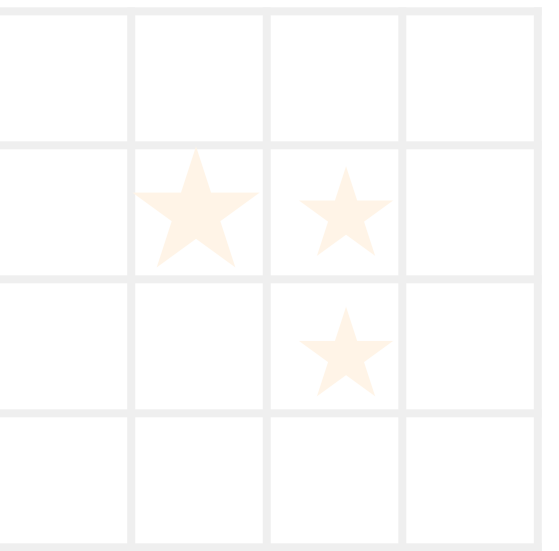


They also have fixed covariates (like elevation) that we ignore for now.

Hospital Admissions
(Outcome)

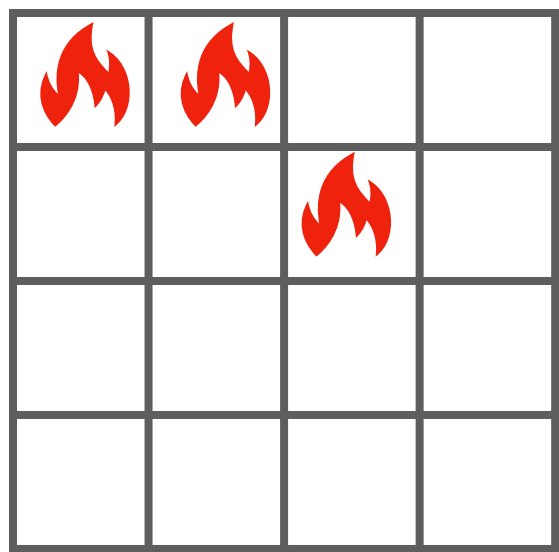


Air Quality Policies
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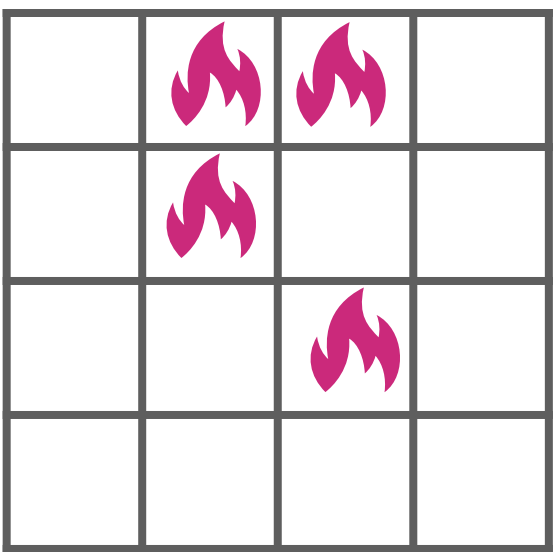
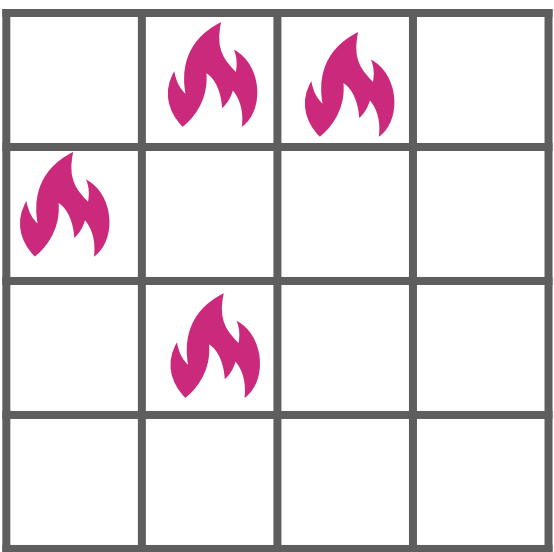
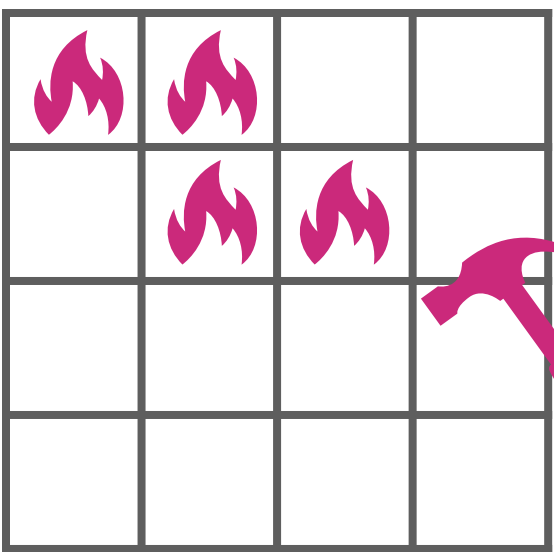


Running Example

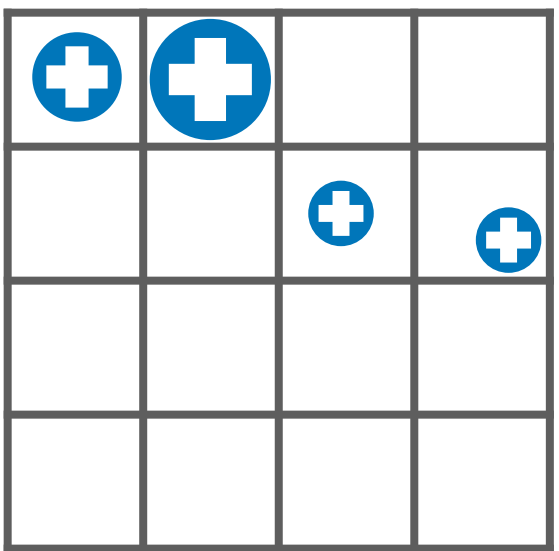
Wildfire Smoke
(Treatment)



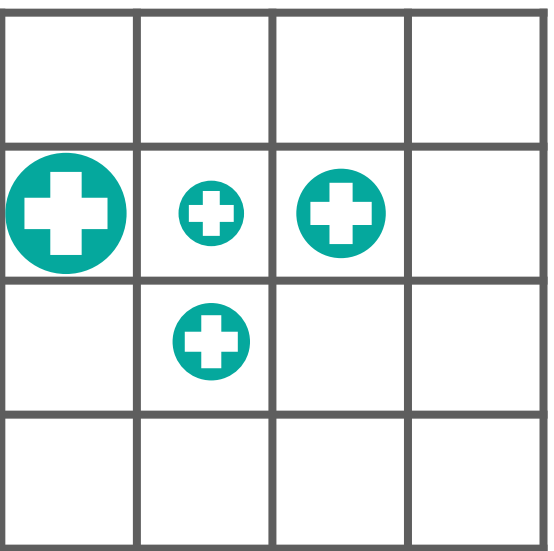
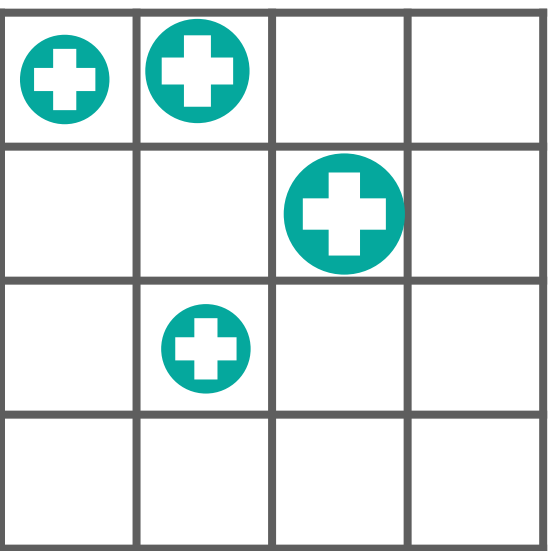
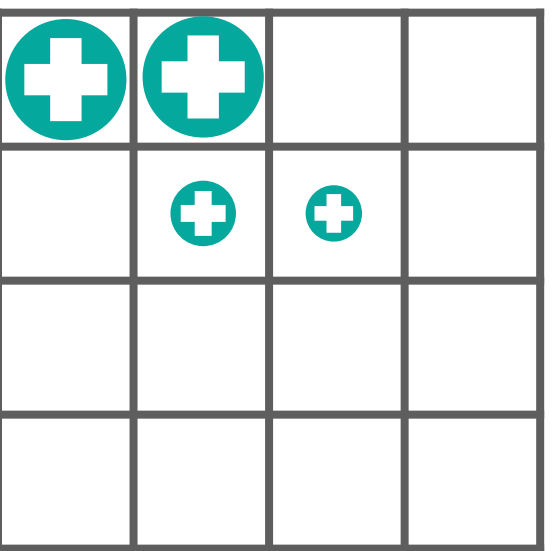
Counterfactual treatment sequence



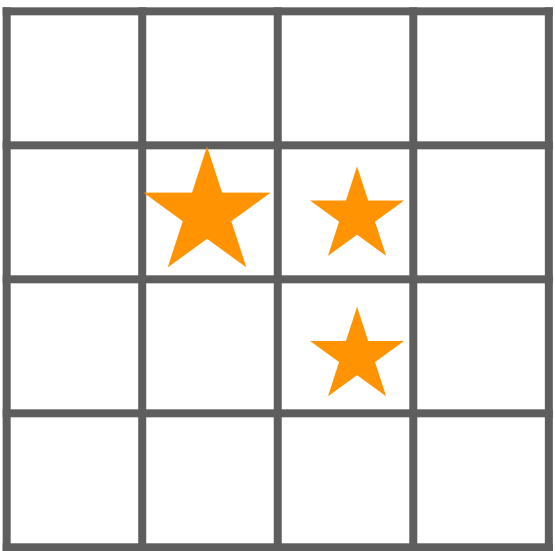
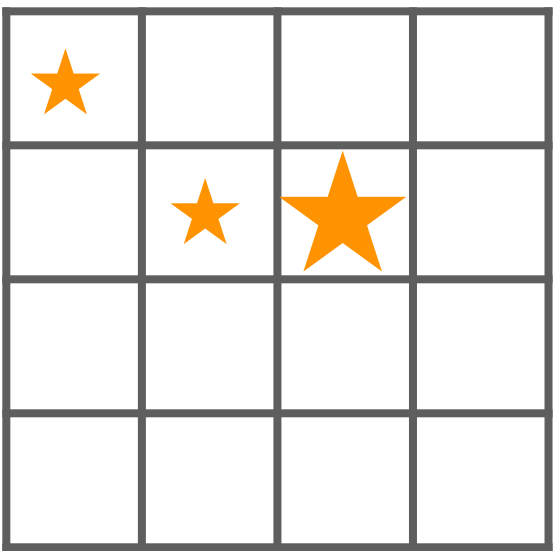
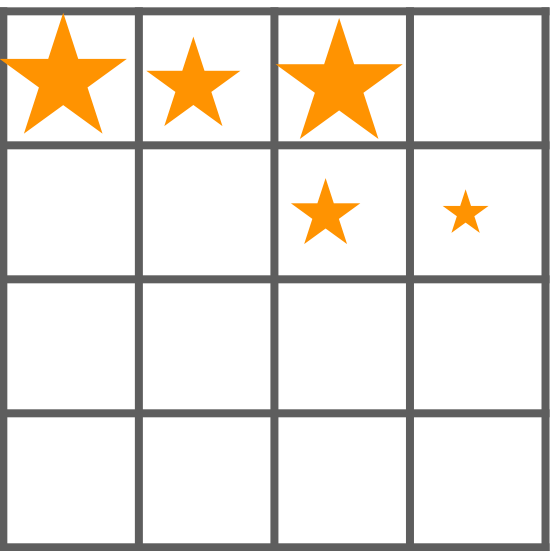
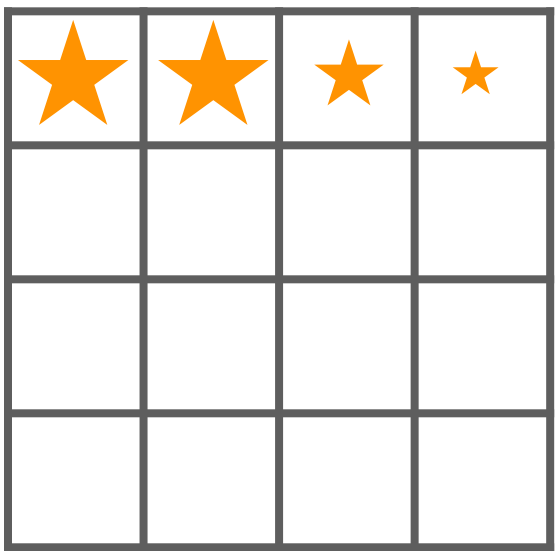
Hospital Admissions
(Outcome)



Counterfactual treatment sequence

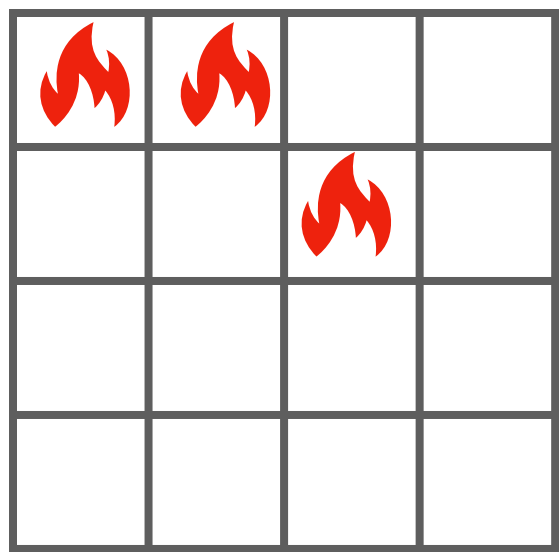


Air Quality Policies
(Time-Varying Confounder)
(aka Covariate with Feedback)

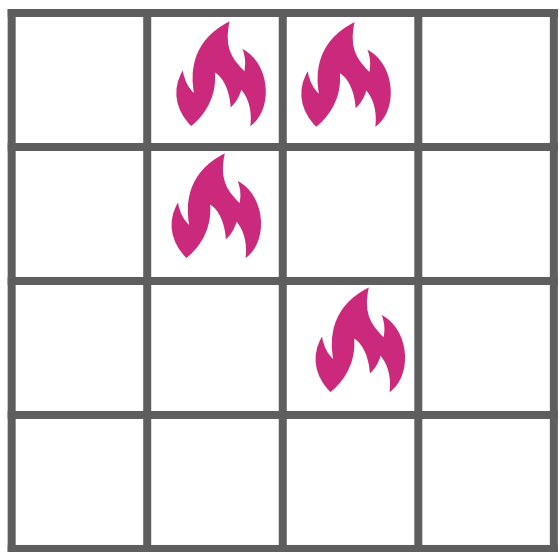
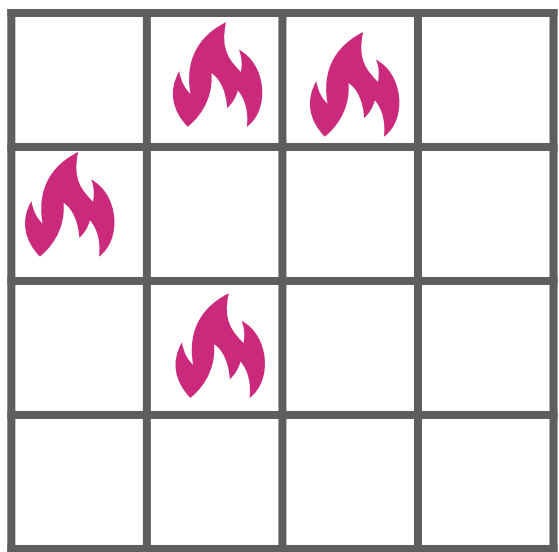
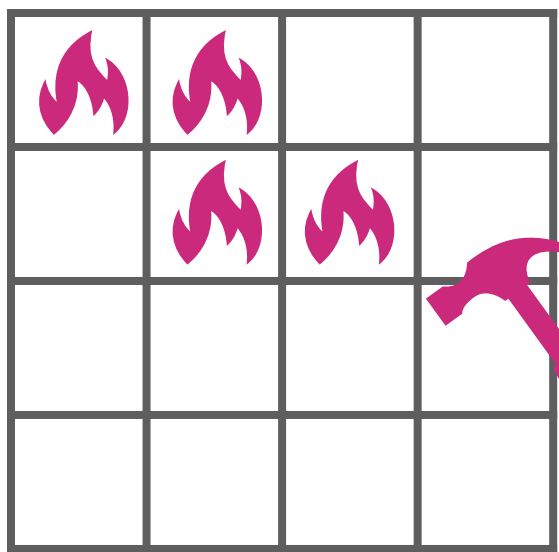


Running Example

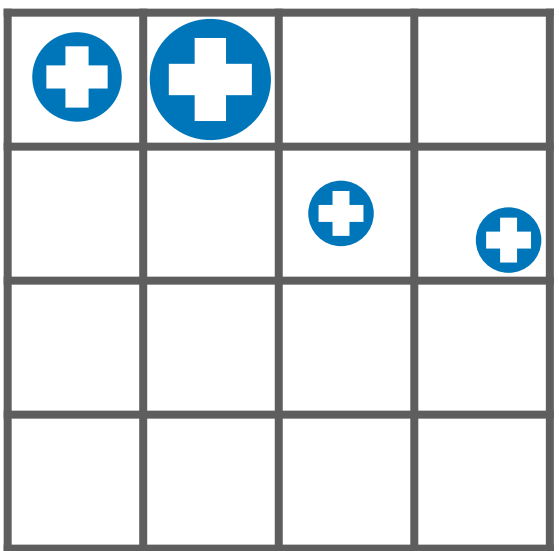
Wildfire Smoke
(Treatment)



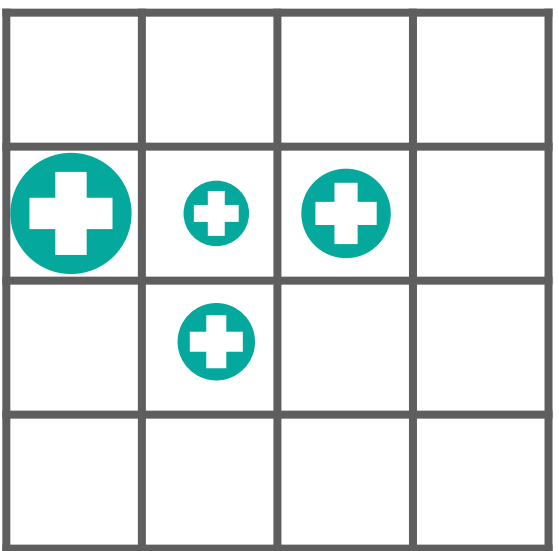
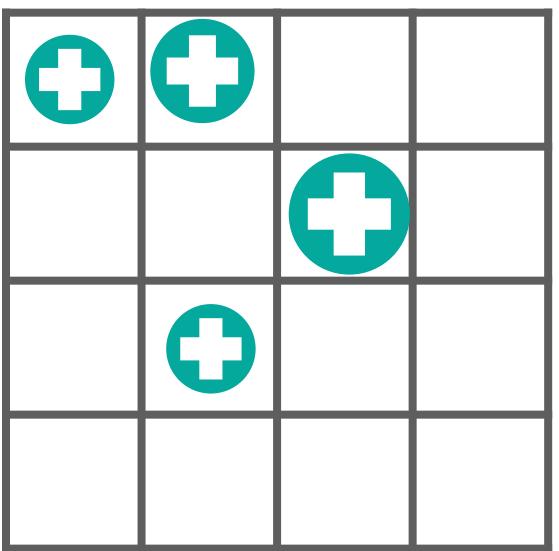
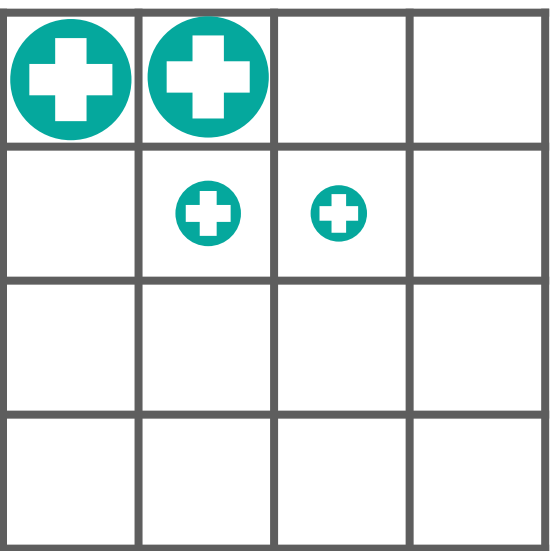
Counterfactual treatment sequence



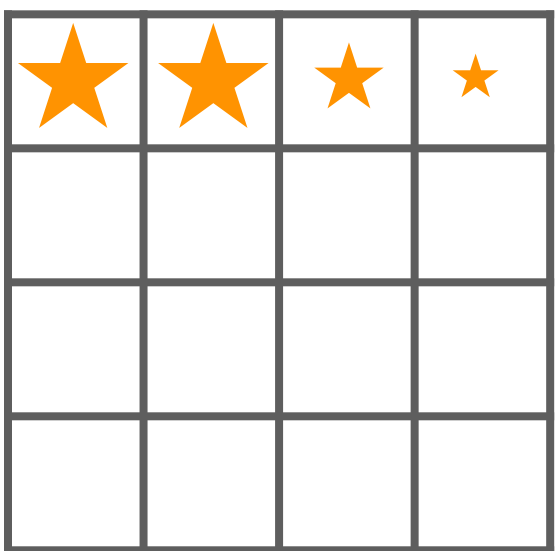
Hospital Admissions
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Counterfactual treatment sequence

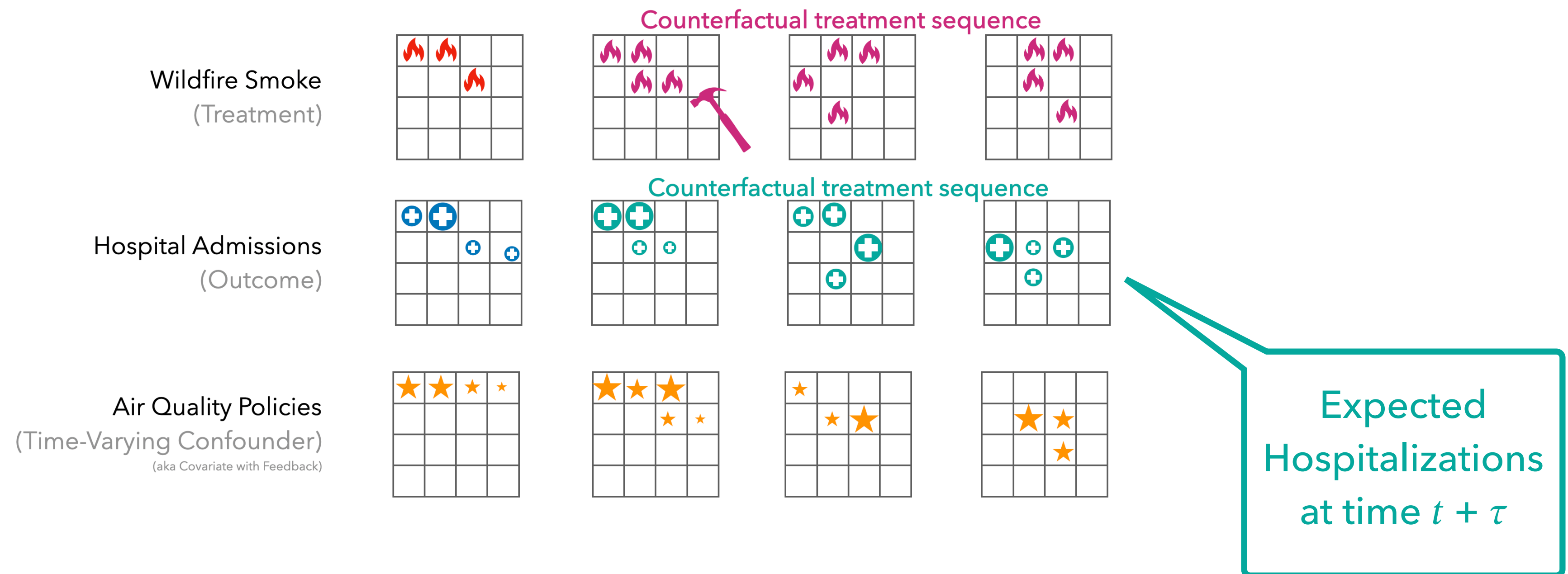


Air Quality Policies
(Time-Varying Confounder)
(aka Covariate with Feedback)



This will also change but we only
compute this implicitly.

CAPO

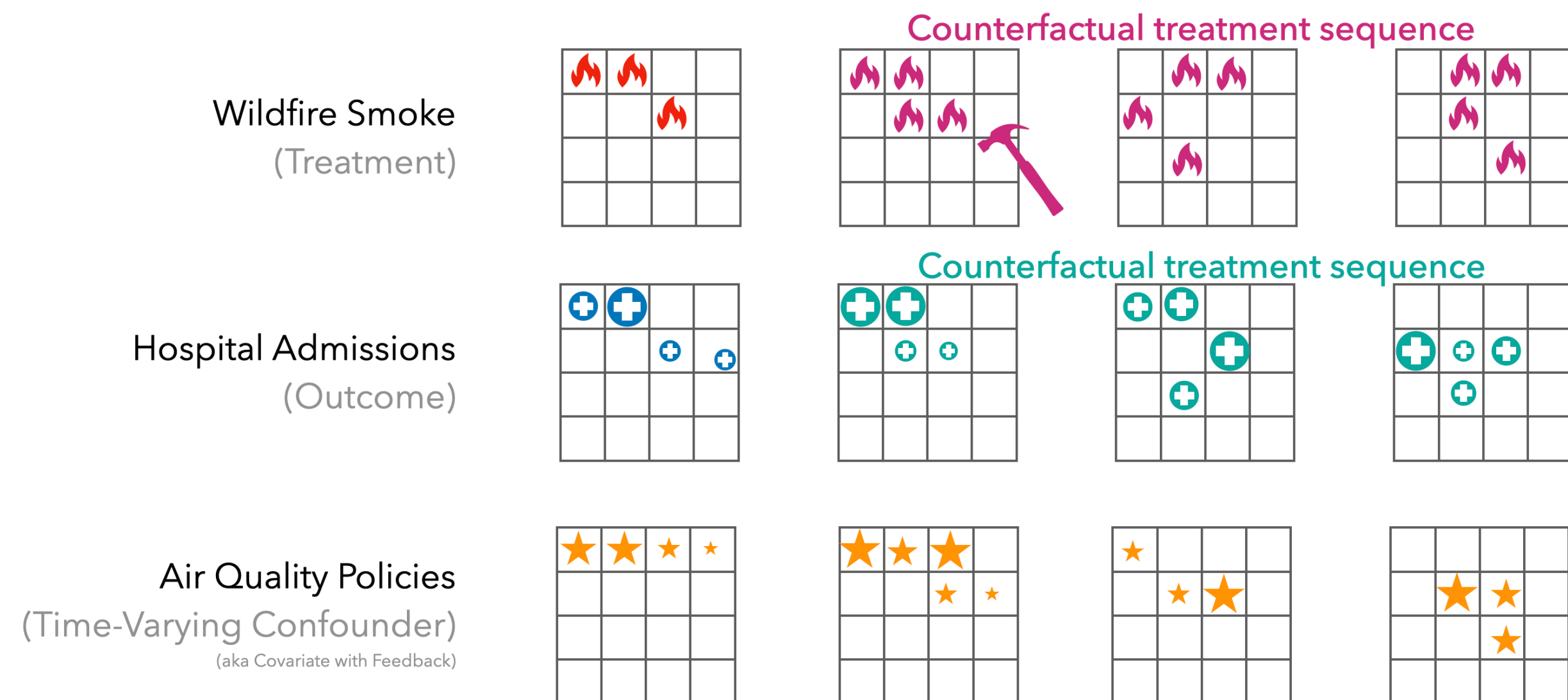


CAPO = Conditional Average Potential Outcomes
(w.r.t. history, counterfactual sequence, horizon τ)

=

Expected number of hospitalizations at time $t + \tau$ if we were to apply a specific sequence of treatments from time t to $t + \tau - 1$.

Assumptions



Assumptions

Where it breaks:

Causal Sufficiency:

Political pressure from activist groups that is not captured.

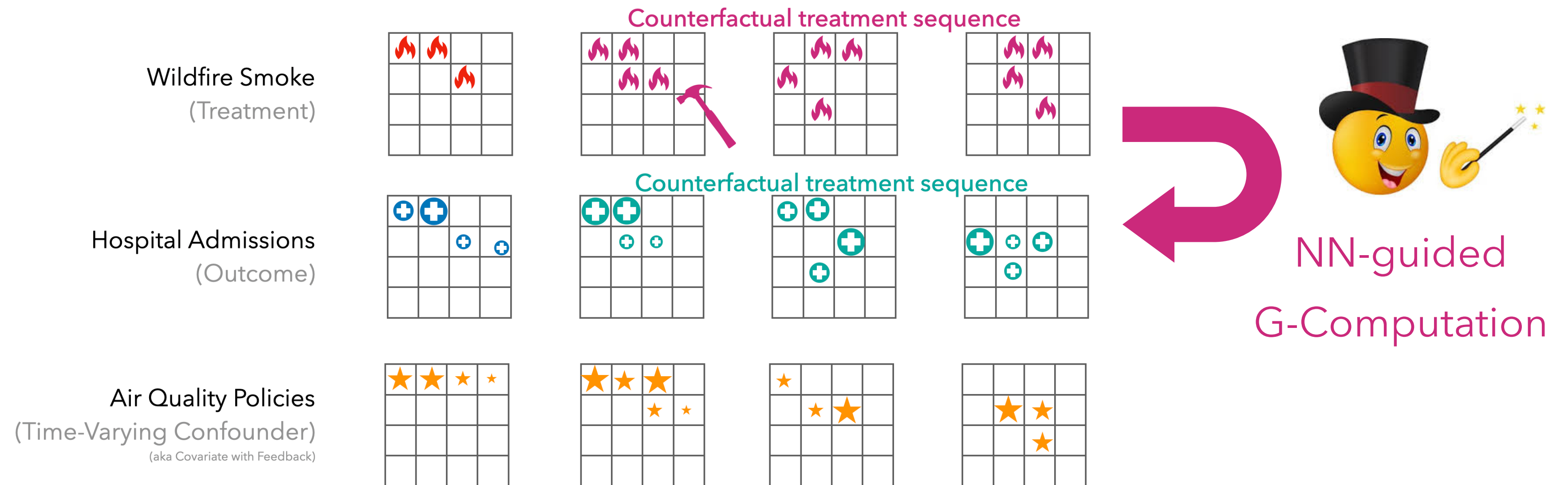
Temporal Ordering:

Correct the air quality sensor readings retrospectively.

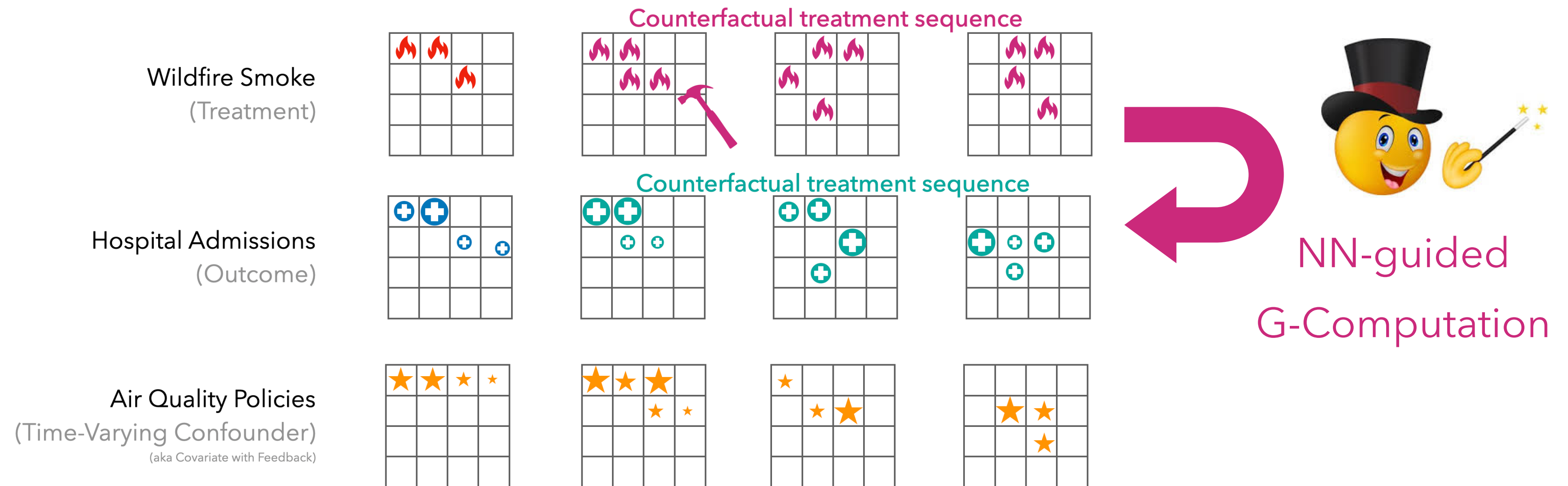
Time-Invariant Dynamics:

Behavior changes after 5 month.

G-Computation (Robins, 1986)



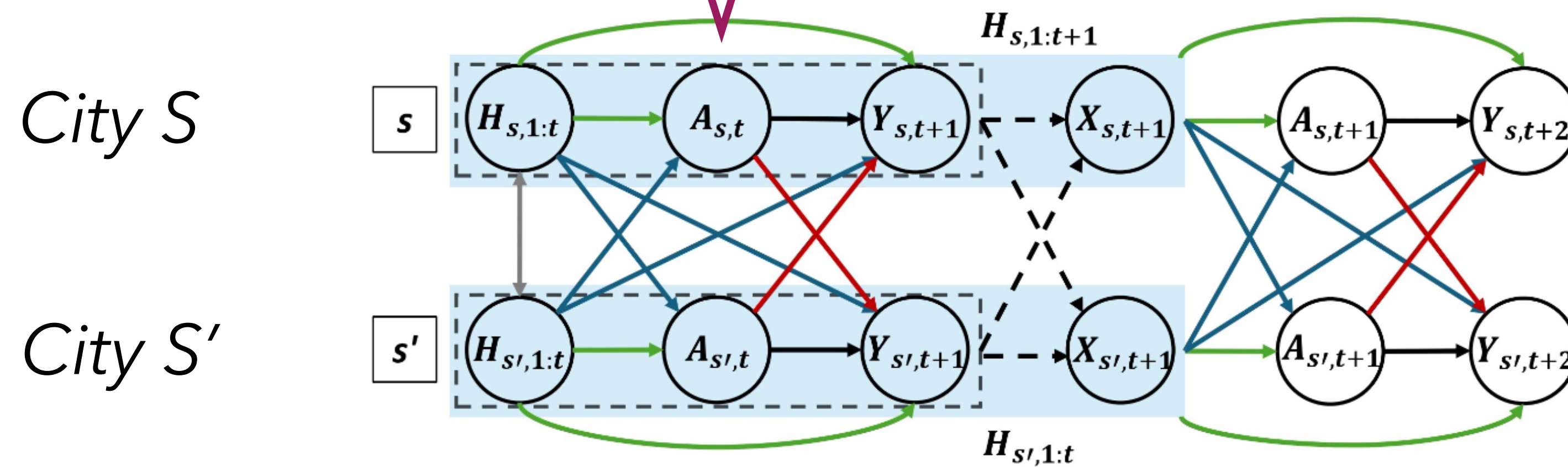
G-Computation (Robins, 1986)



- ▶ Estimate counterfactual outcomes with regression + recursion
- ▶ Good understanding of how outcomes depend on covariates and treatments.
- ▶ You cannot estimate effects of treatments that never occur in some part of the covariate space.

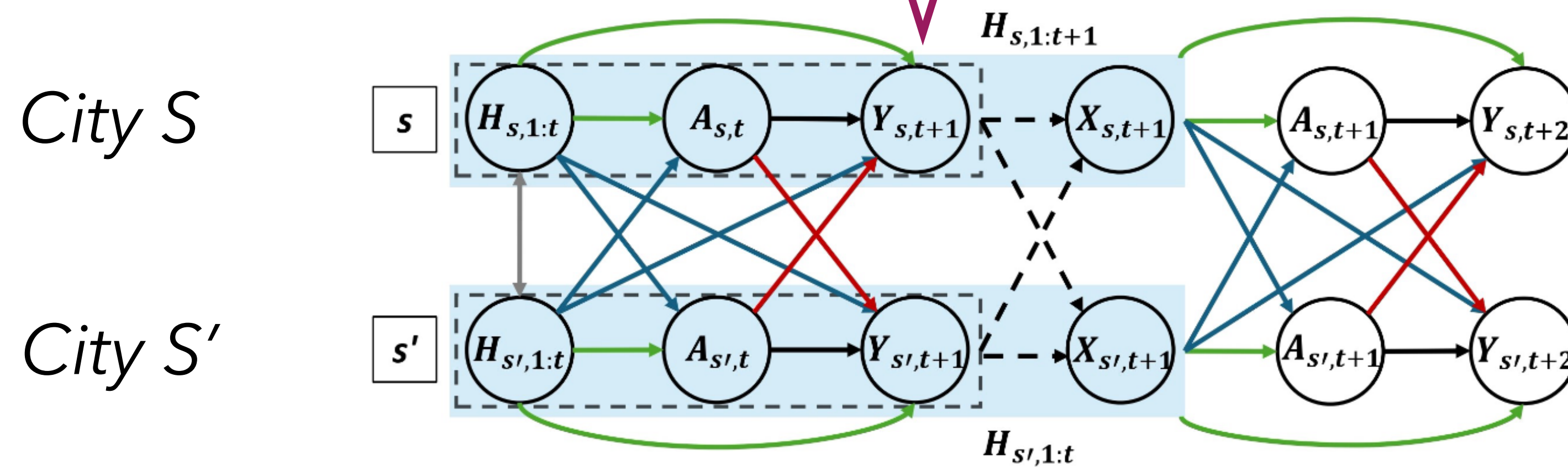
Setup

Intervention (binary, good vs bad air) at time t at City S .



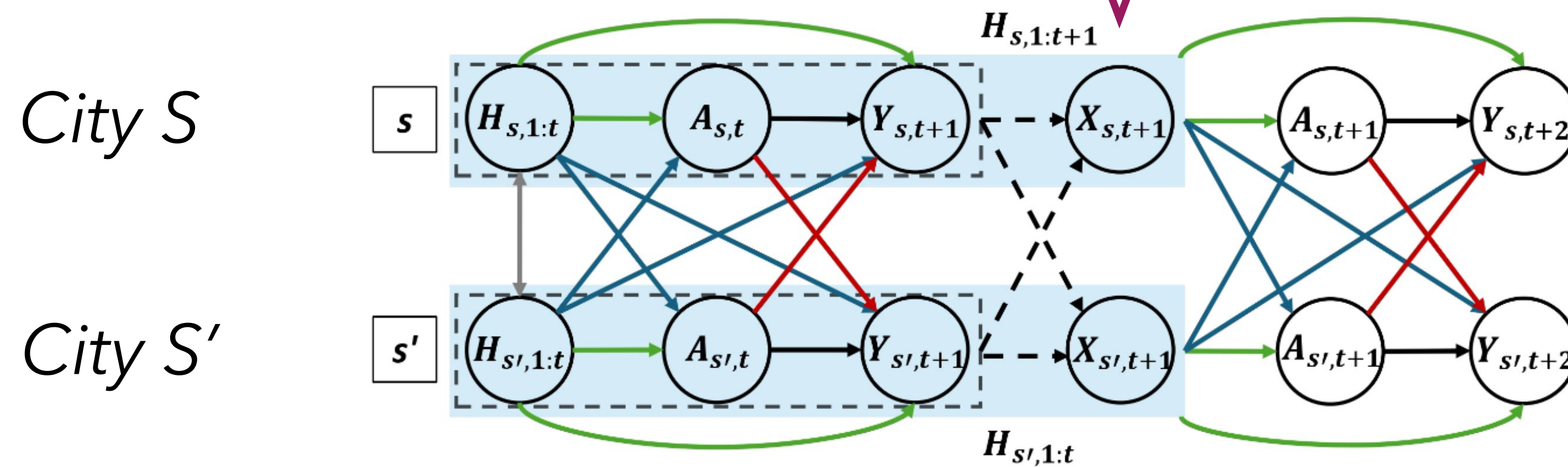
Setup

Outcome (scalar, hospitalization level) at time $t+1$ at City S.

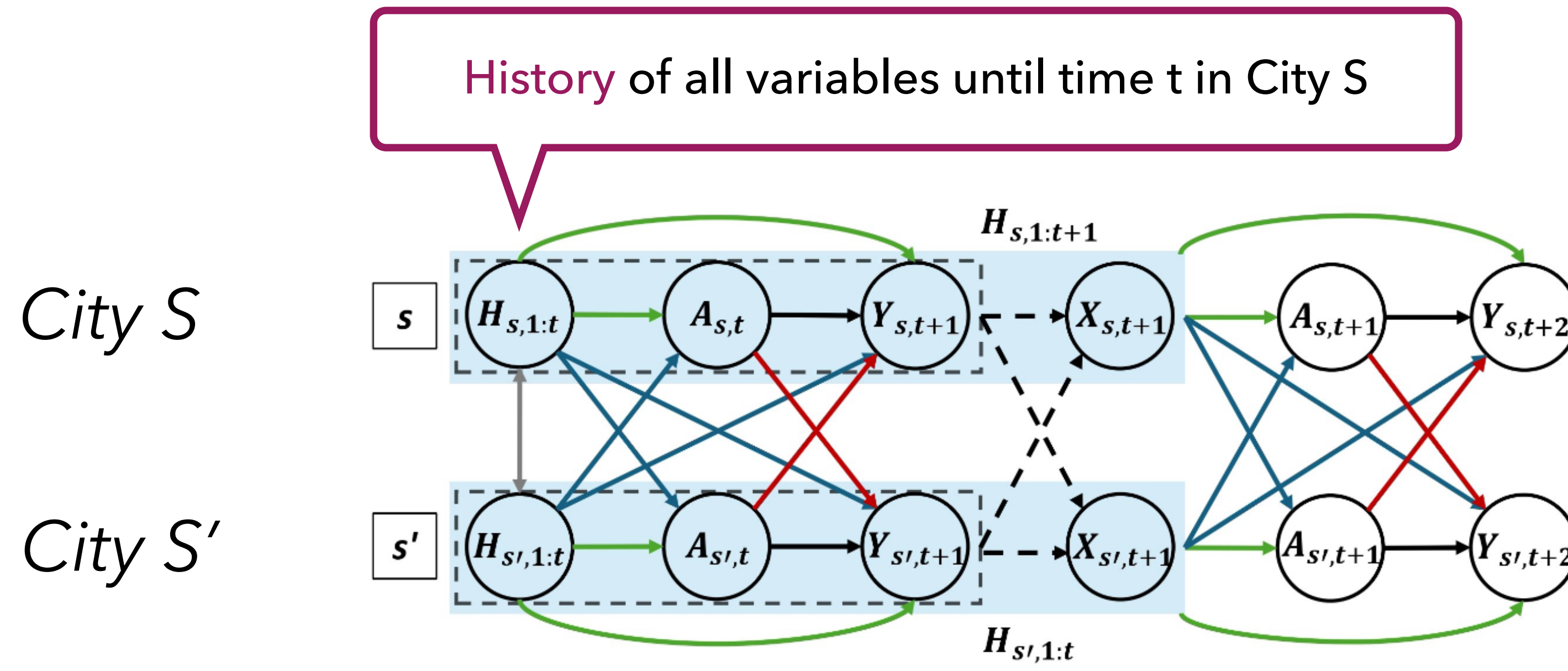


Setup

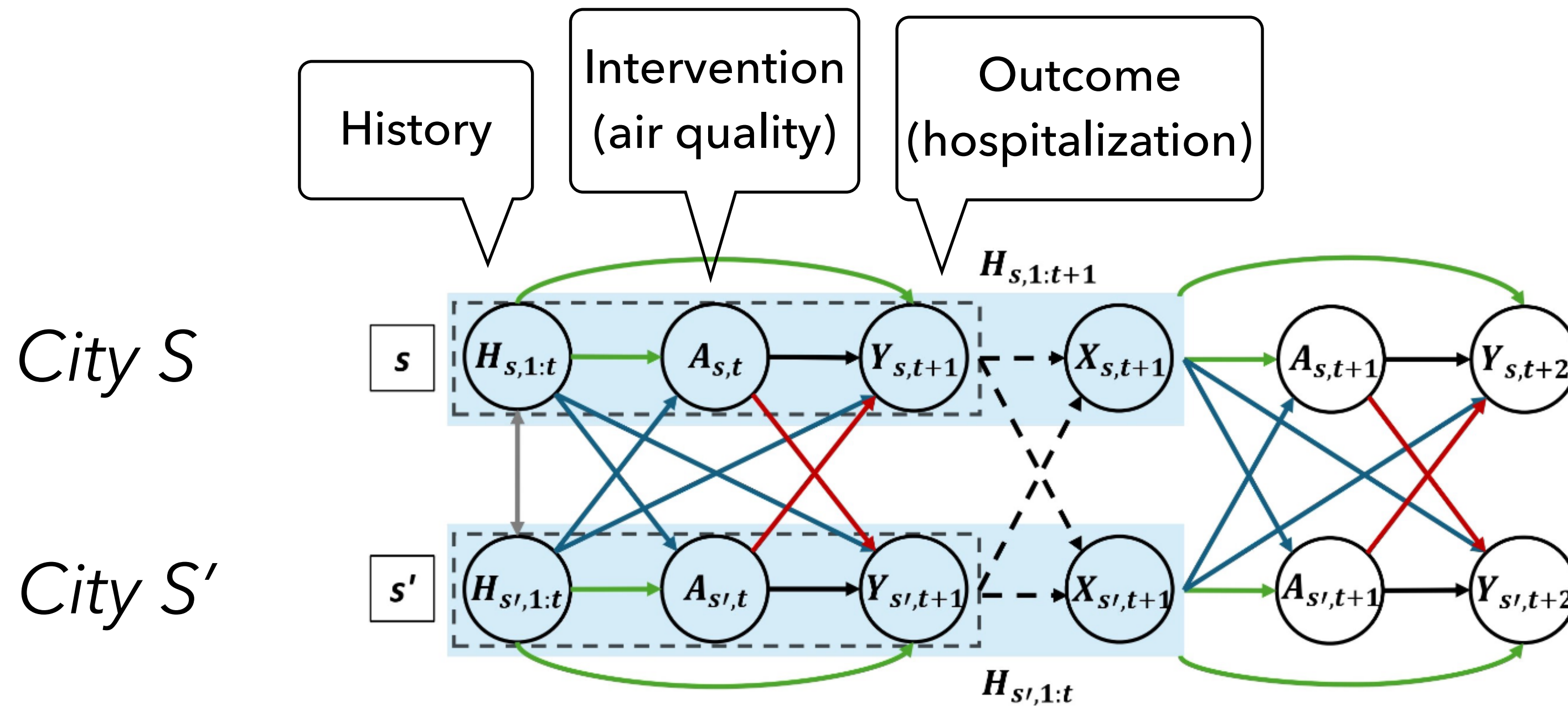
Covariates (temperature) at time $t+1$ at City S.



Setup



Setup



→ Direct effects → Temporal carryover → Spatial confounding → Interference - -> Time-varying confounding

Air pollution today causes more hospitalizations today.

Smoke exposure yesterday increases hospitalizations tomorrow

Temperature in City S causes air quality changes in City S'

Pollution in City S causes hospitalizations in City S'

Weather influences pollution levels and respiratory health

Setup

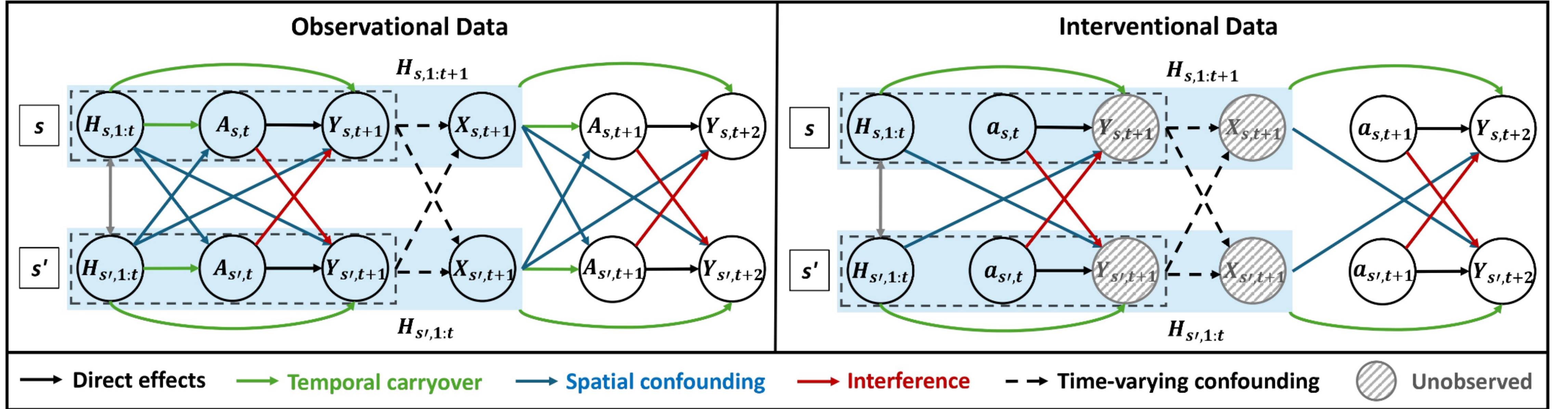
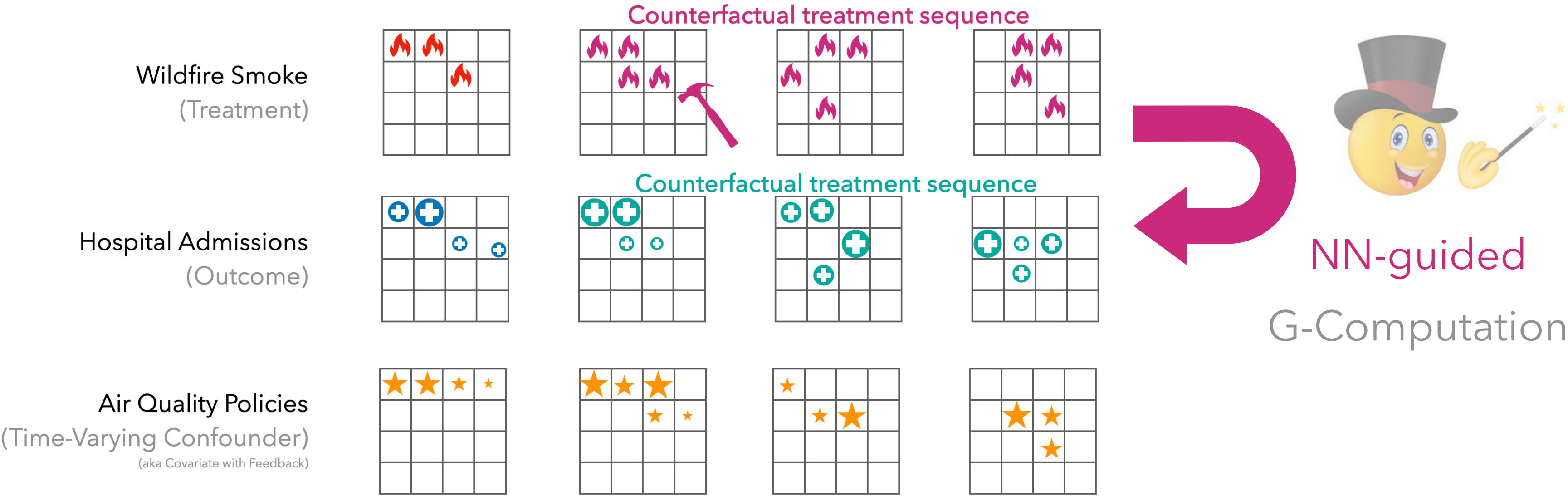
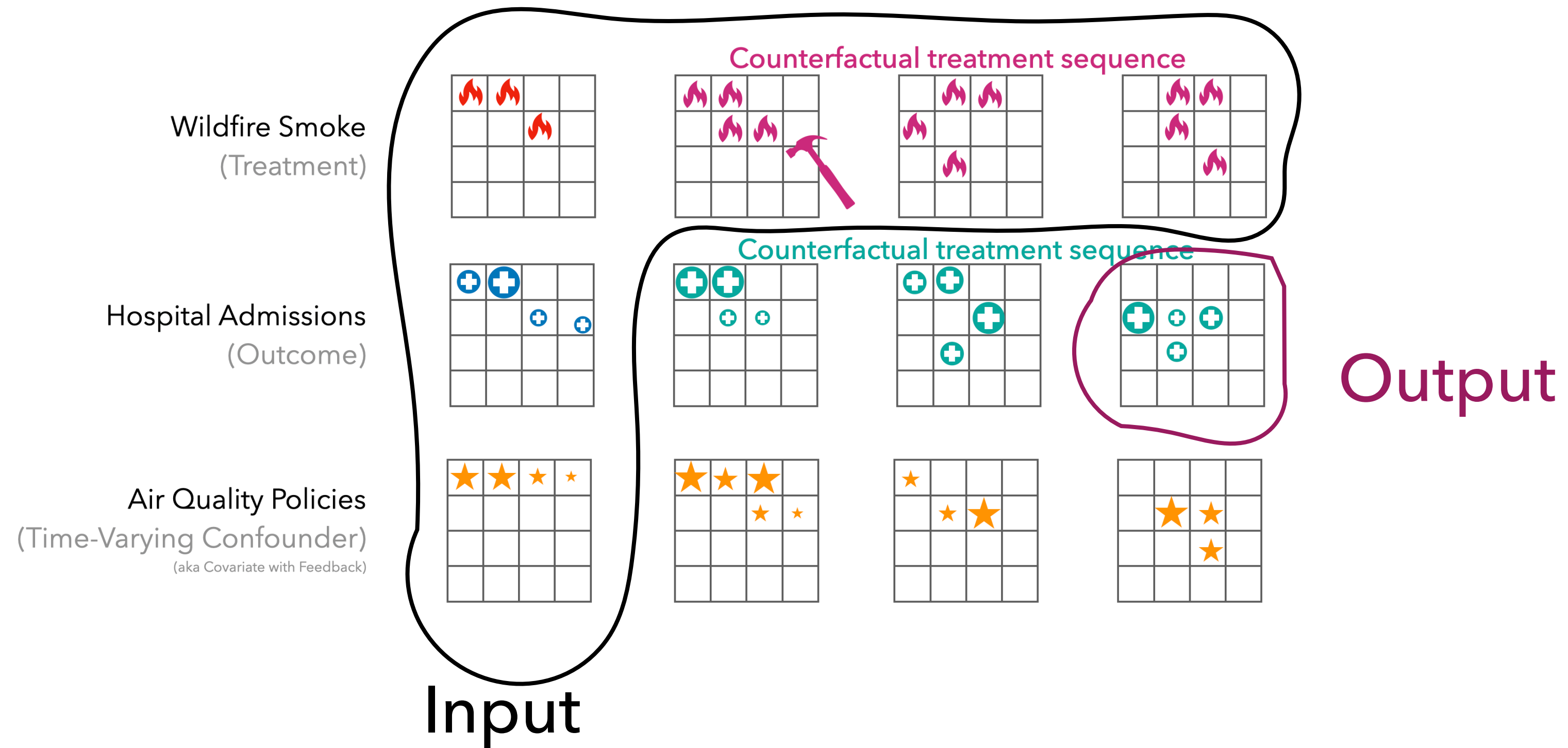


Figure 1. Observational data (left) versus interventional data (right) for a horizon $\tau = 2$ across multiple locations (s, s') . Green arrows indicate temporal carryover, blue arrows show spatial confounding, and red arrows depict interference; dashed arrows denote time-varying confounding, and dashed circles represent unobserved variables at inference time. Under the intervention (right), treatments are set independently of confounders, and the full history is not observed for the entire horizon.

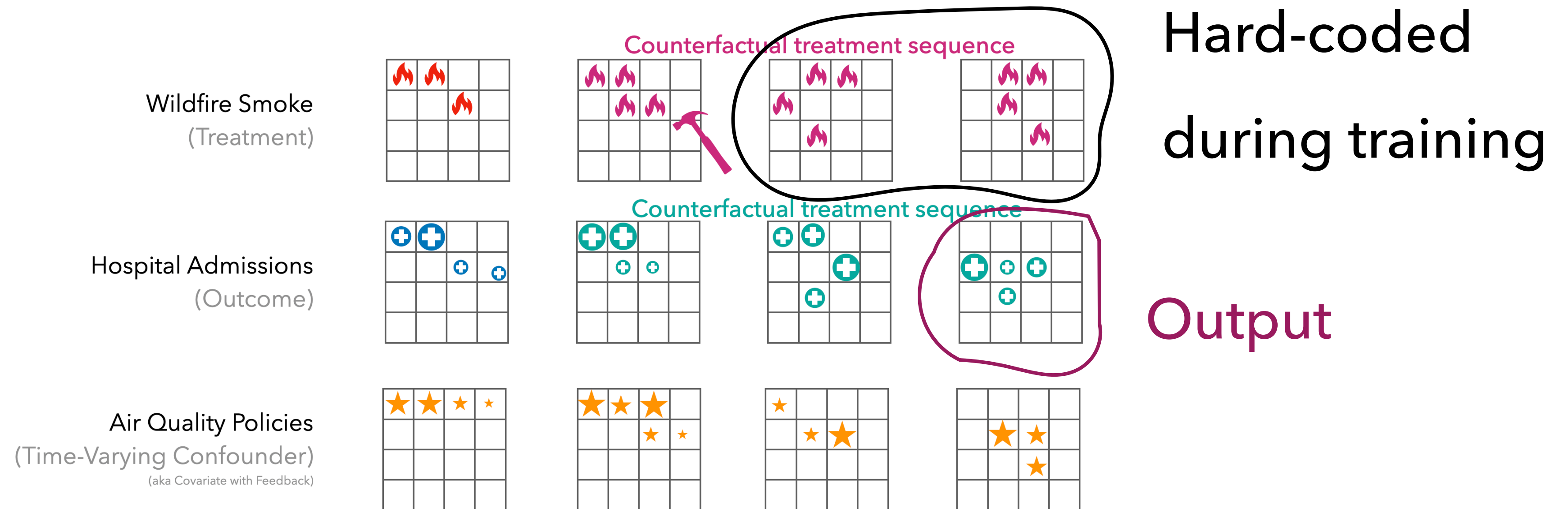
G-Computation (Robins, 1986)



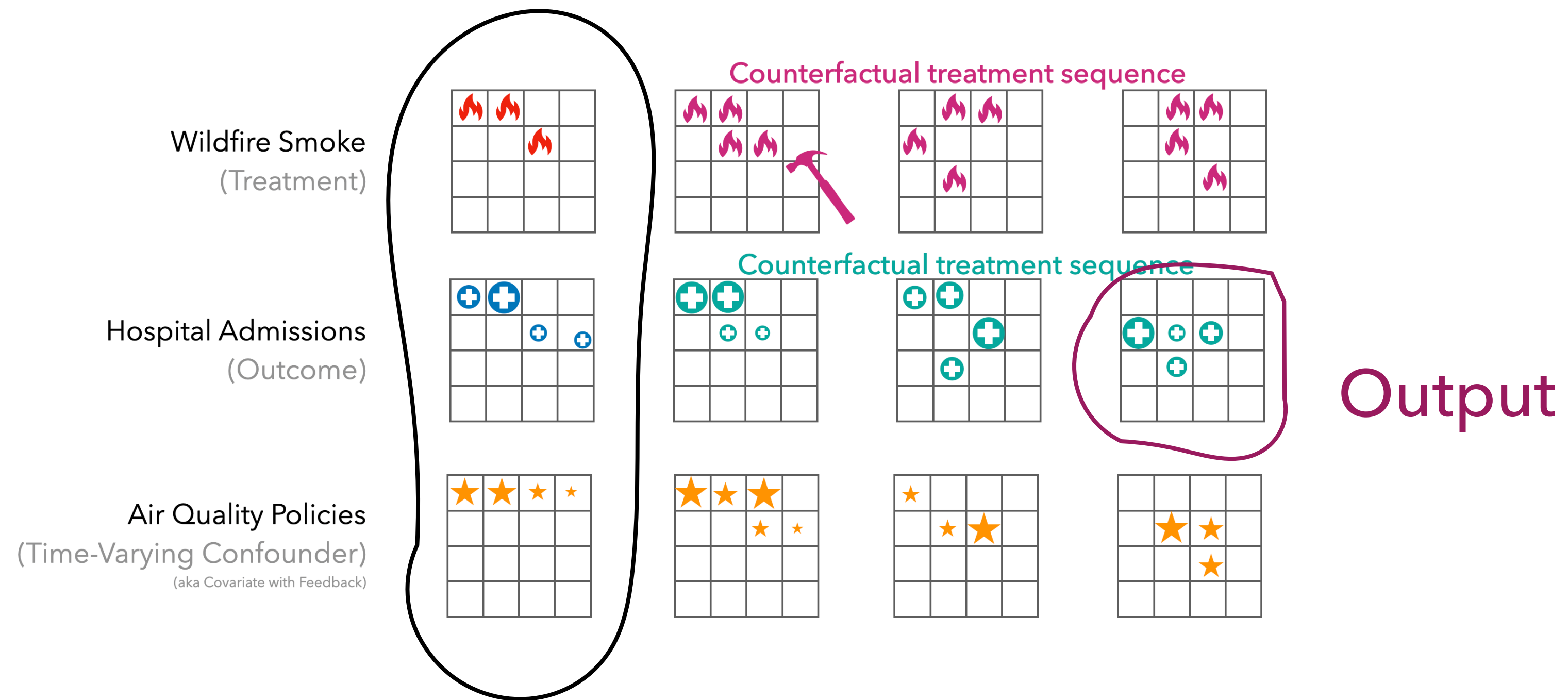
G-Computation (Robins, 1986)



G-Computation (Robins, 1986)



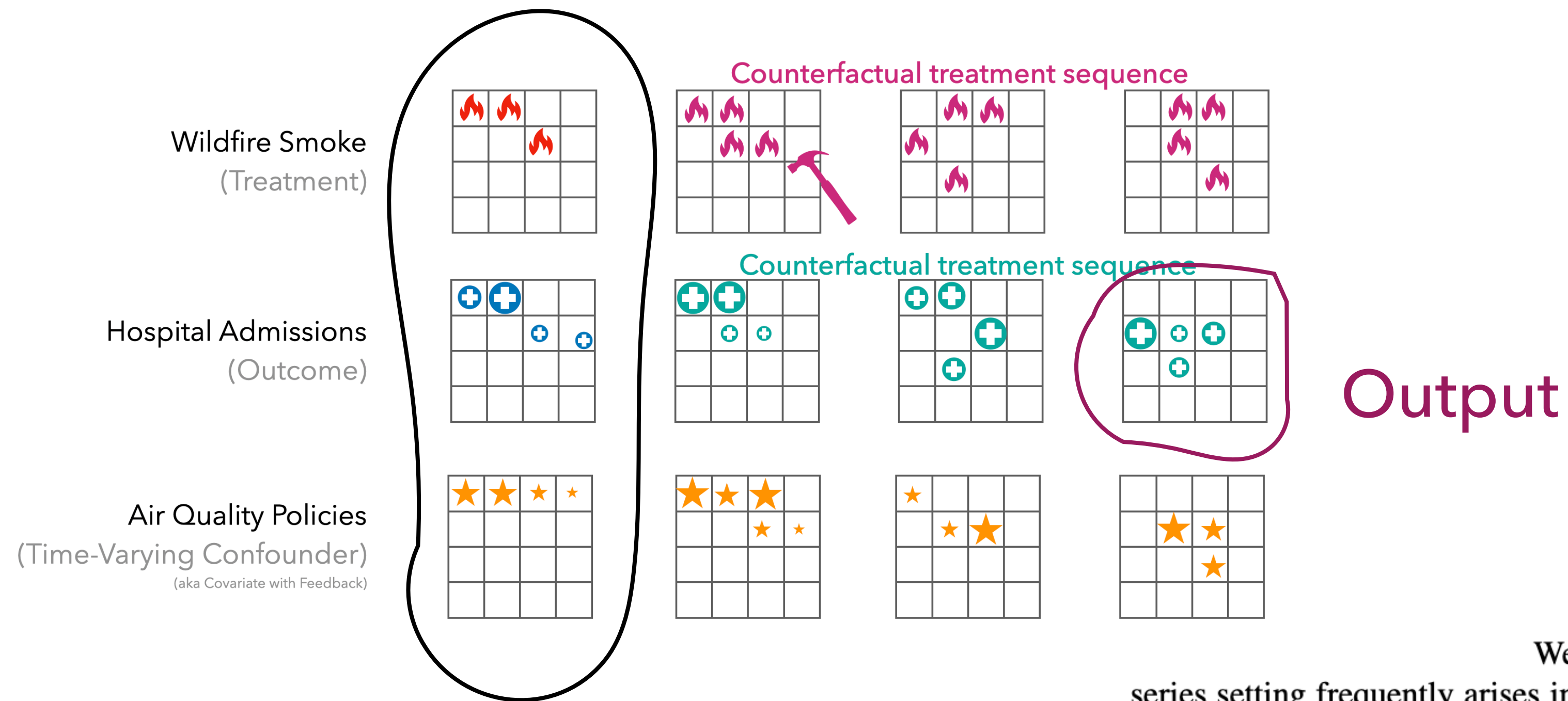
G-Computation (Robins, 1986)



History Encoder

(Makes everything Markovian)

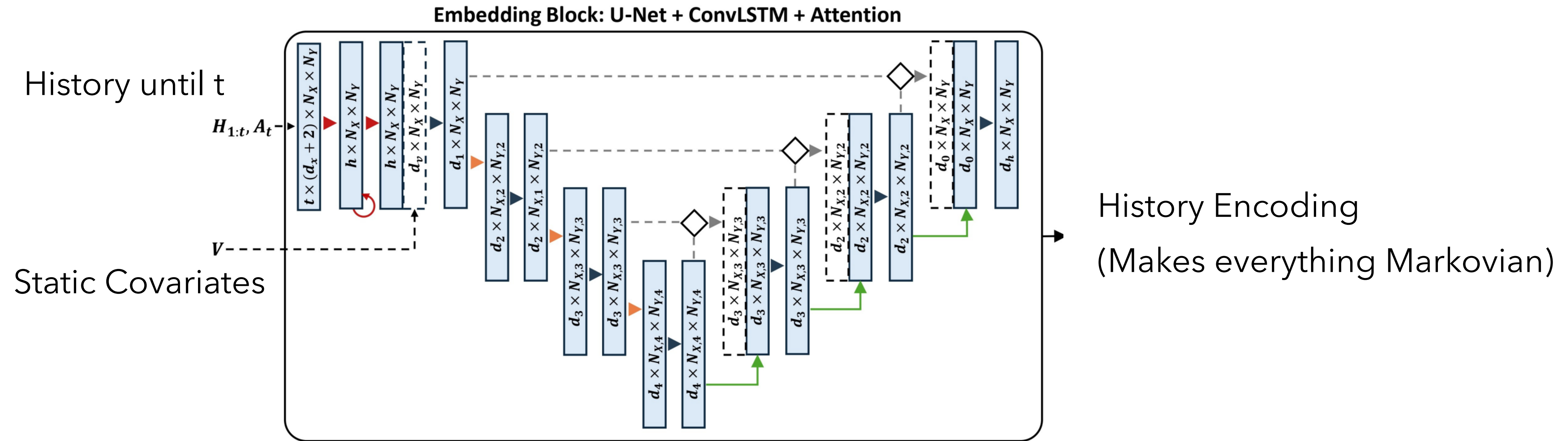
G-Computation (Robins, 1986)



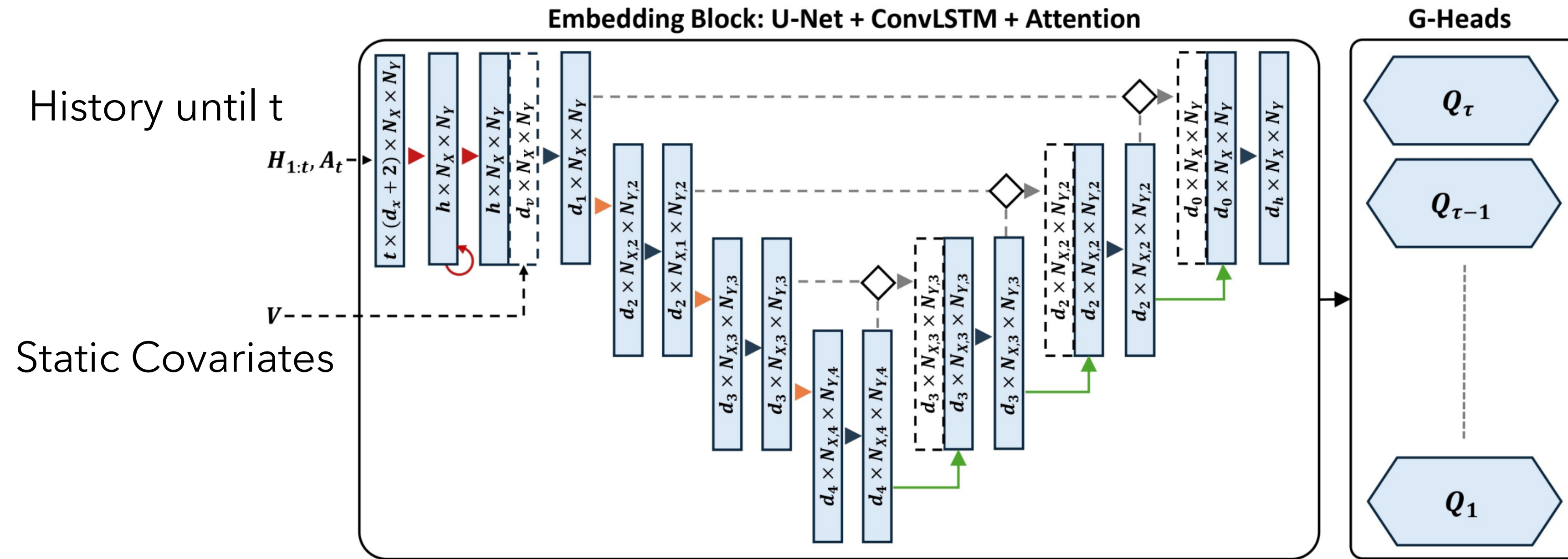
History Encoder
(Makes everything Markovian)

We note that the single time-series setting frequently arises in causal inference, where assumptions such as stationarity or strict time homogeneity enable consistent estimation (Bojinov and Shephard, 2019; Papadogeorgou et al., 2022; Zhou et al., 2024). In contrast, our representation-based time invariance is *weaker*: rather than requiring $\mathbf{X}_t, \mathbf{Y}_t$ themselves to have a time-invariant distribution, we only assume that, once the history is summarized by $\phi(\mathbf{H}_{1:t}, \mathbf{A}_t)$, the transition to $(\mathbf{X}_{t+1}, \mathbf{Y}_{t+1})$ follows a single shared mechanism.

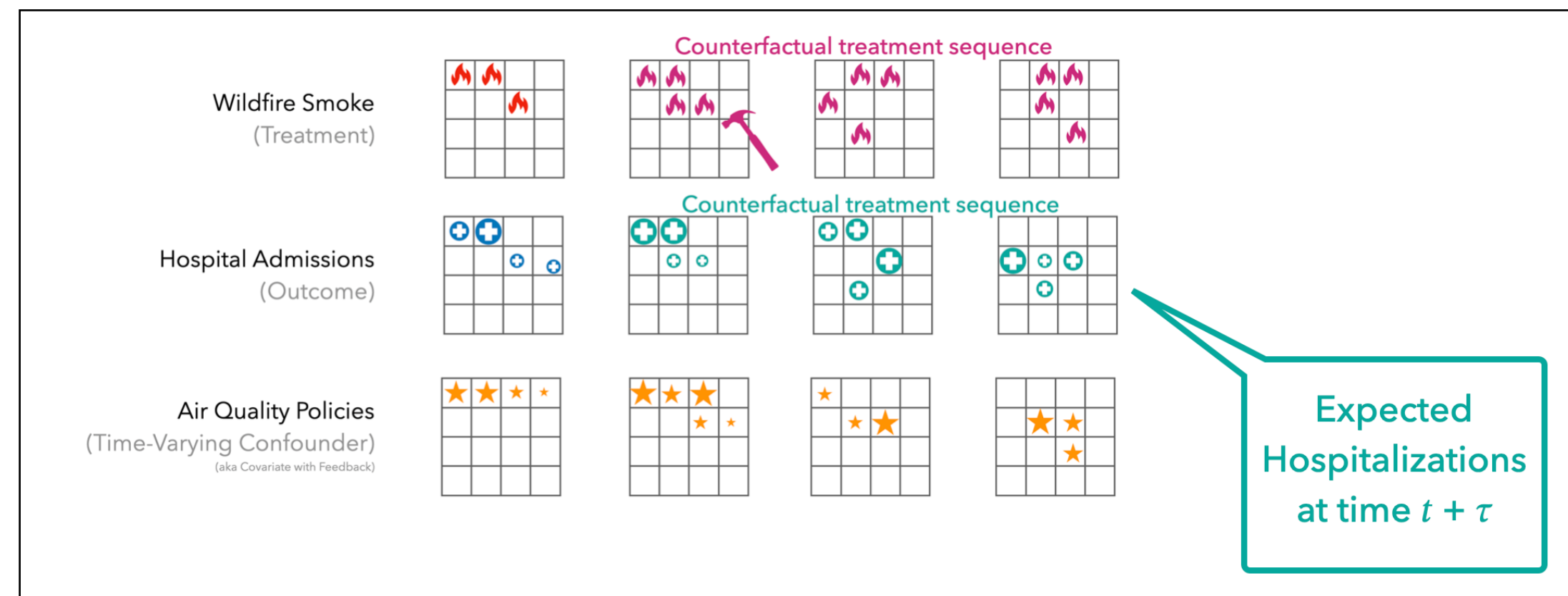
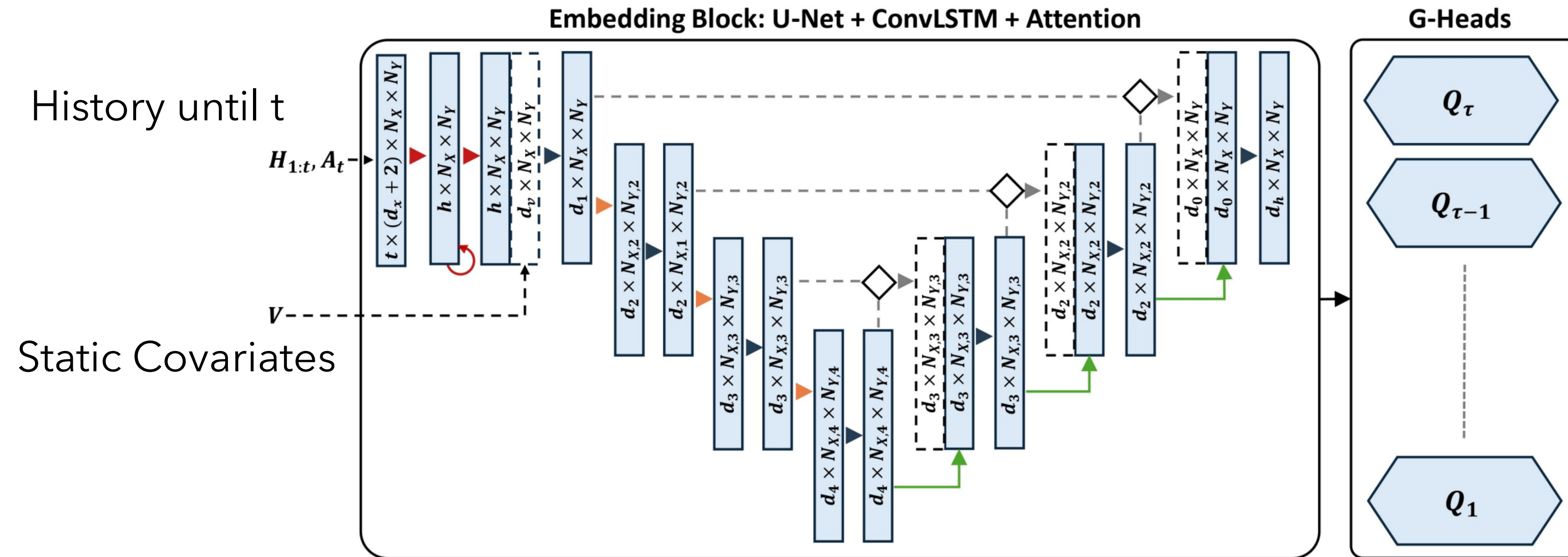
NN



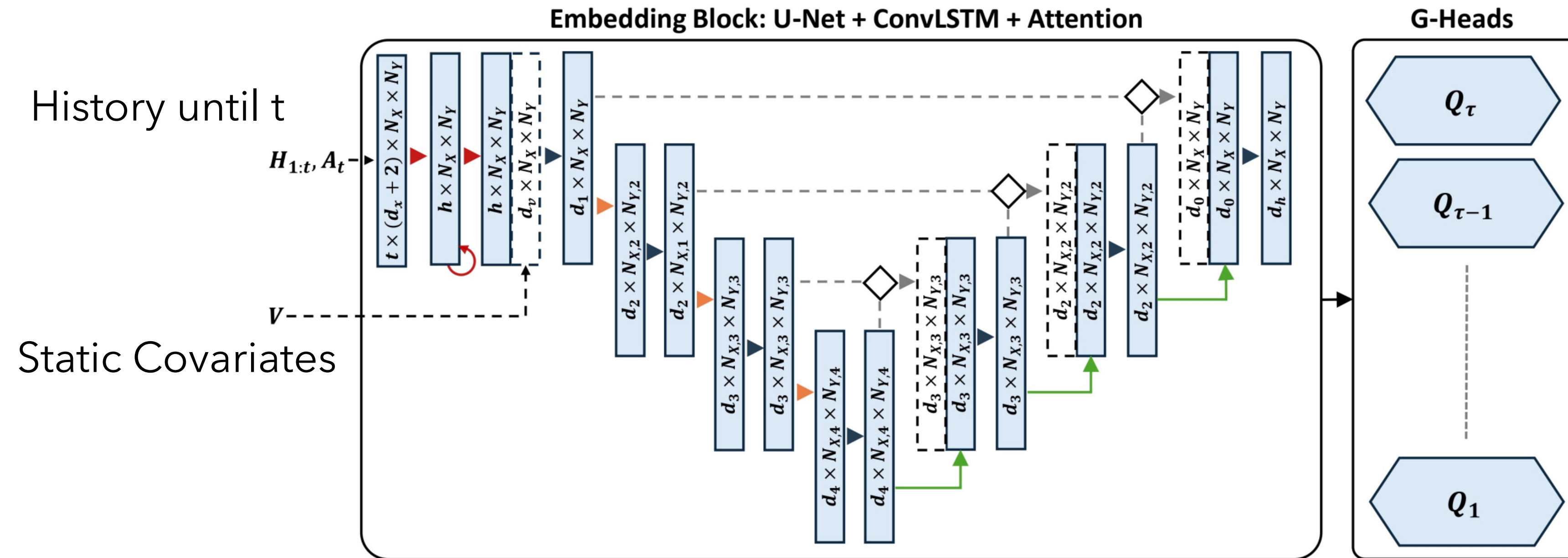
NN



NN

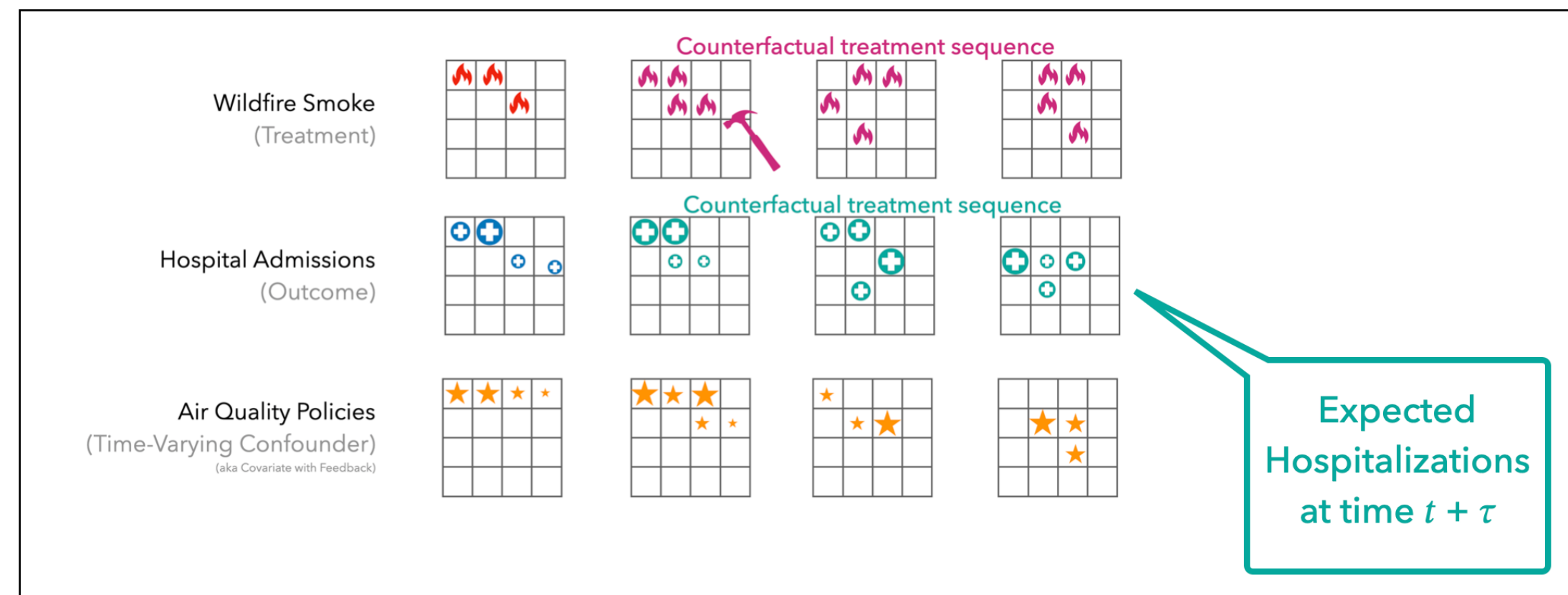


NN

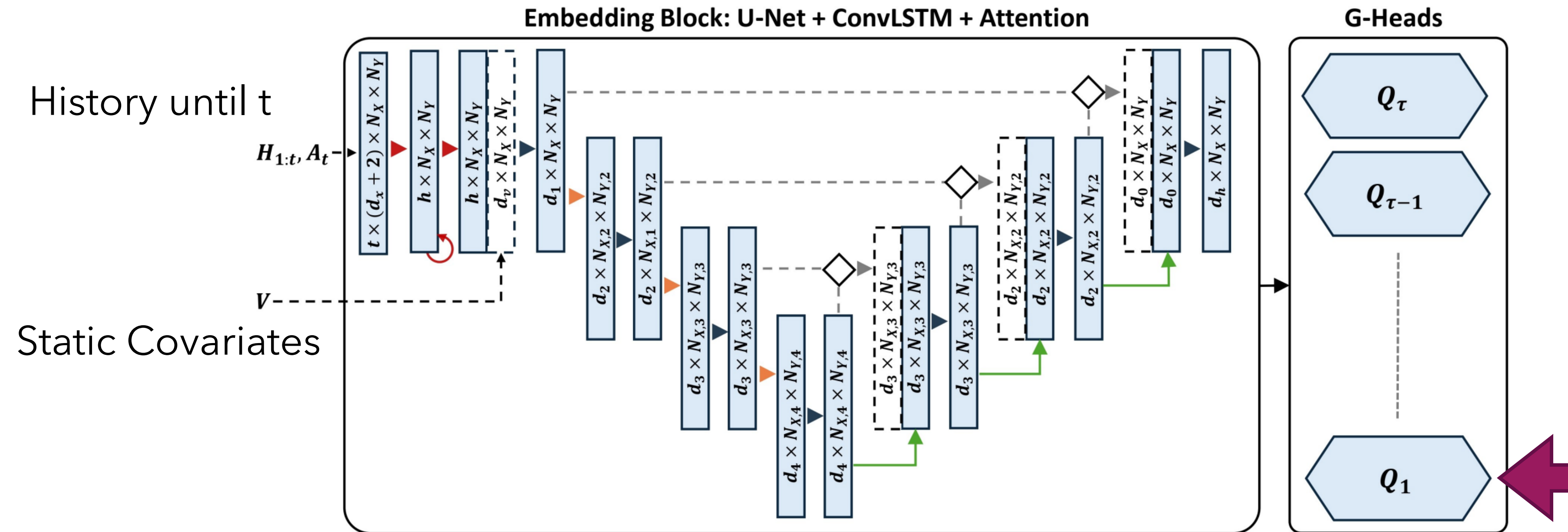


Each head Q_k estimates the CAPO: The expected hospitalisations on the final day $t + \tau$.

Q_k does so under the assumption that we know the history up to time $t + k - 1$.

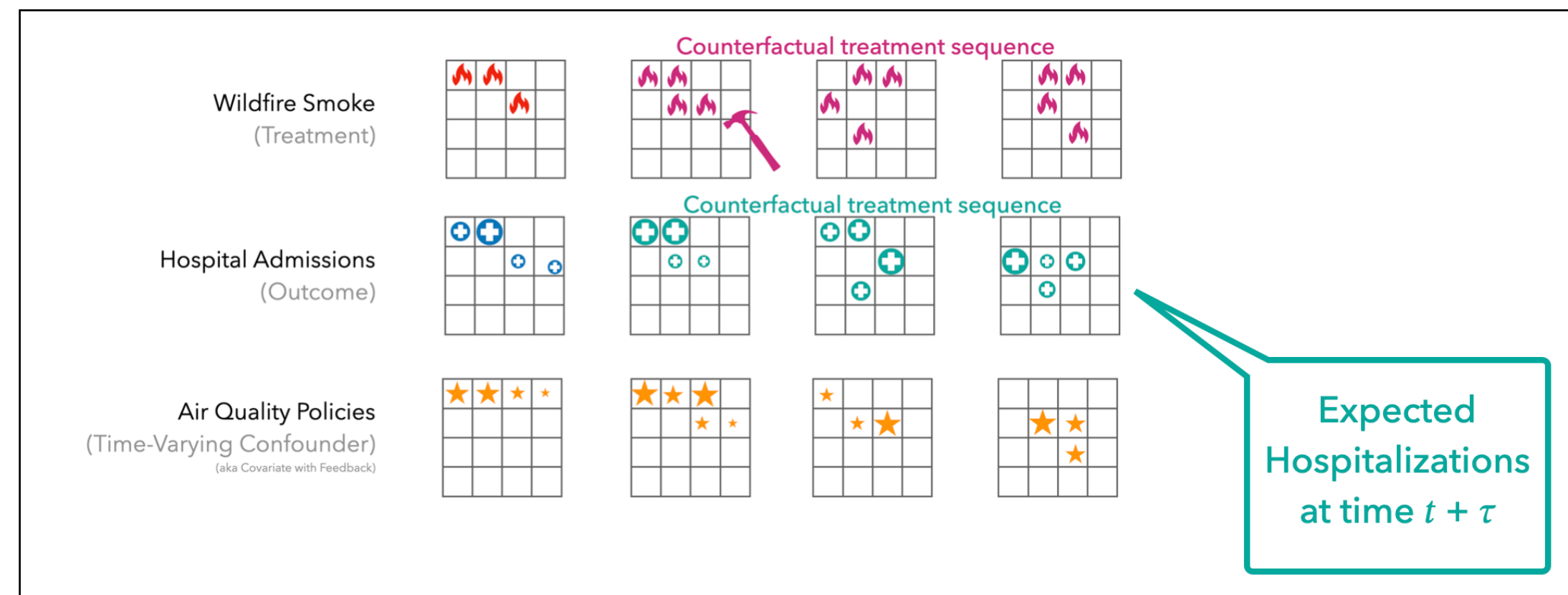


NN

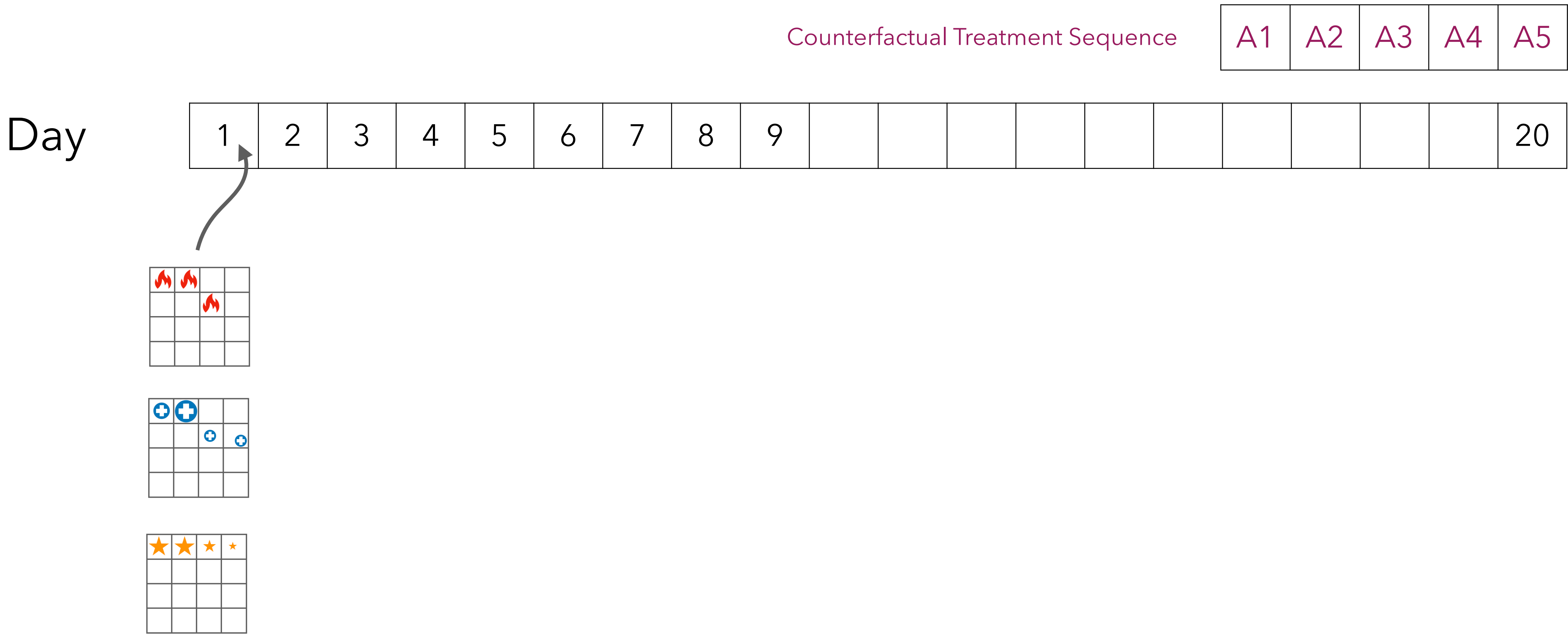


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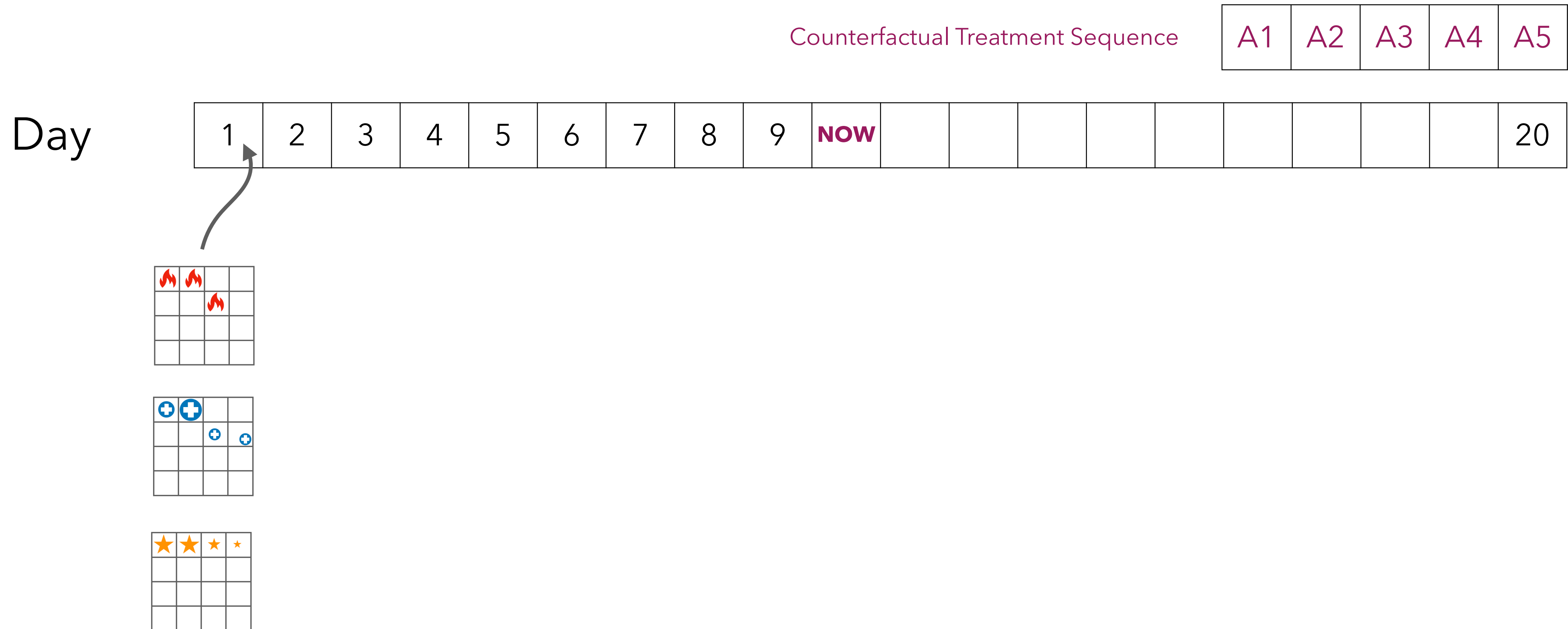
Q_k does so under the assumption that we know the history up to time $t + k - 1$.



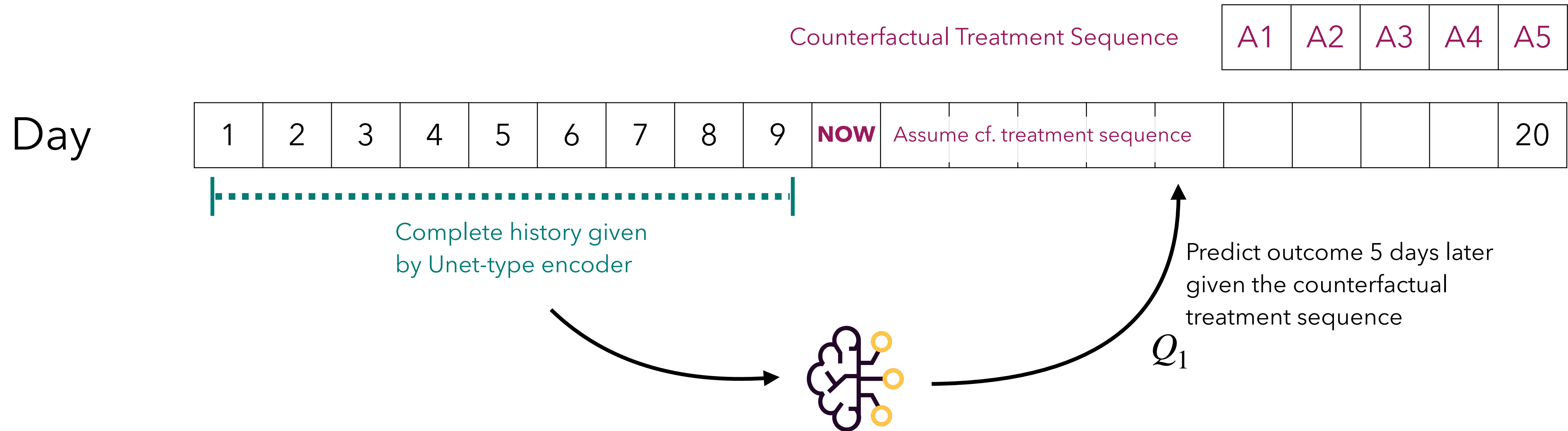
Splitting



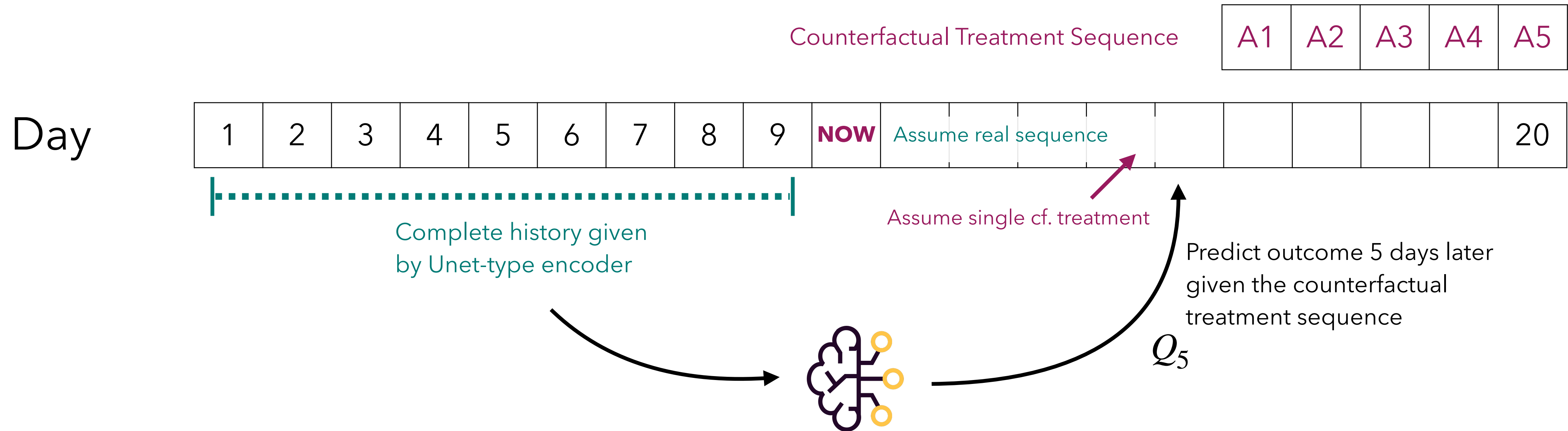
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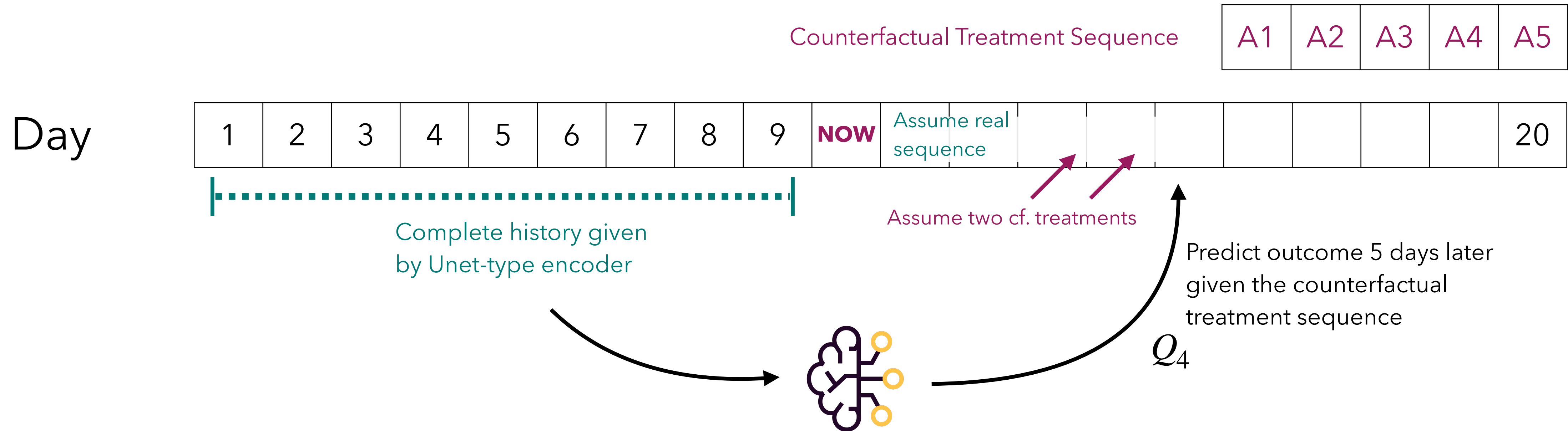
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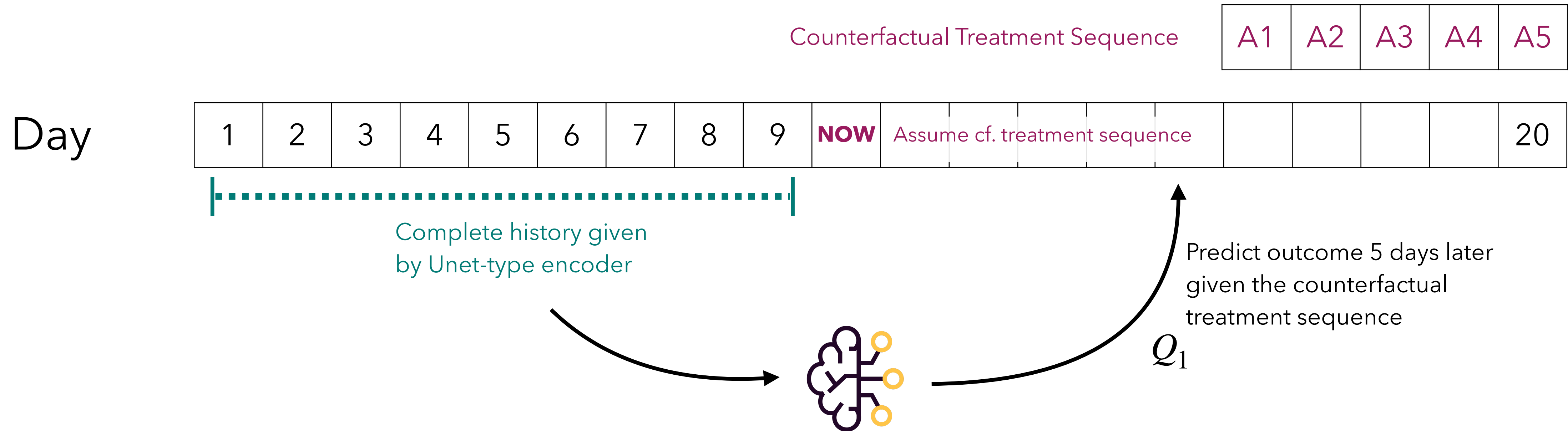
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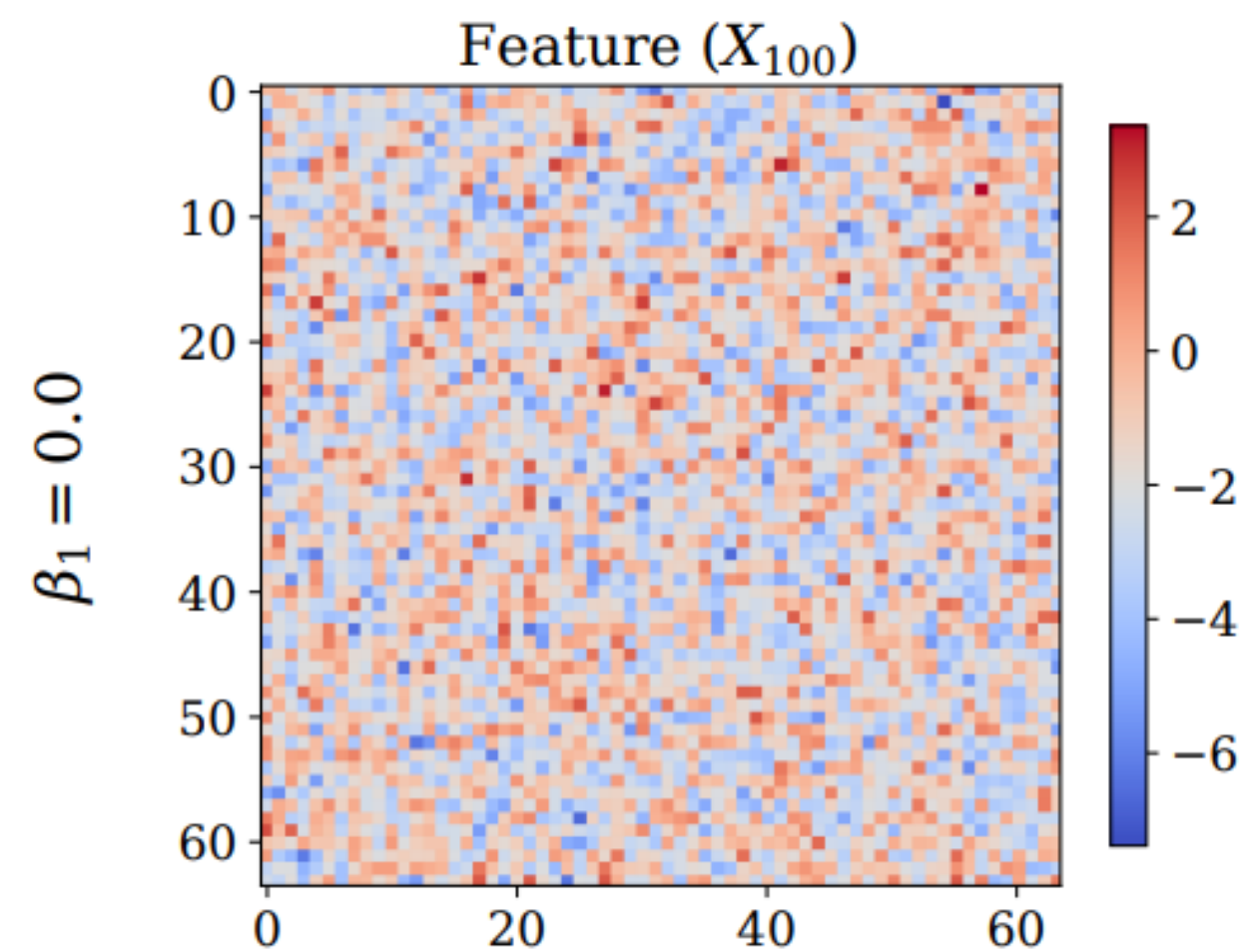


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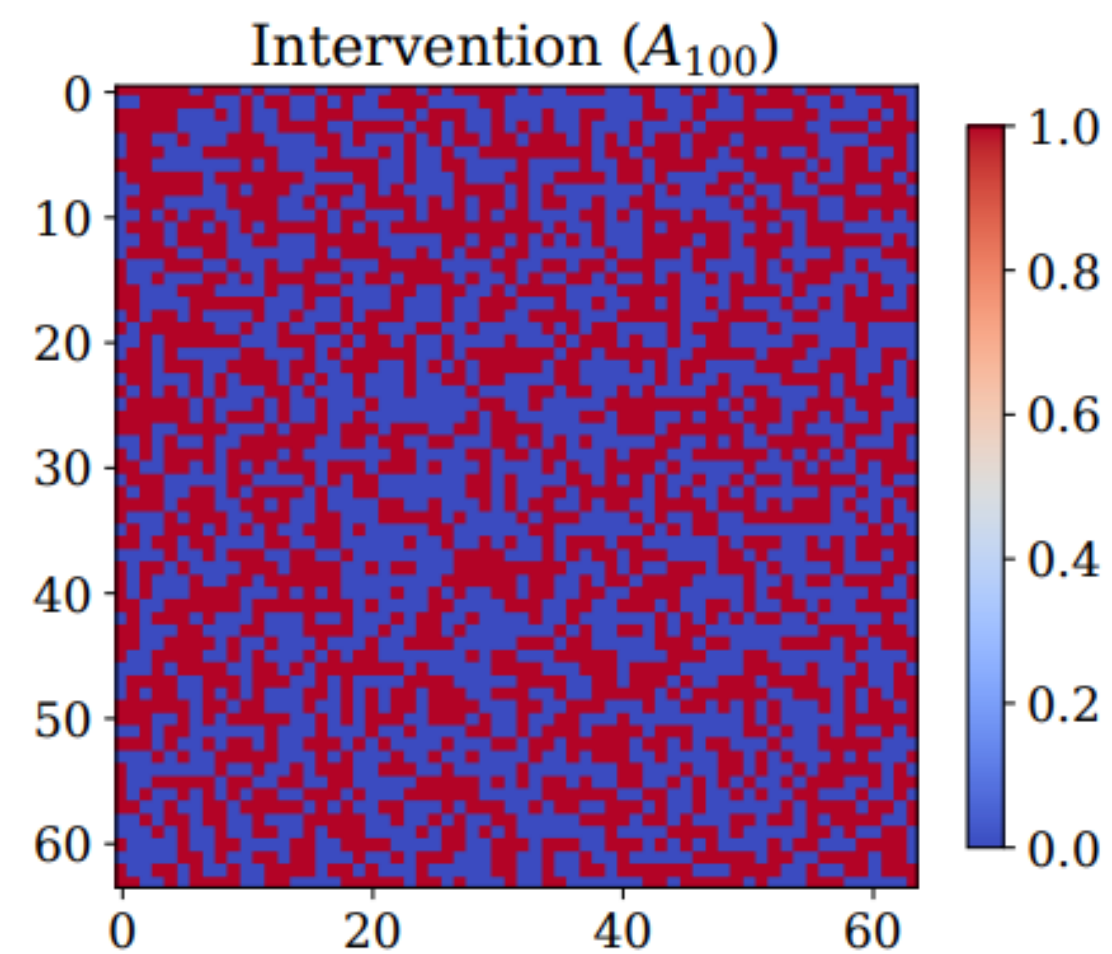


Simulation

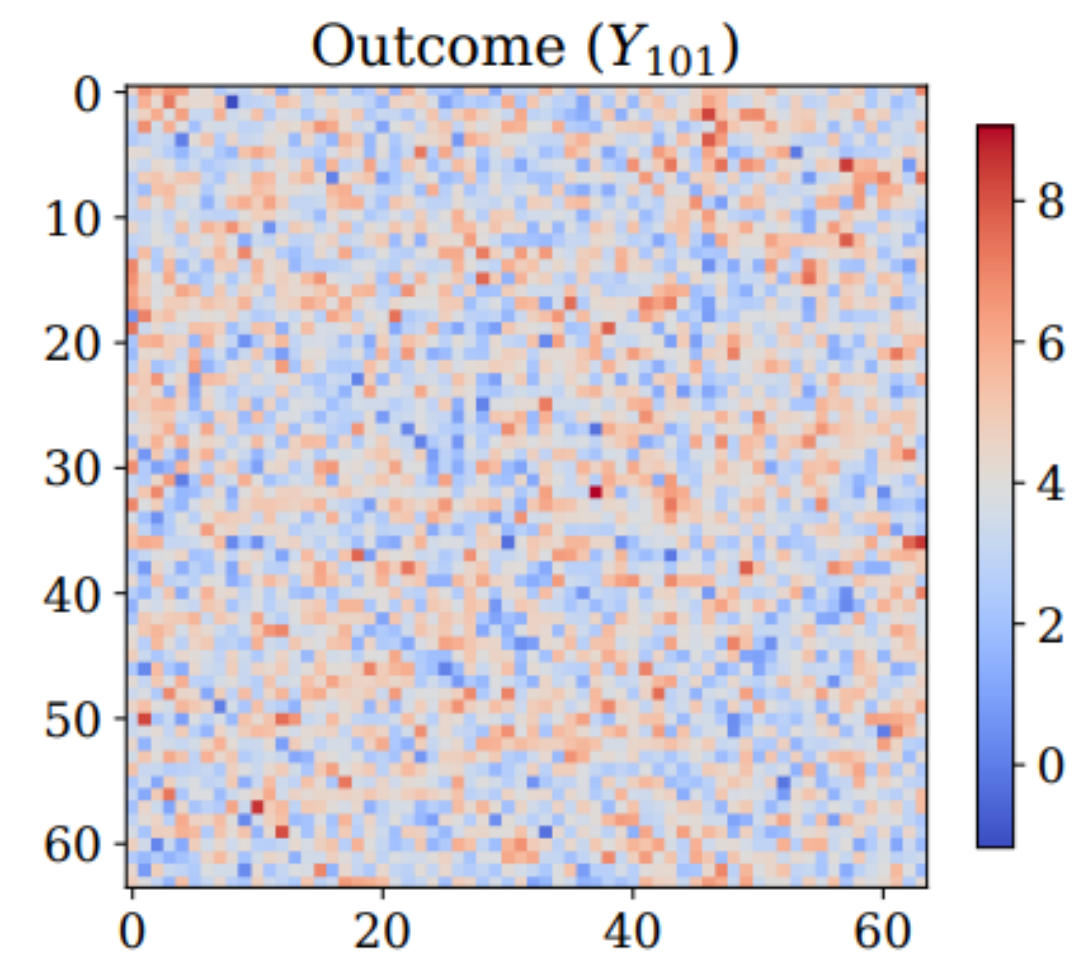
Air Quality Policies
(Time-Varying Confounder)
(aka Covariate with Feedback)



Wildfire Smoke
(Treatment)



Hospital Admissions
(Outcome)



Time-varying confounders grow => GST-UNET becomes better than the baselines.

Real-World Case Study

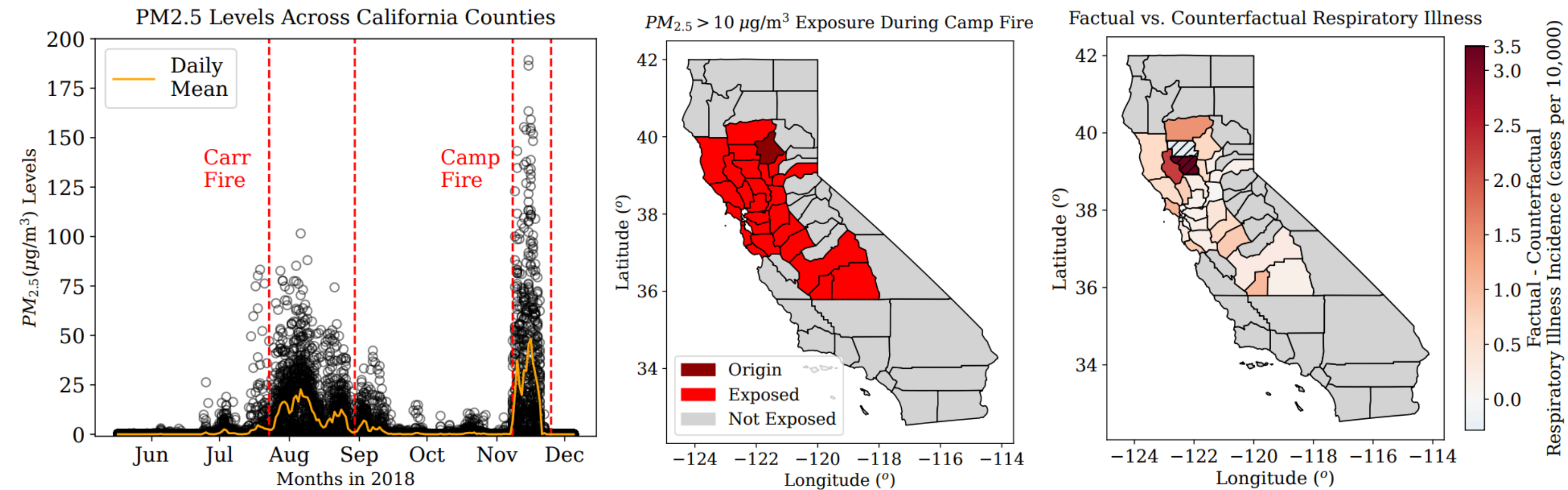
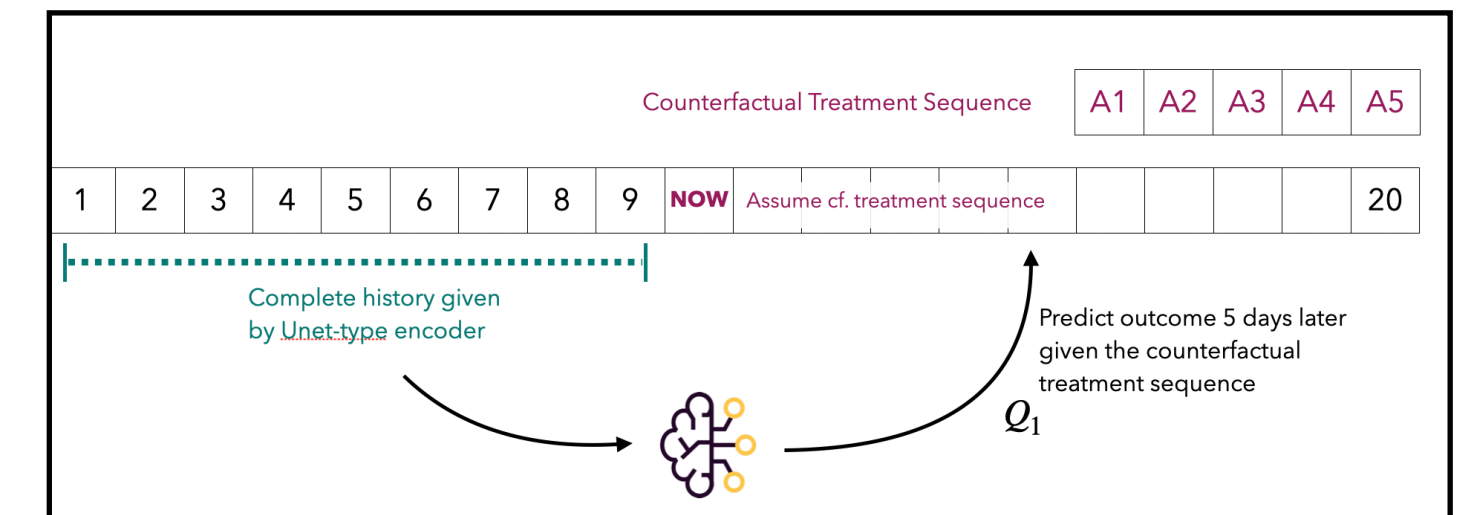
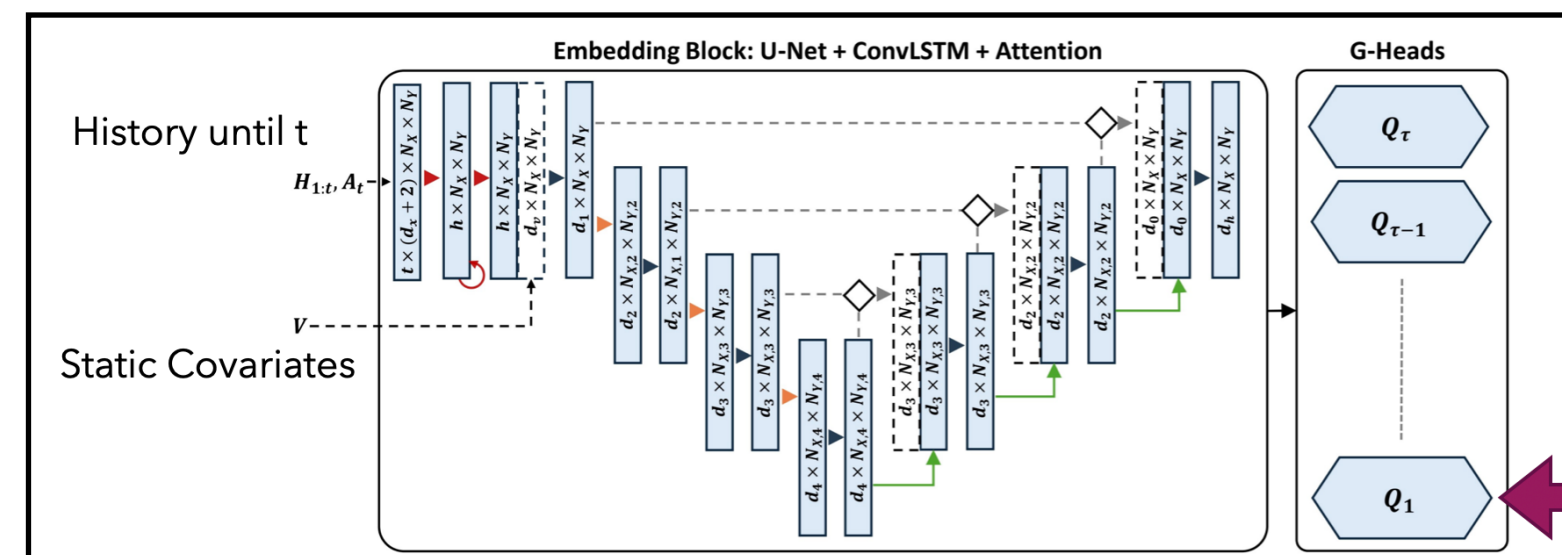
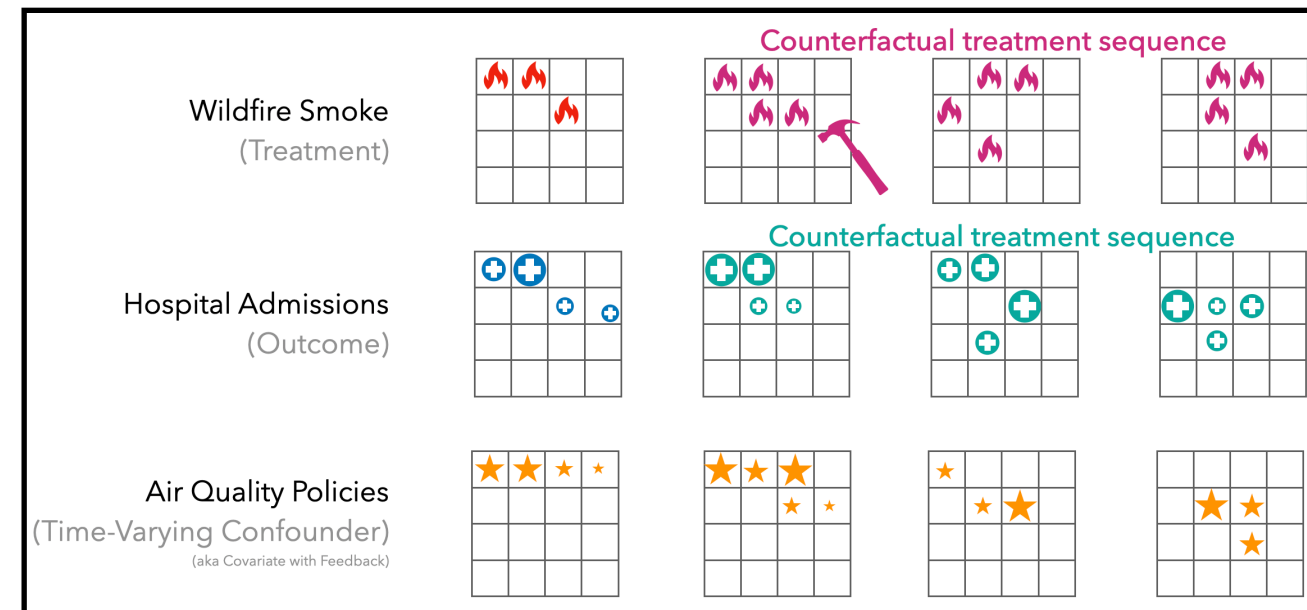


Figure 3. (Left) Daily PM_{2.5} levels across California from May to December 2018, with red lines marking major wildfires. **(Center)** Counties exposed to average PM_{2.5} > 10 $\mu\text{g}/\text{m}^3$ during the Camp Fire (red), origin county in dark red. **(Right)** Factual minus CAPO-predicted daily respiratory admissions during peak Camp Fire. Hashed areas indicate small-population counties (< 30,000).

- Quantify **extra respiratory hospitalizations** caused by the 2018 Camp Fire smoke across California.
- Spatial grid: 10 km x 10 km.
- Counterfactual treatment: Set every cell to "**no-smoke**" for 8 – 17 Nov 2018 (10 days ahead).
- Outcome: model attributes $\approx$ **4 650 excess admissions** to the fire-driven pollution.

Summary



- How realistic are the assumptions?
- NN-architecture + training unprincipled?
- Is there a conceptual difference than just learning the transition operator?
- Can you sample from the counterfactual distribution?
- Effects of grid size not discussed.